

LAUREN TOMPKINS

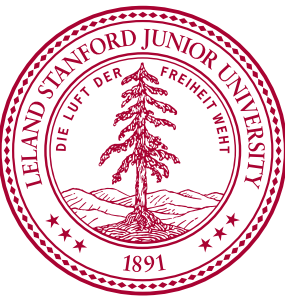
HEPCAT SUMMER SCHOOL 2024

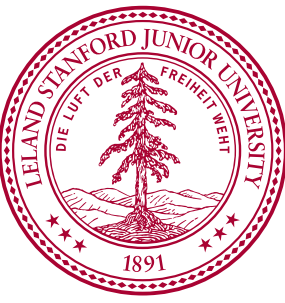
BASICS OF TRIGGER AND DATA ACQUISITION SYSTEMS



Stanford
University

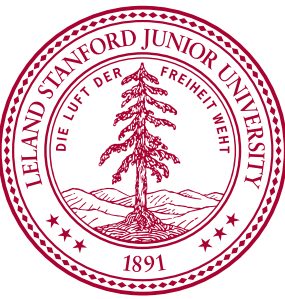
GENERAL OUTLINE OF THE LECTURE





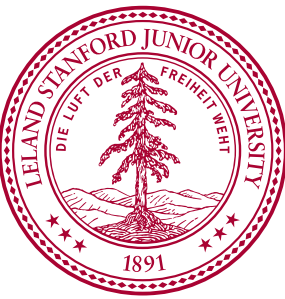
GENERAL OUTLINE OF THE LECTURE

- Introduction to me, this talk, and TDAQ



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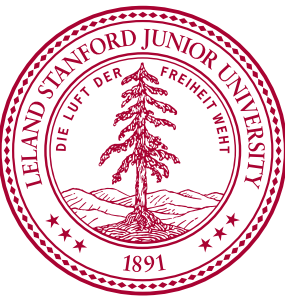
- Introduction to me, this talk, and TDAQ
- Start off with some context: what is the trigger & data acquisition challenge?



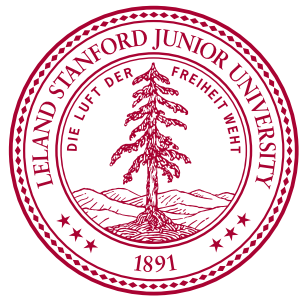
GENERAL OUTLINE OF THE LECTURE

- Introduction to me, this talk, and TDAQ
- Start off with some context: what is the trigger & data acquisition challenge?
- Spend some time with a toy example

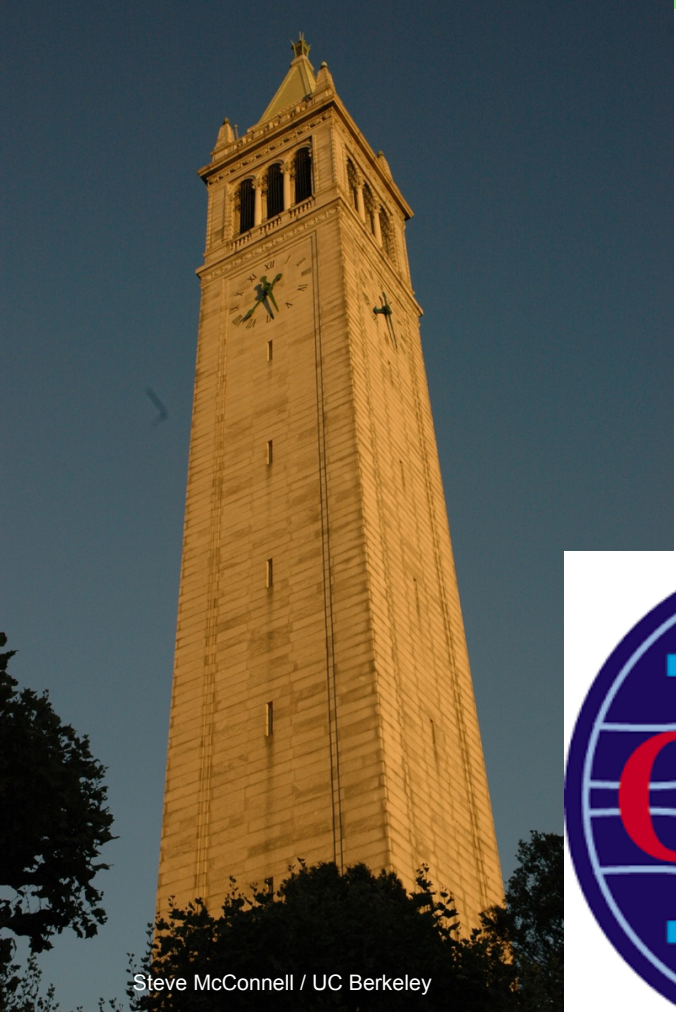
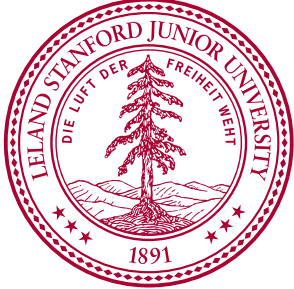
HELLO!



HELLO!



HELLO!



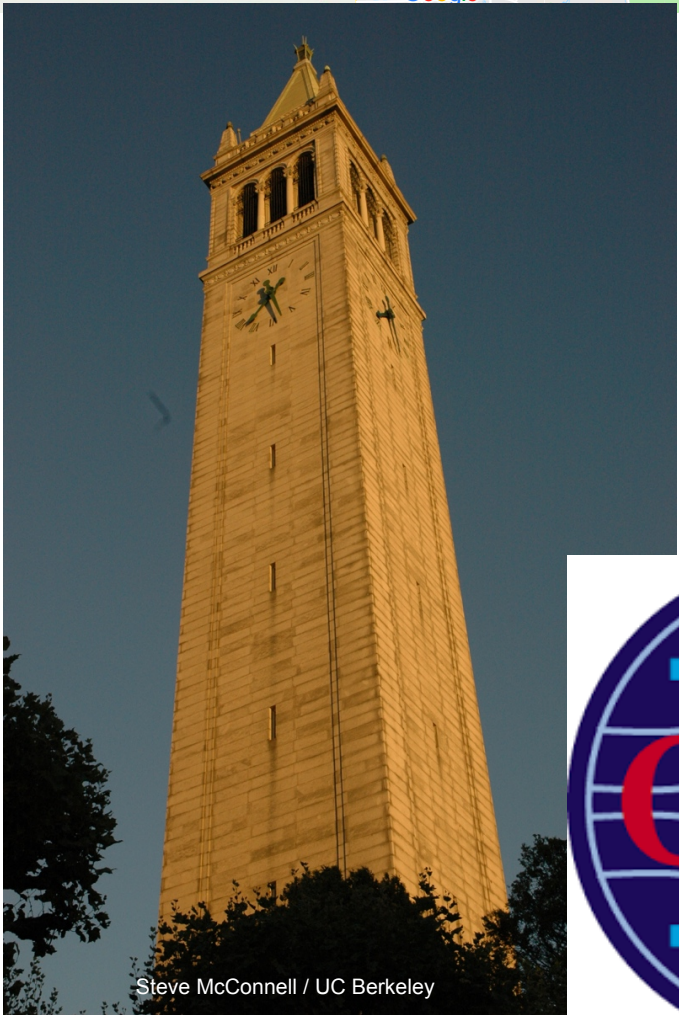
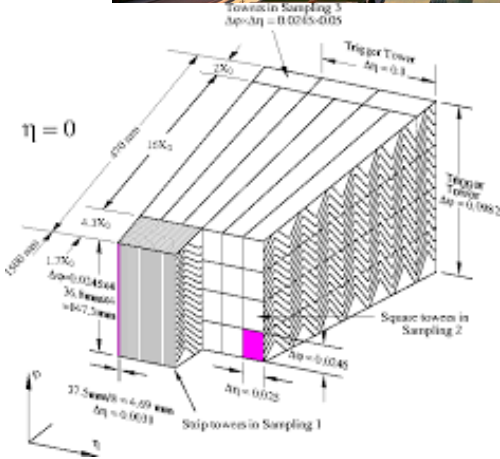
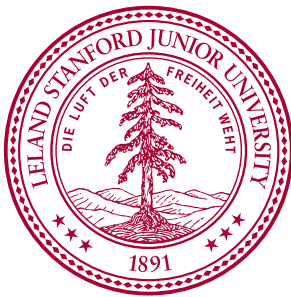
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HELLO!



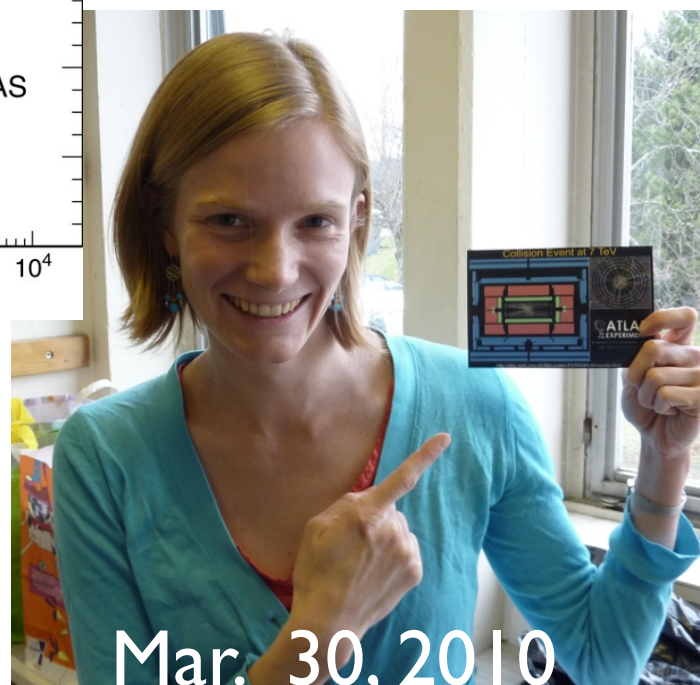
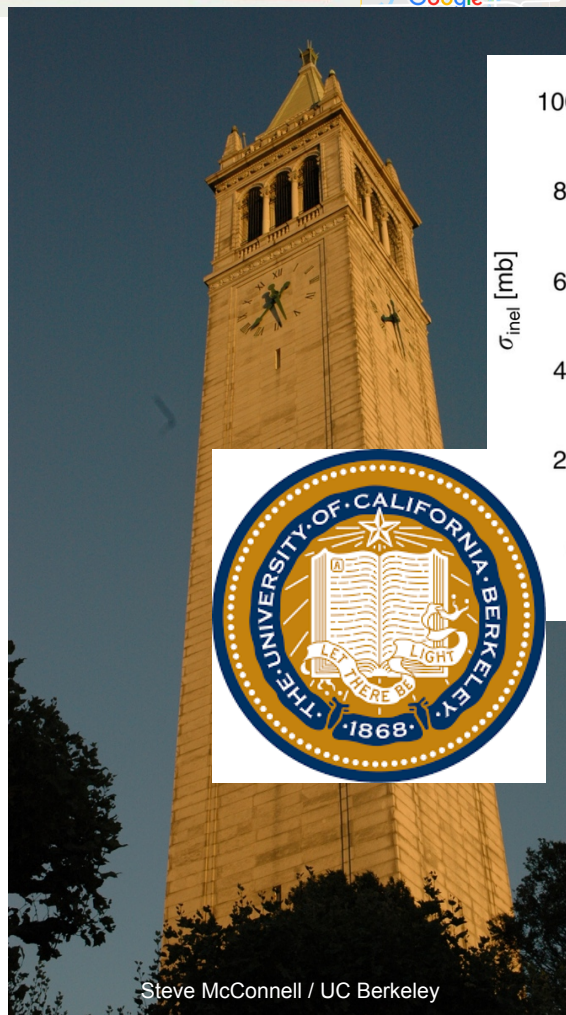
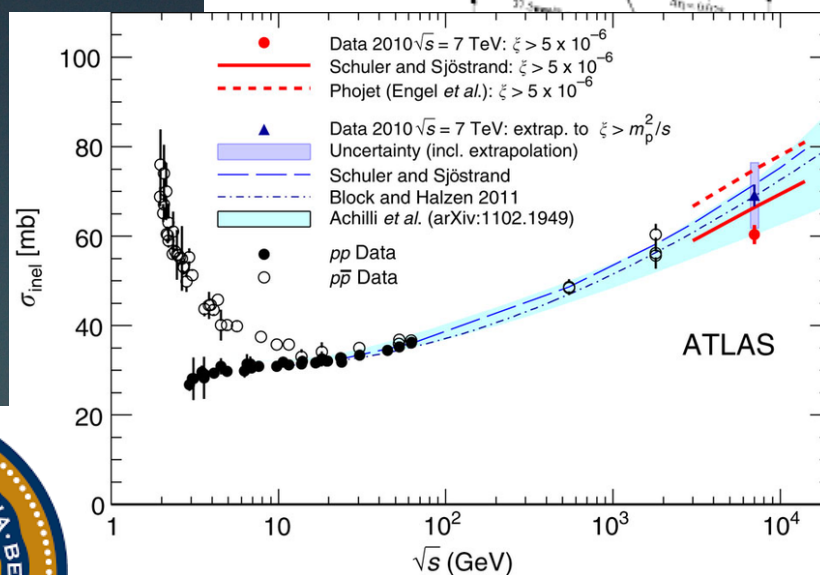
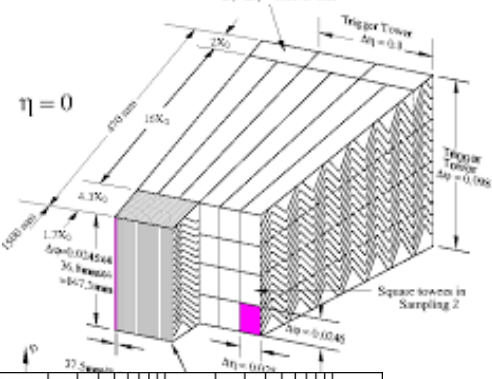
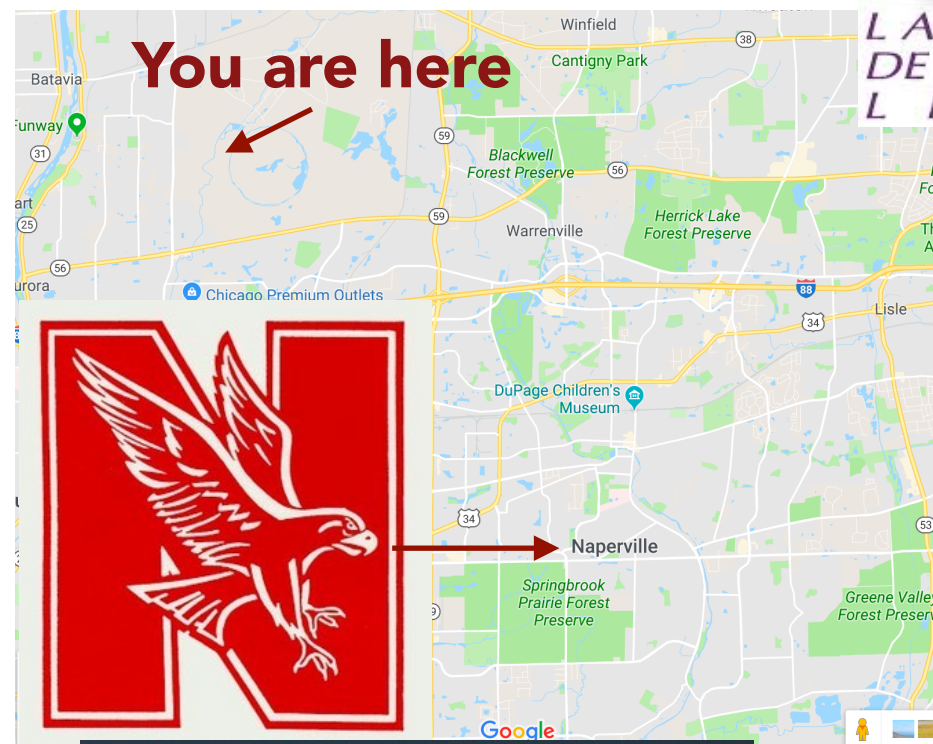
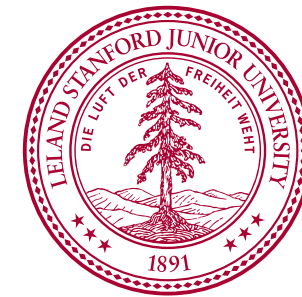
LABORATOIRE
DE L'ACCELERATEUR
LINÉAIRE



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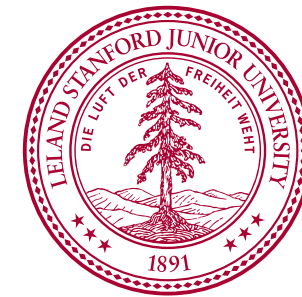


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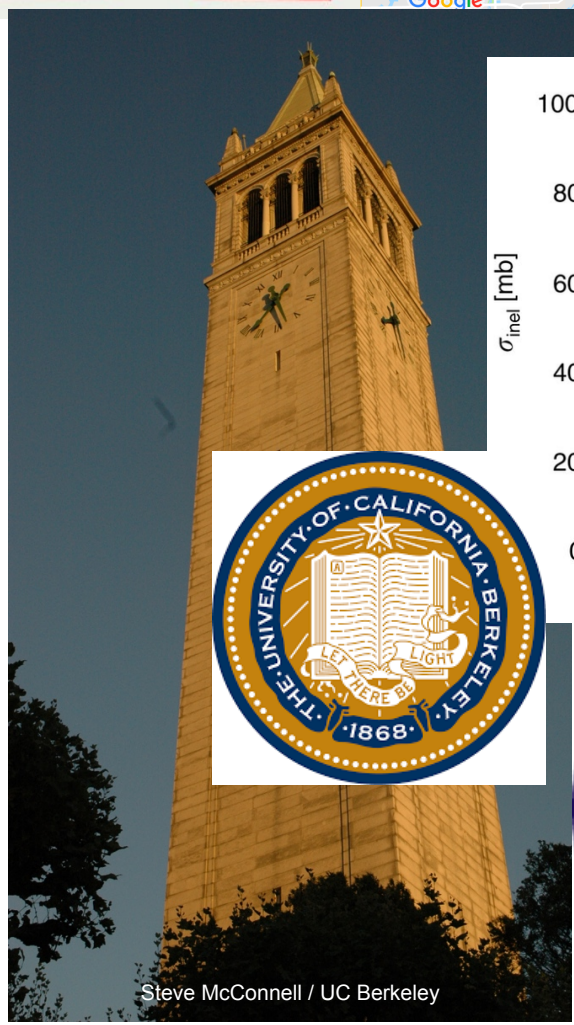
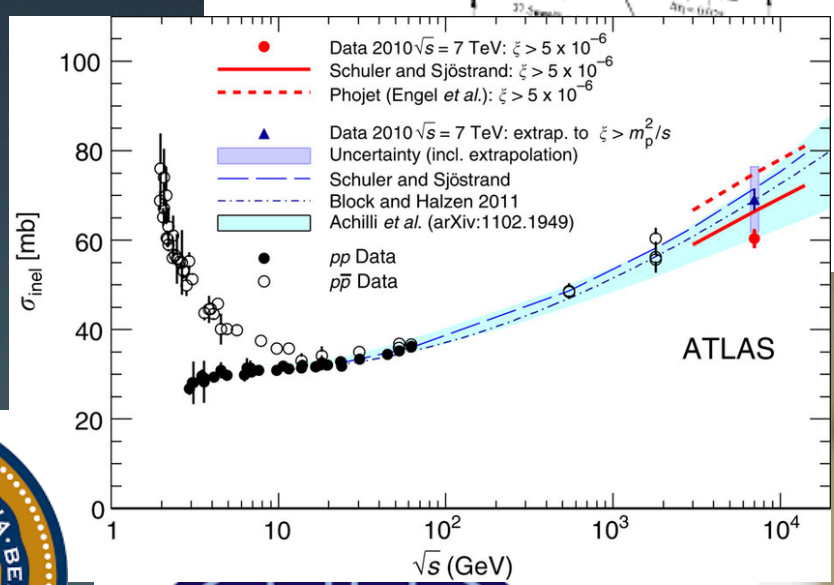
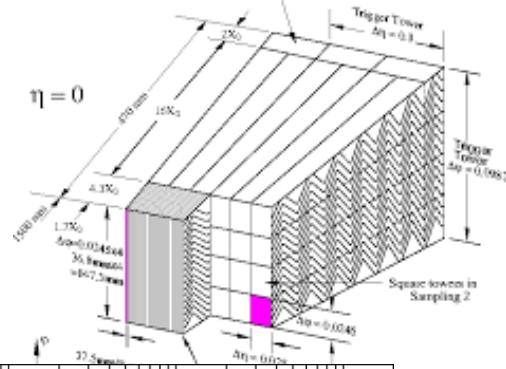
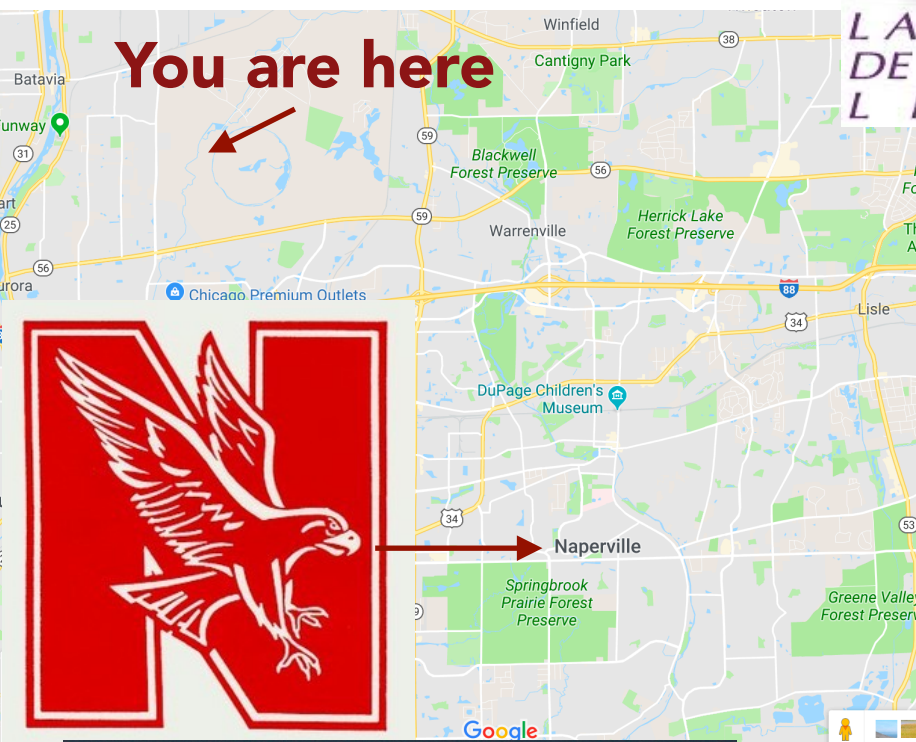


Mar. 30, 2010

HELLO!

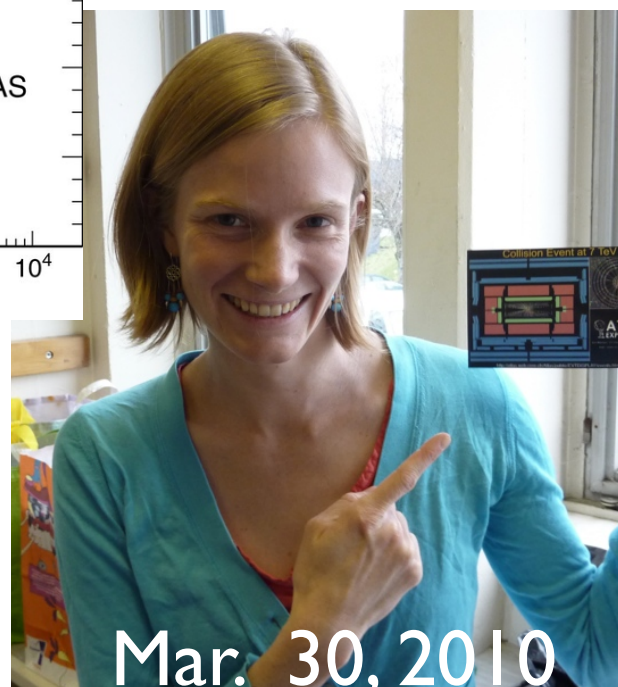
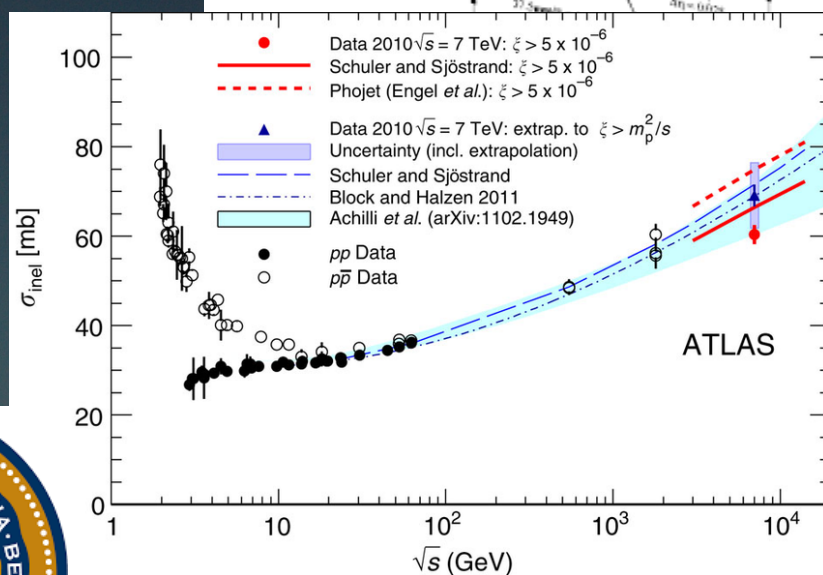
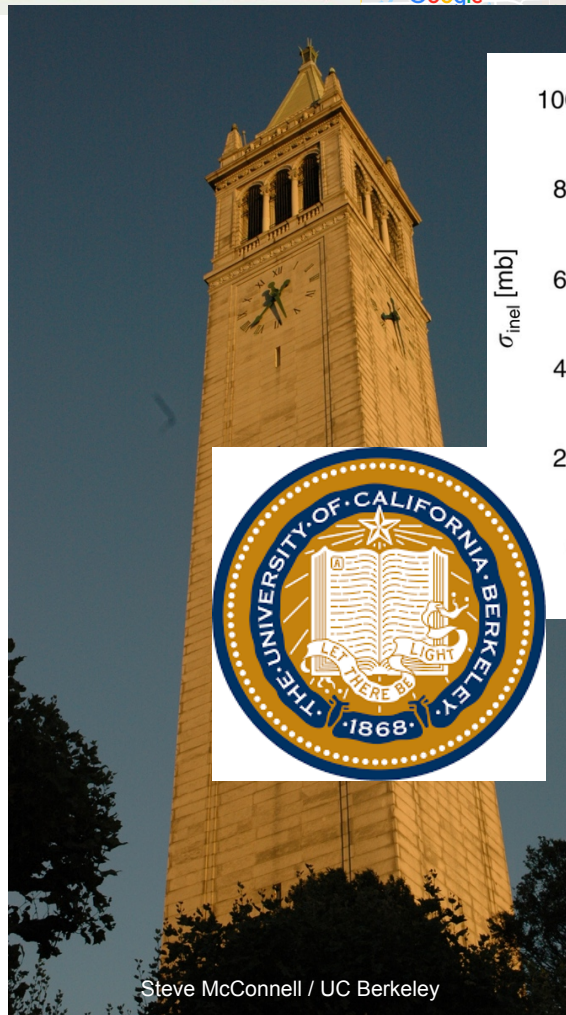
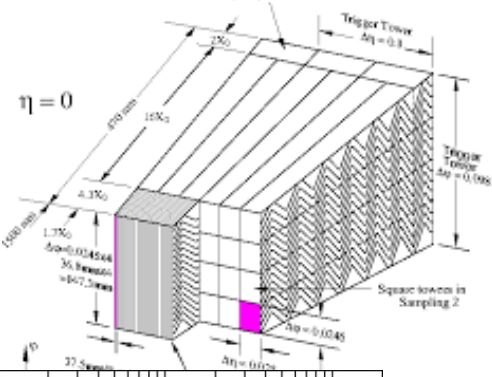
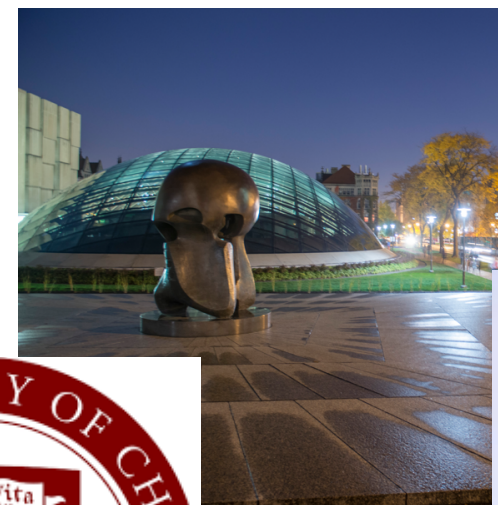
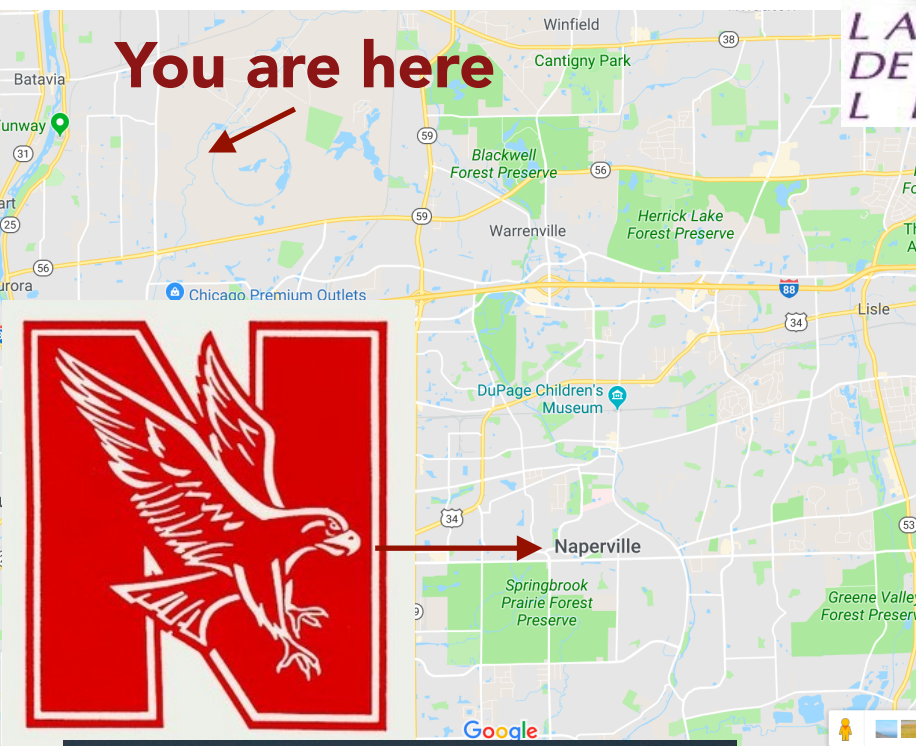
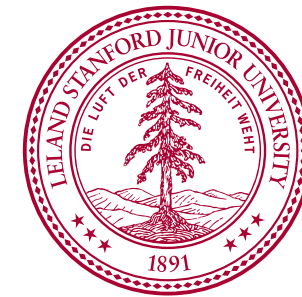


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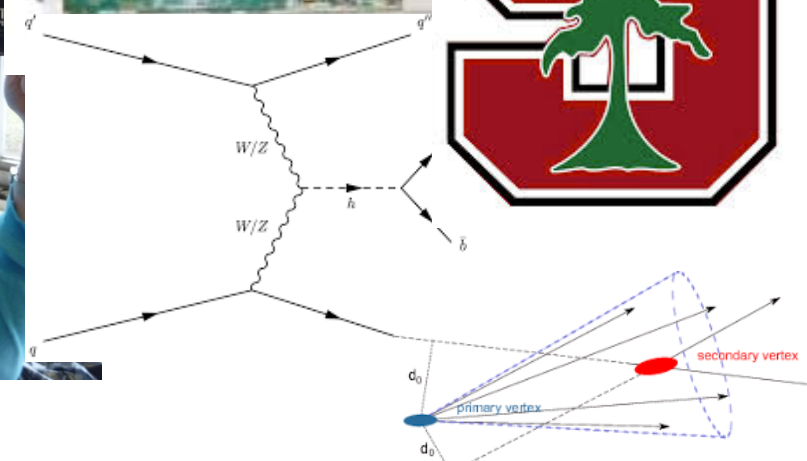


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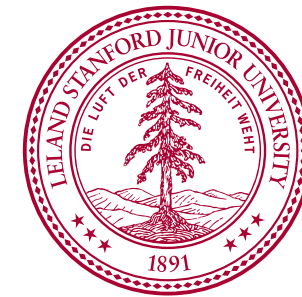
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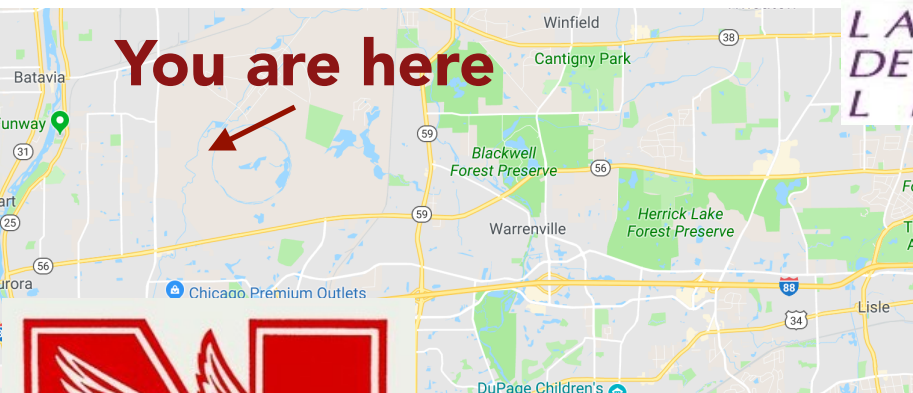
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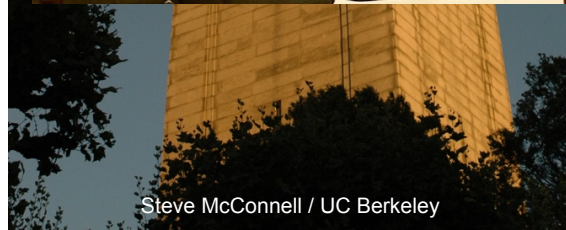
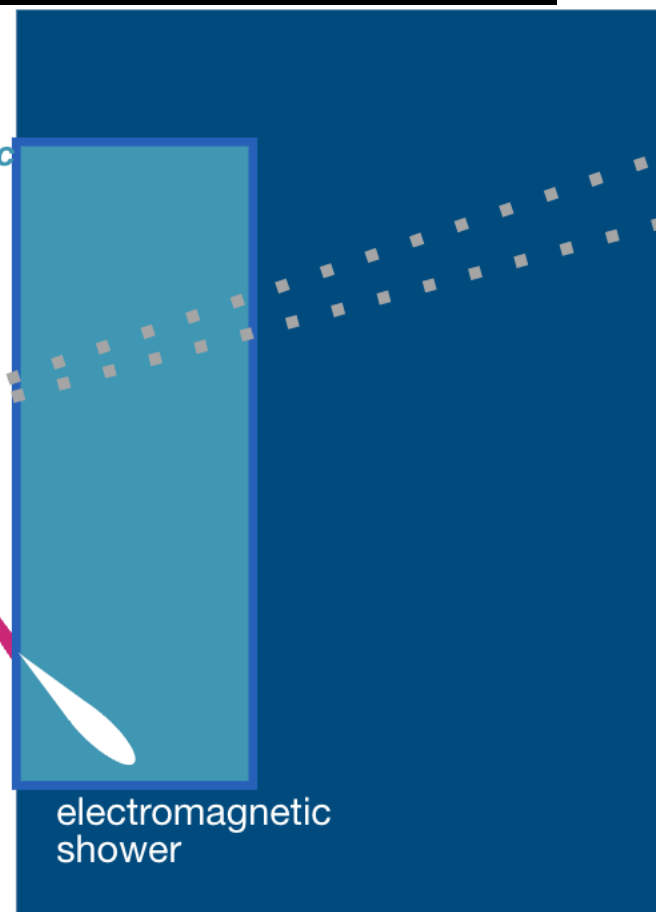
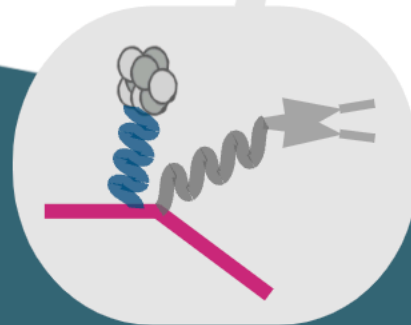
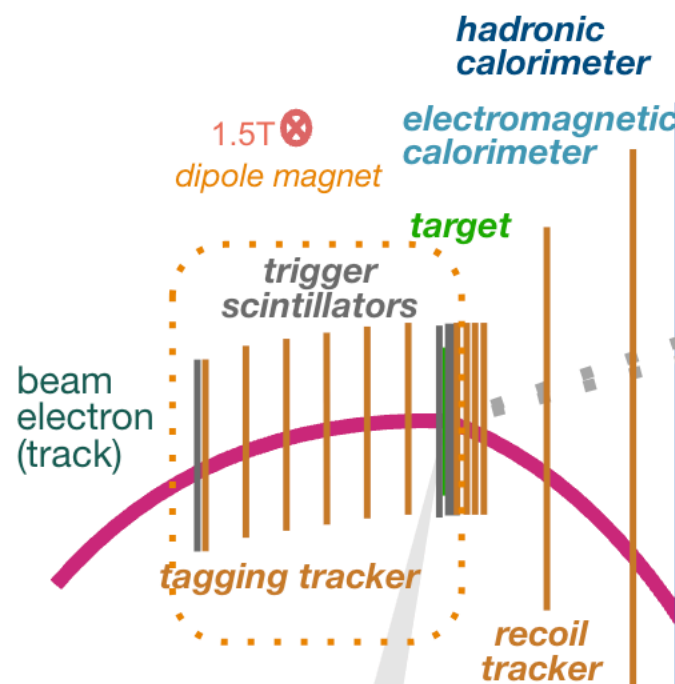
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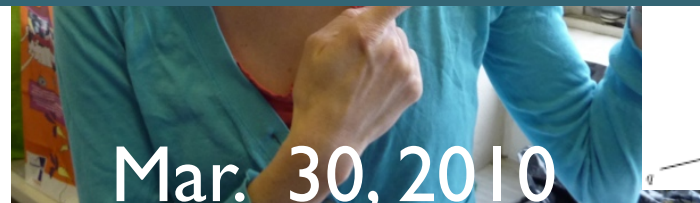
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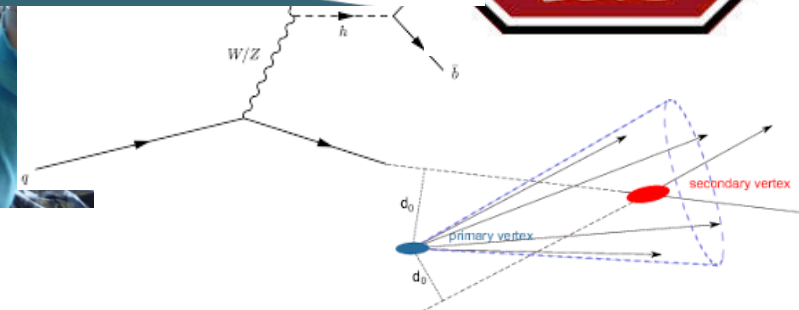
LDMX



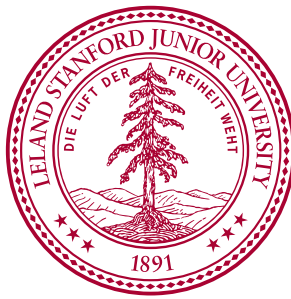
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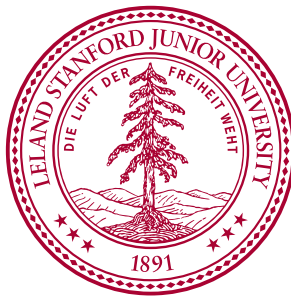


BEFORE WE GET STARTED

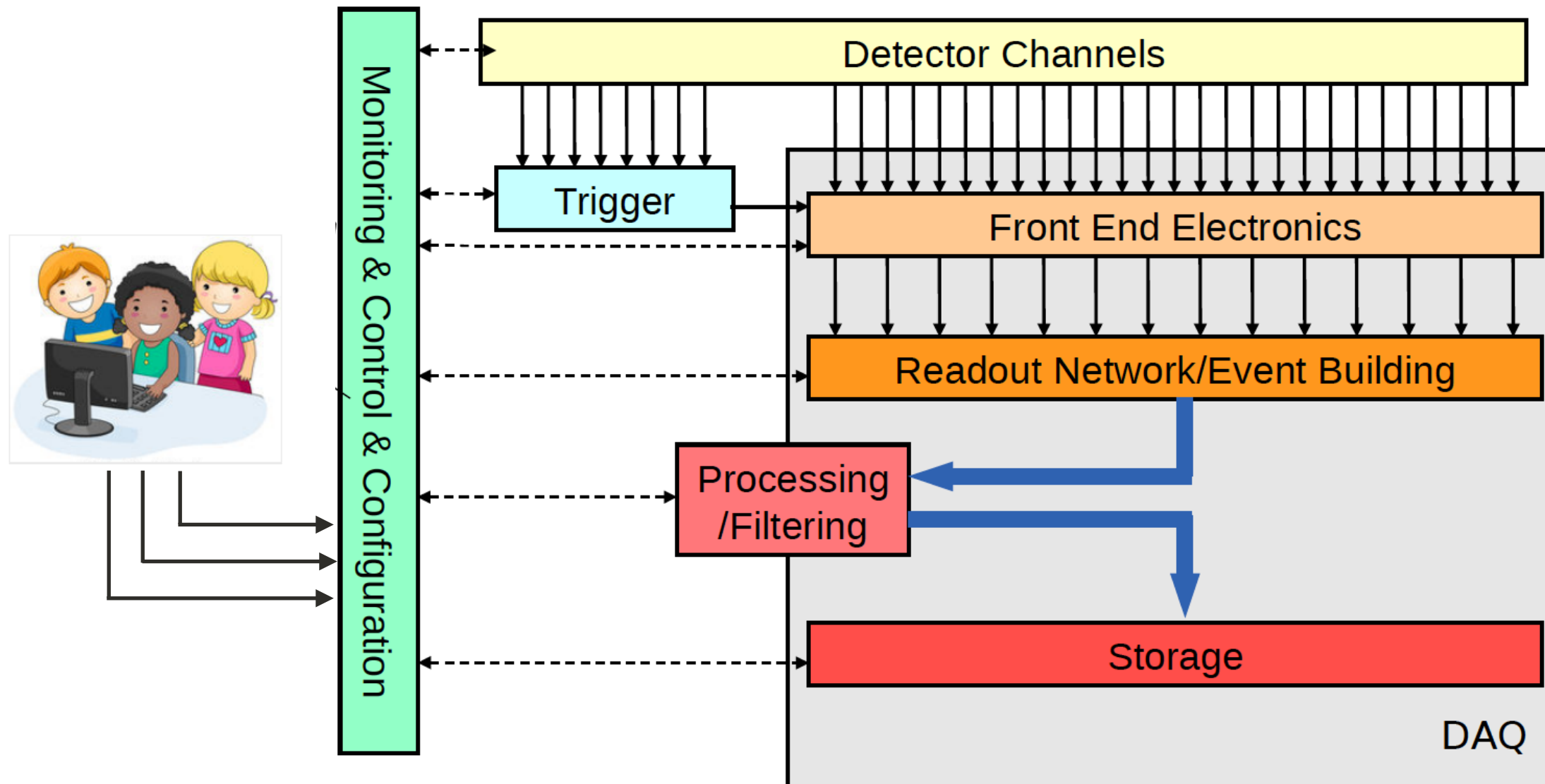


- Will I learn how (insert experiment here) specifically triggers on (insert physics process here)?
 - No, my goal is to give you enough of a framework for understanding TDAQ generally such that you can apply your knowledge to specific situations
- Will I learn basic electronics?
 - Not really. We'll cover a few important concepts, but take a class at your institution or attend the ISOTDAQ or EDIT schools for more information
- These lectures are inspired by Andrea Negri, Wainer Vandelli, and Roberto Ferrari's lectures at ISOTDAQ and CERN.
- These are accelerator-heavy, but the concepts apply somewhat generally so please forgive me!

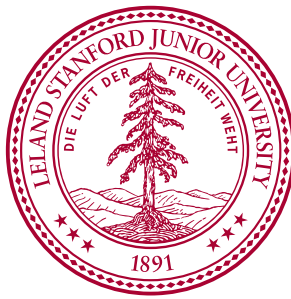
TDAQ COMPONENTS



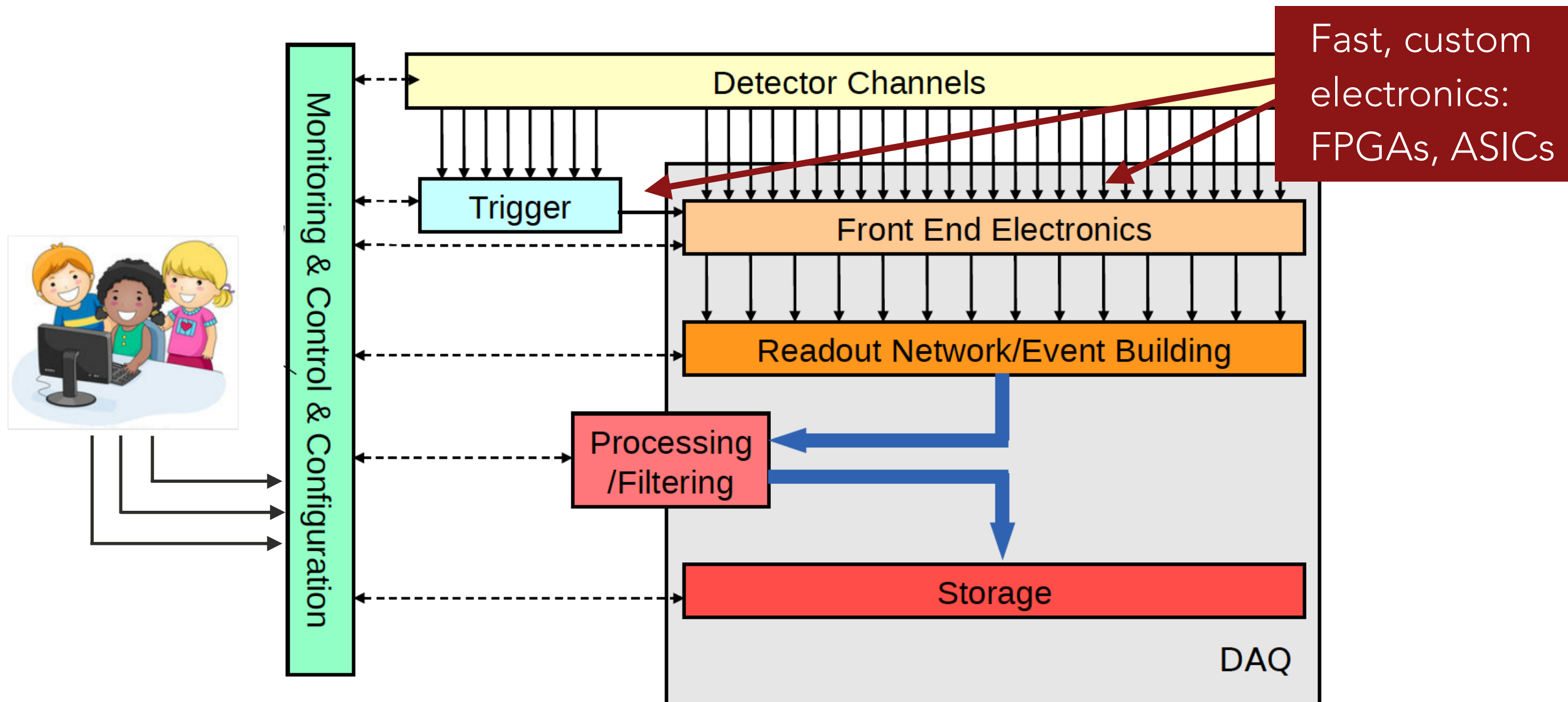
- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)



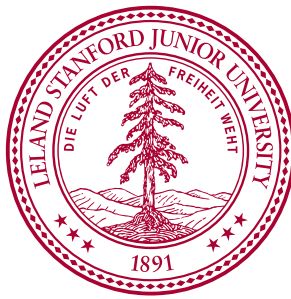
TDAQ COMPONENTS



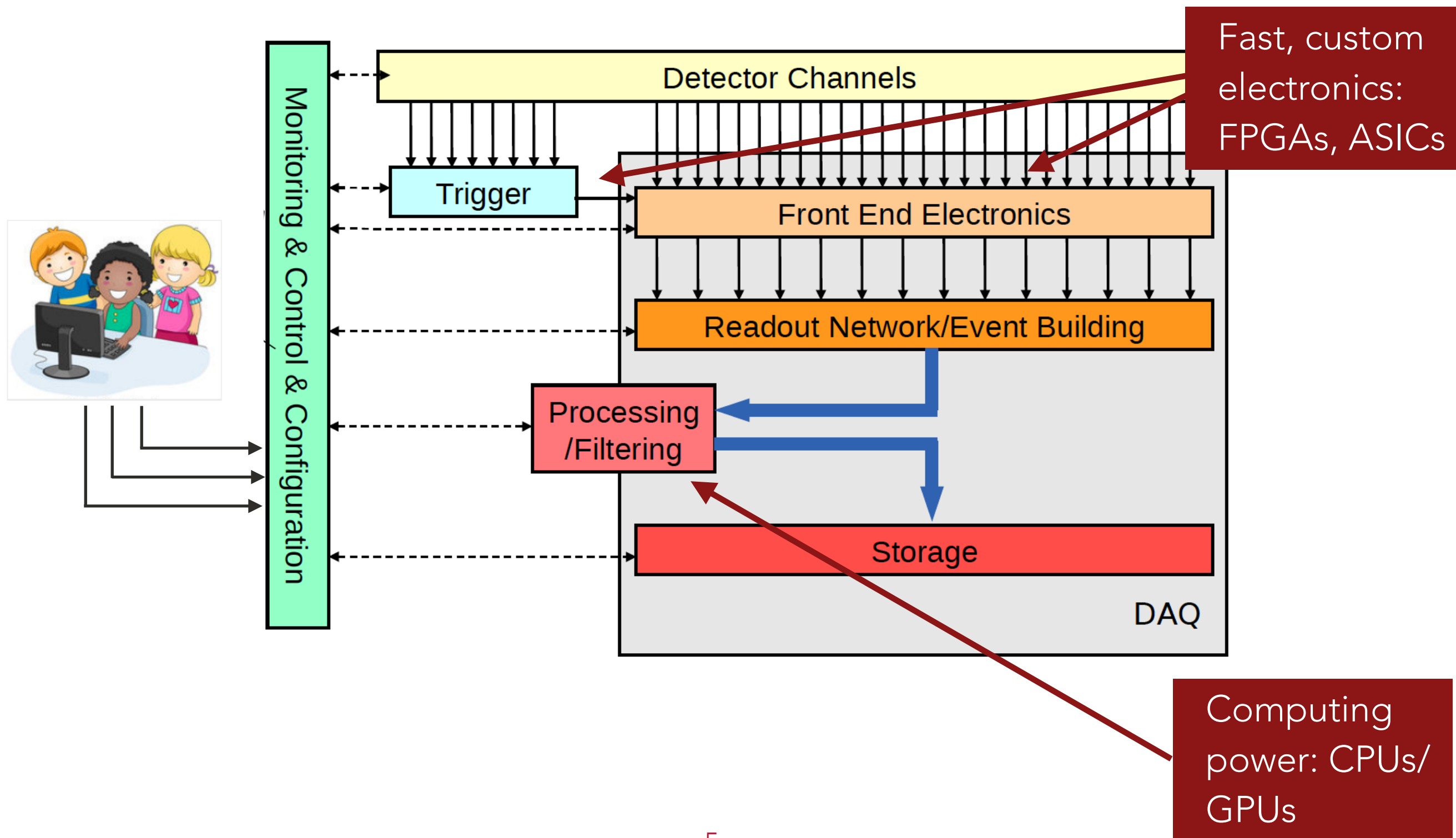
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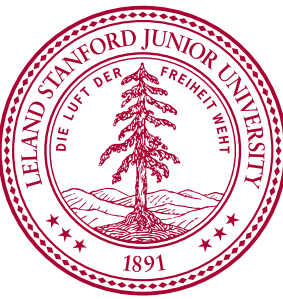
TDAQ COMPONENTS



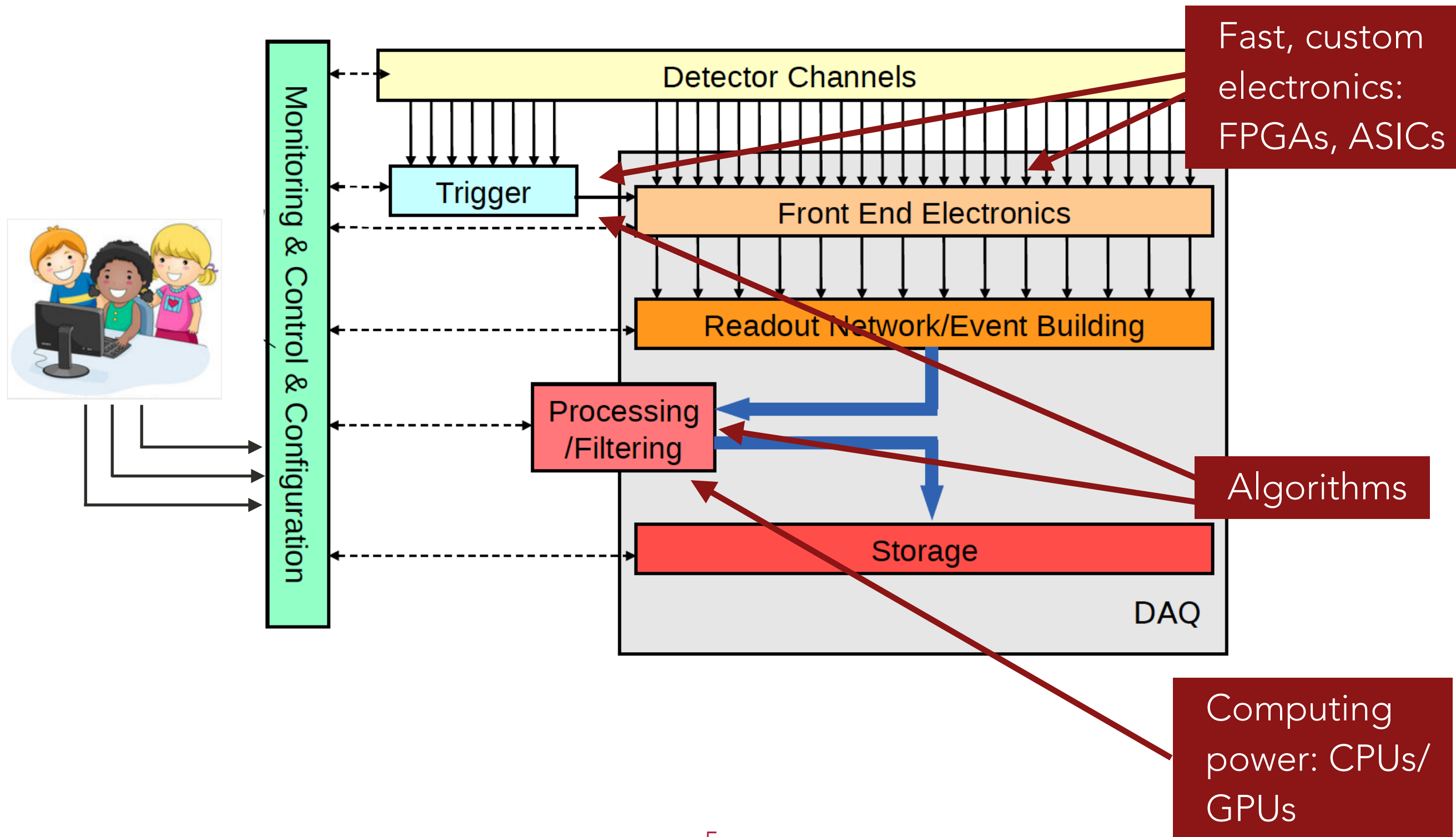
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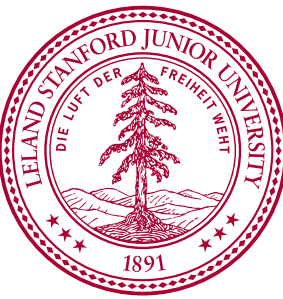
TDAQ COMPONENTS



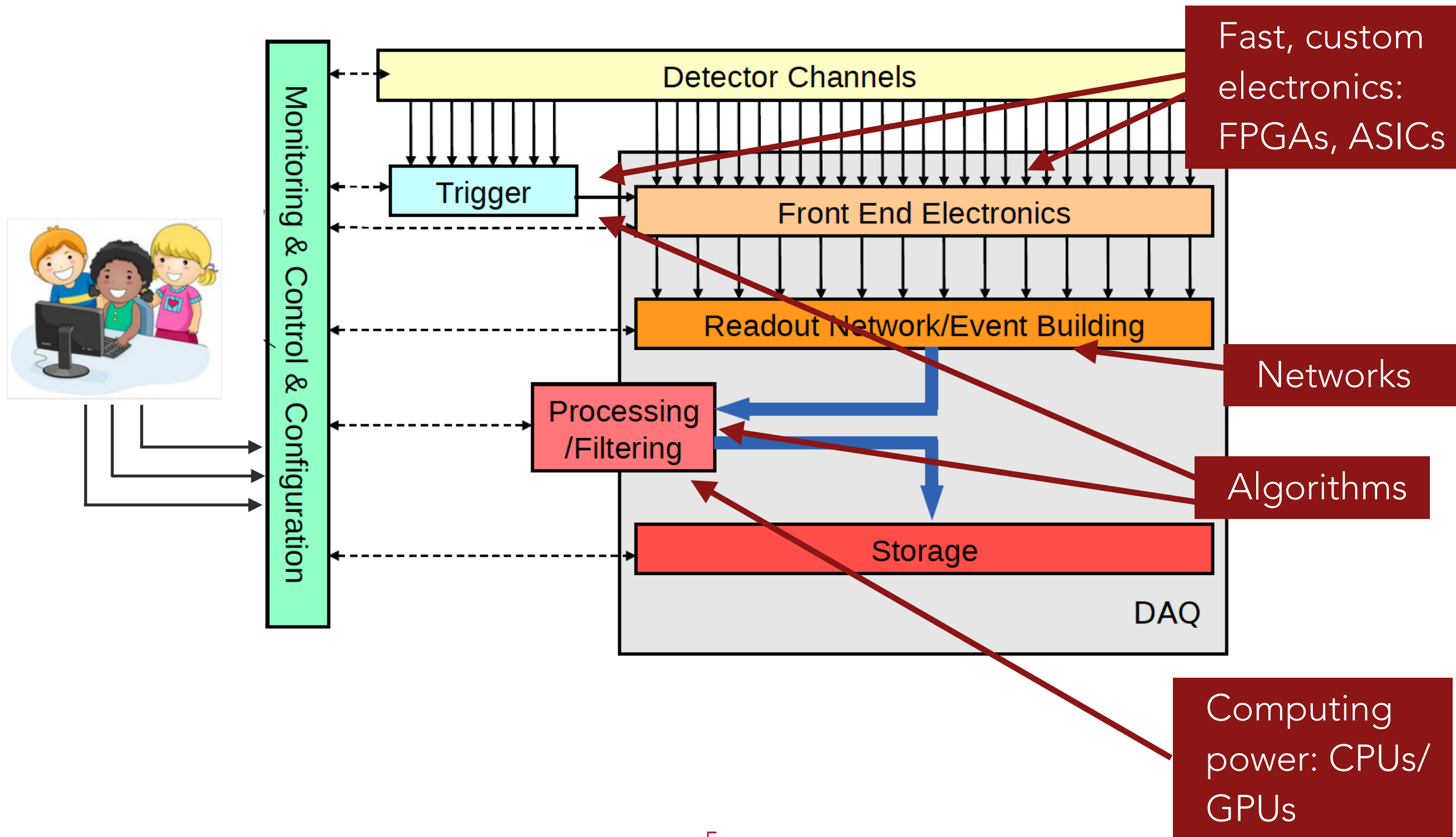
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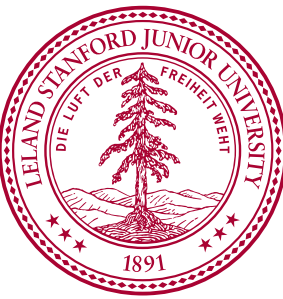
TDAQ COMPONENTS



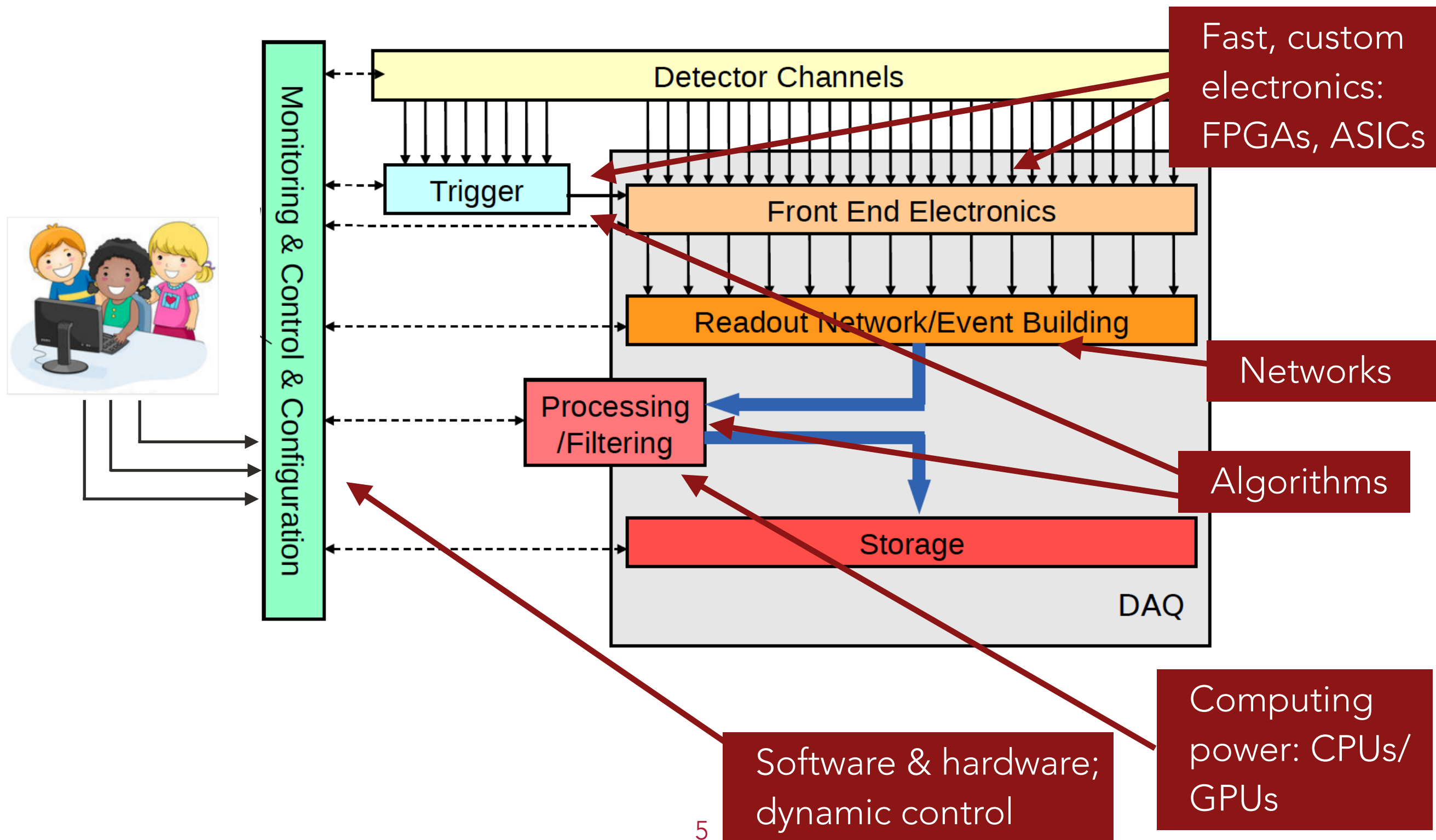
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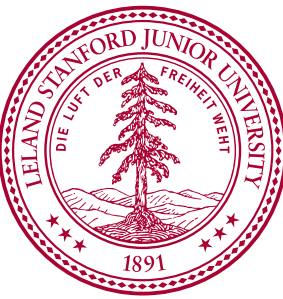
TDAQ COMPONENTS



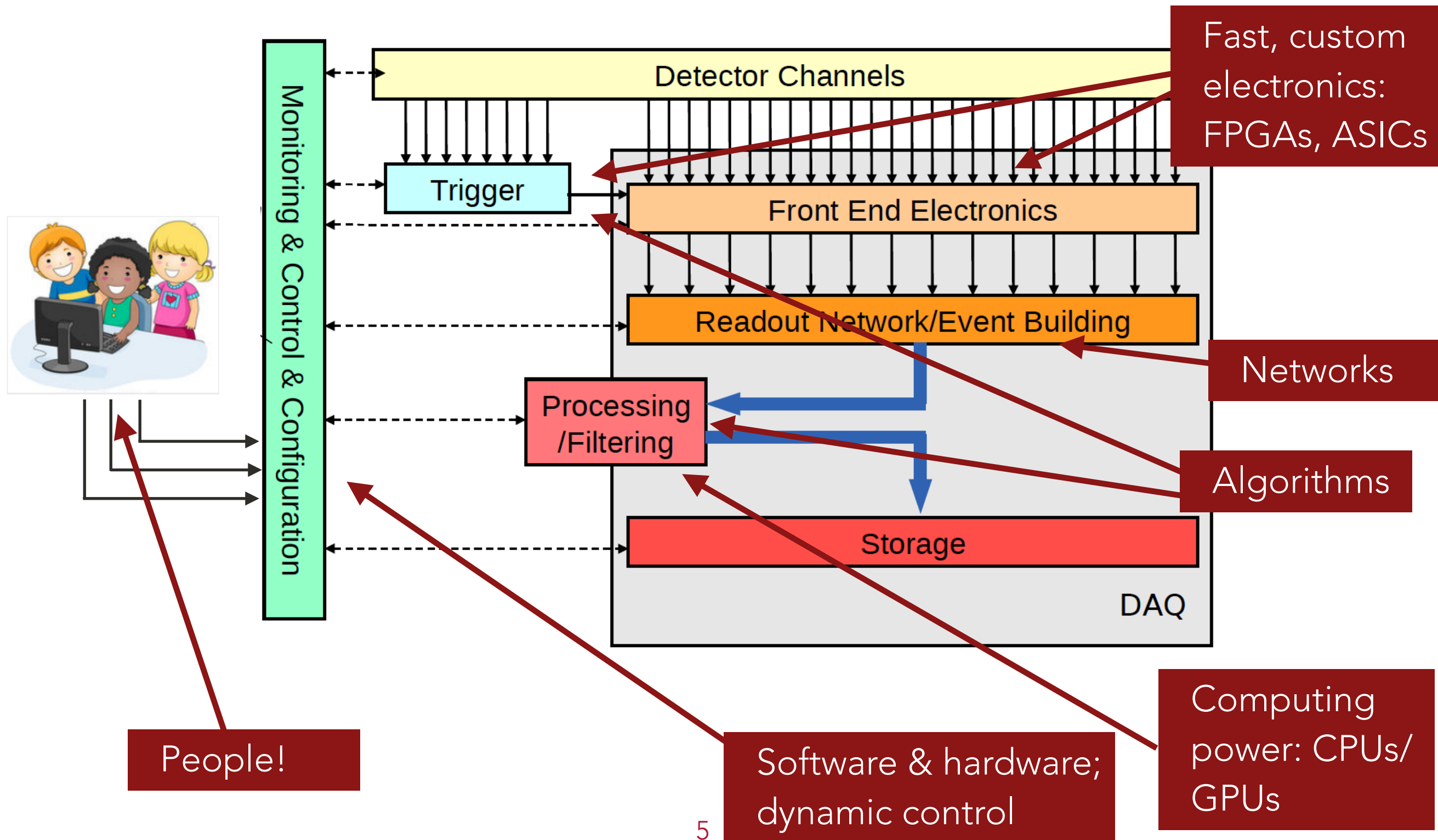
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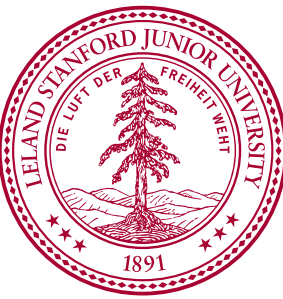
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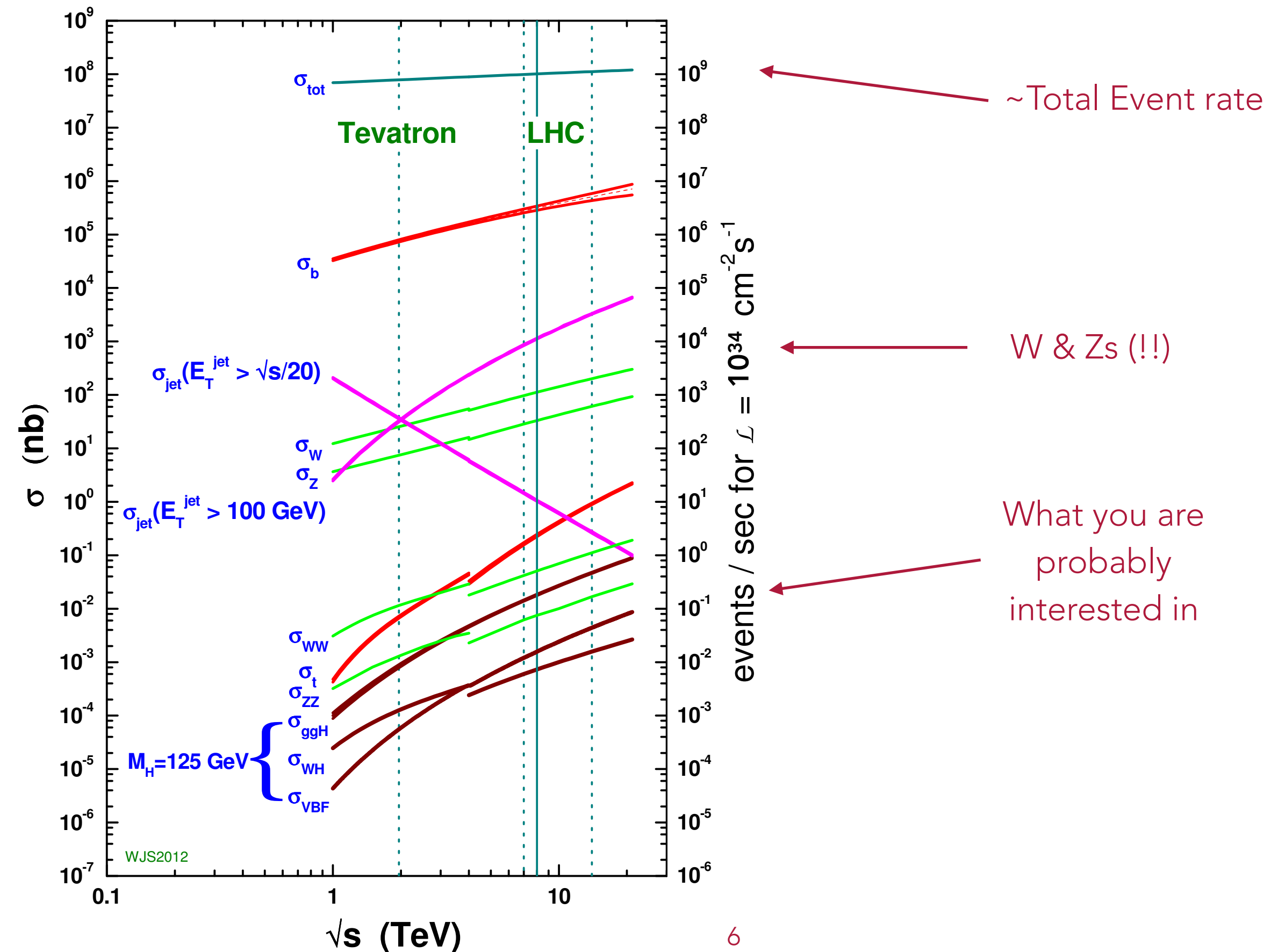
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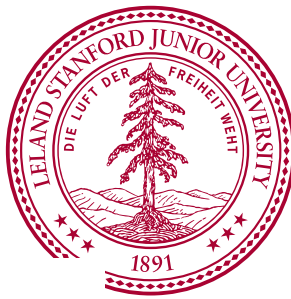
THE CHALLENGE : PART 1



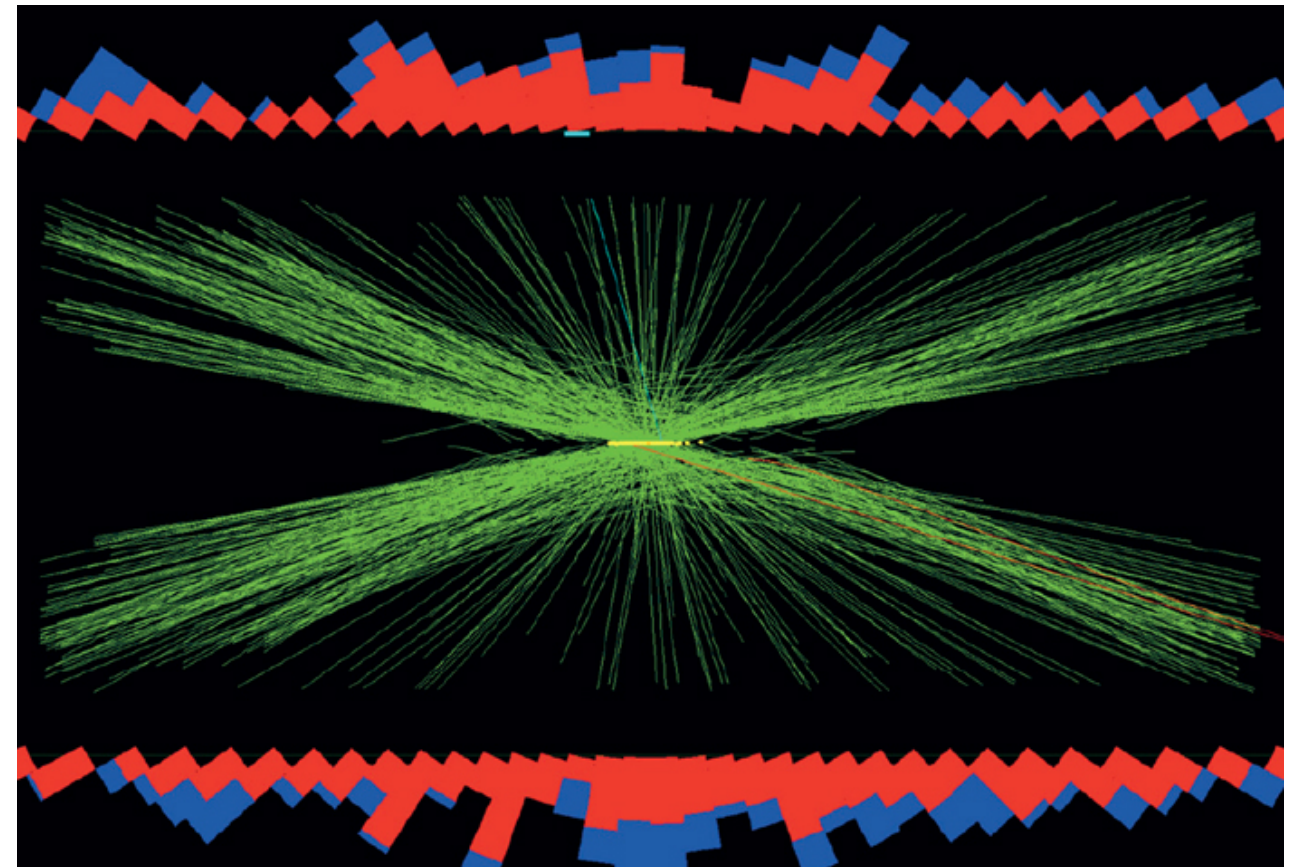
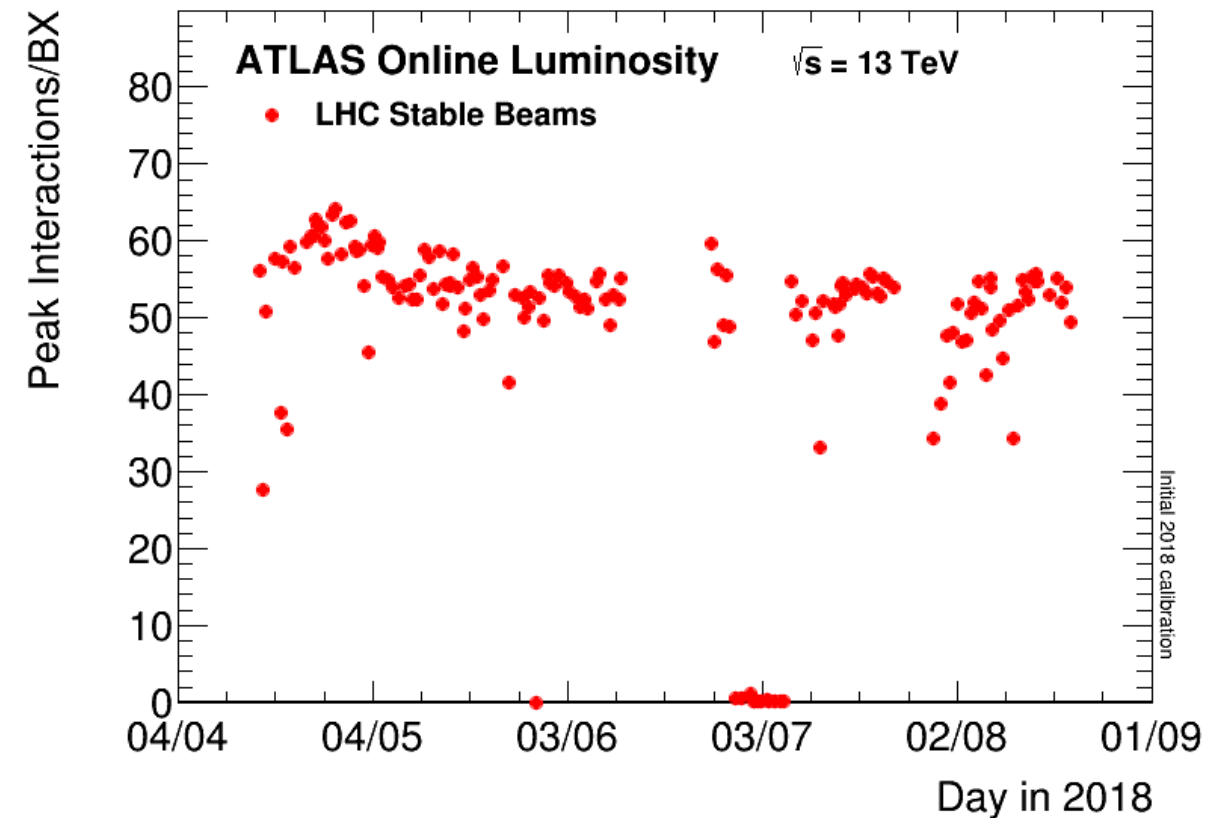
proton - (anti)proton cross sections



THE CHALLENGE : PART 2

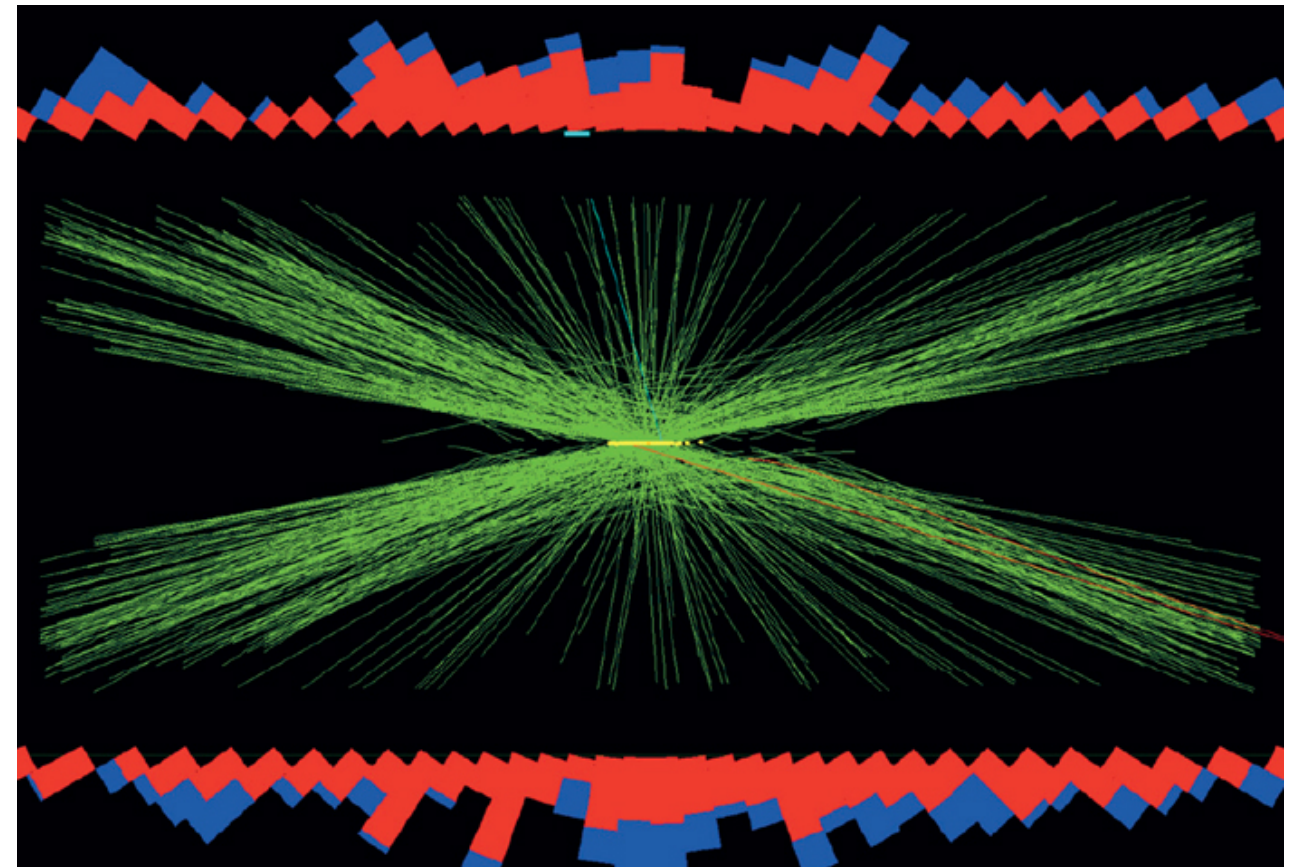
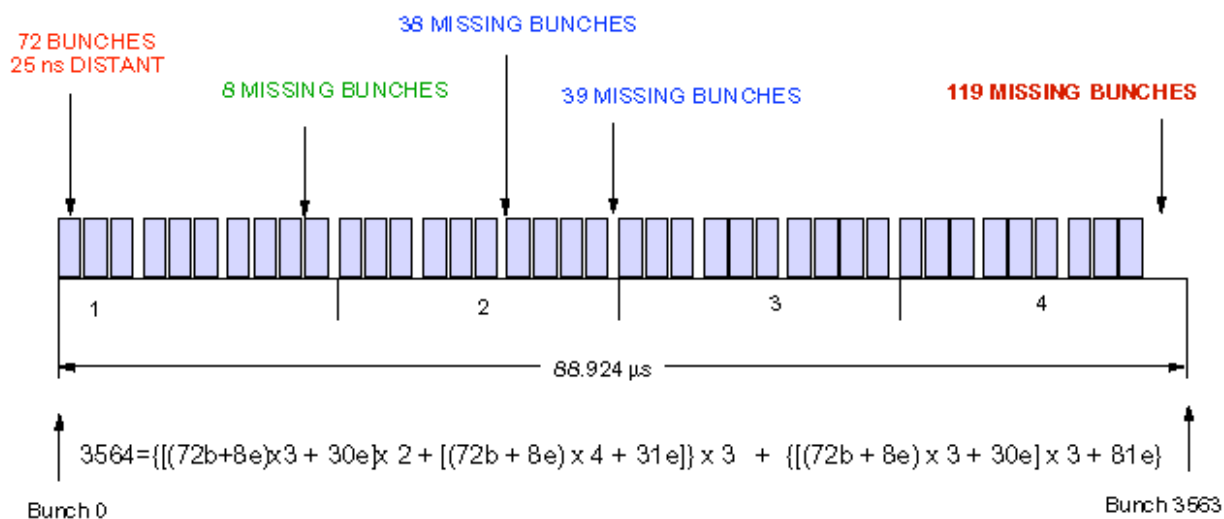
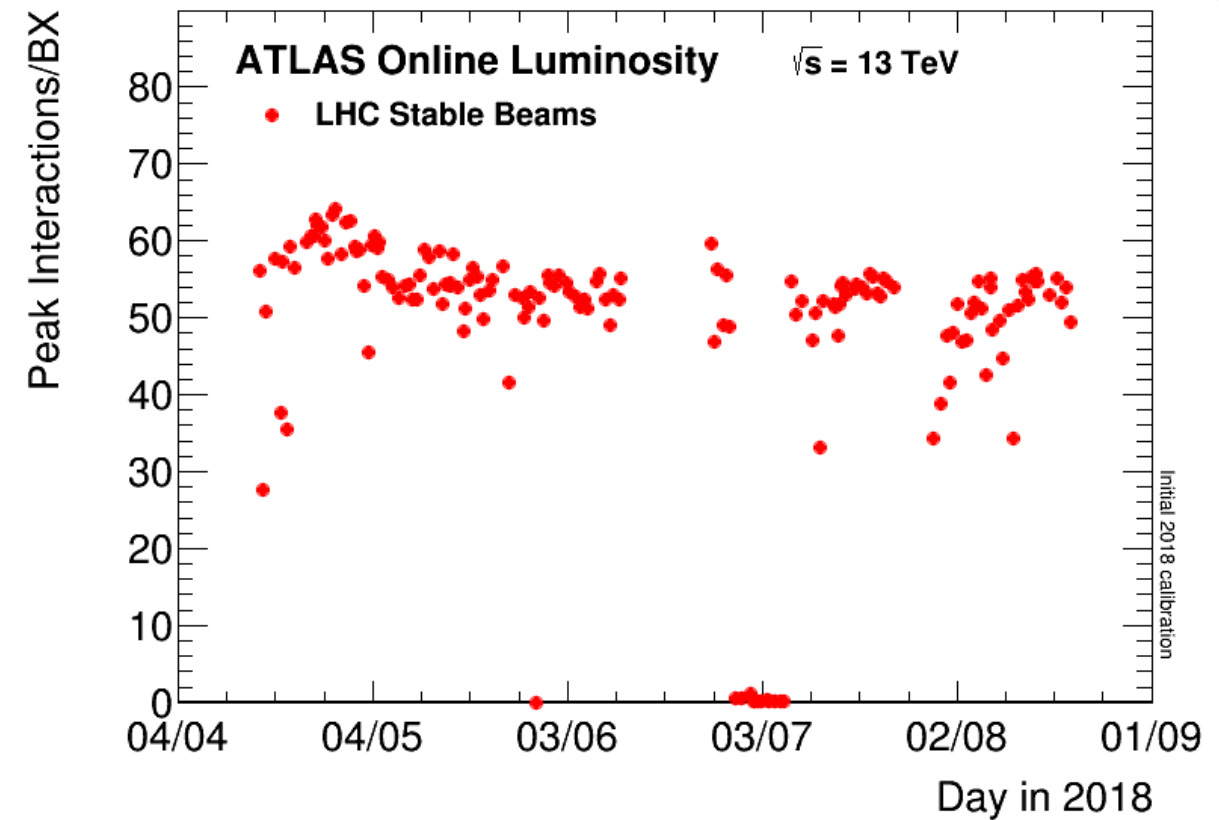


- A lot of things are going on at the same time!
- ~50 simultaneous pp collisions in LHC Runs 2 & 3 (LHC design was 23)
- Collisions every ~25ns
- Come in bunches and trains



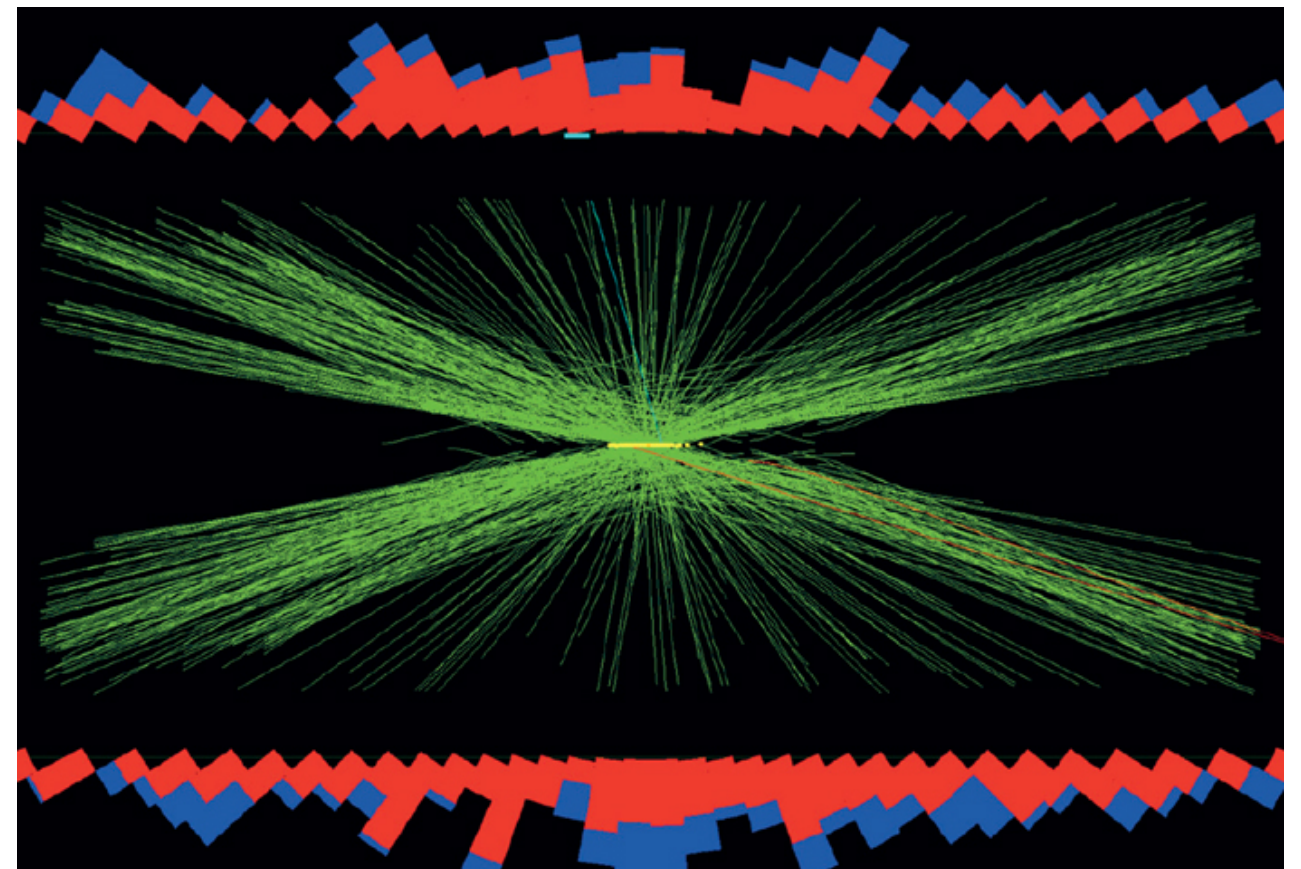
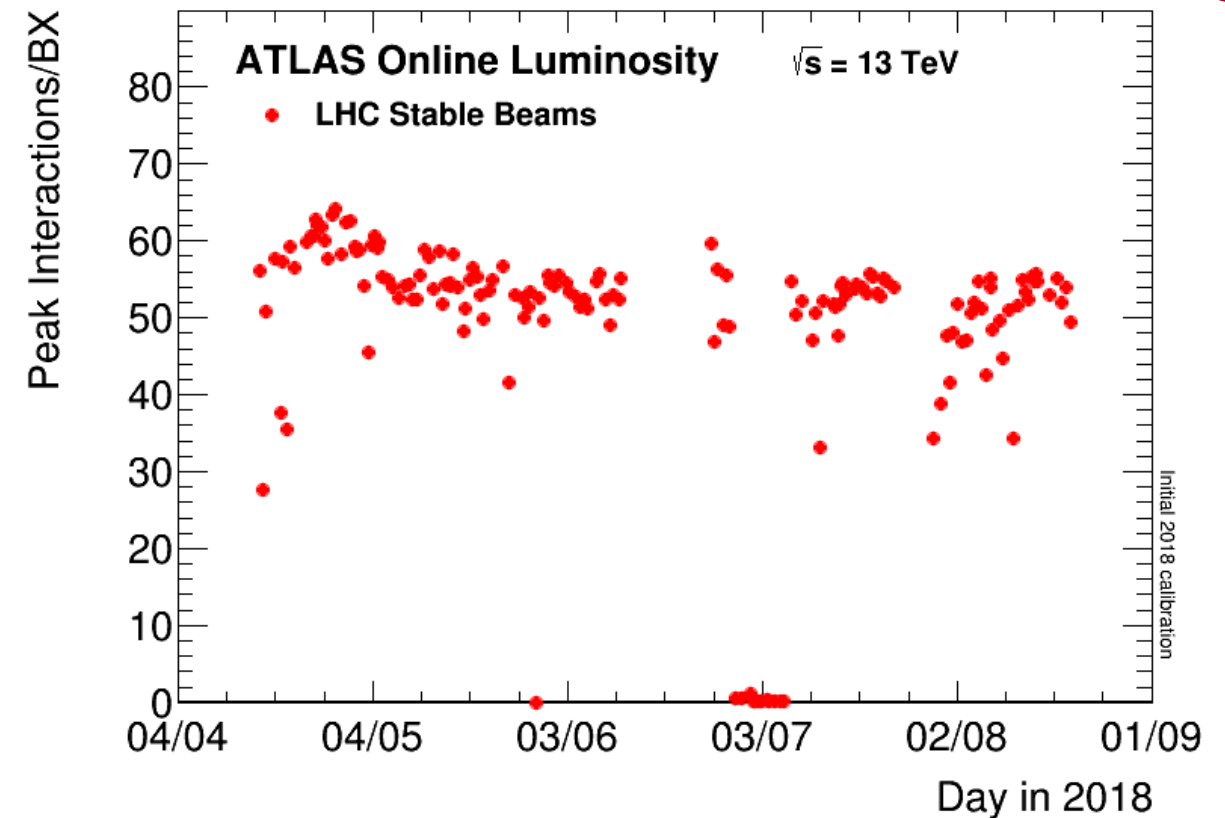
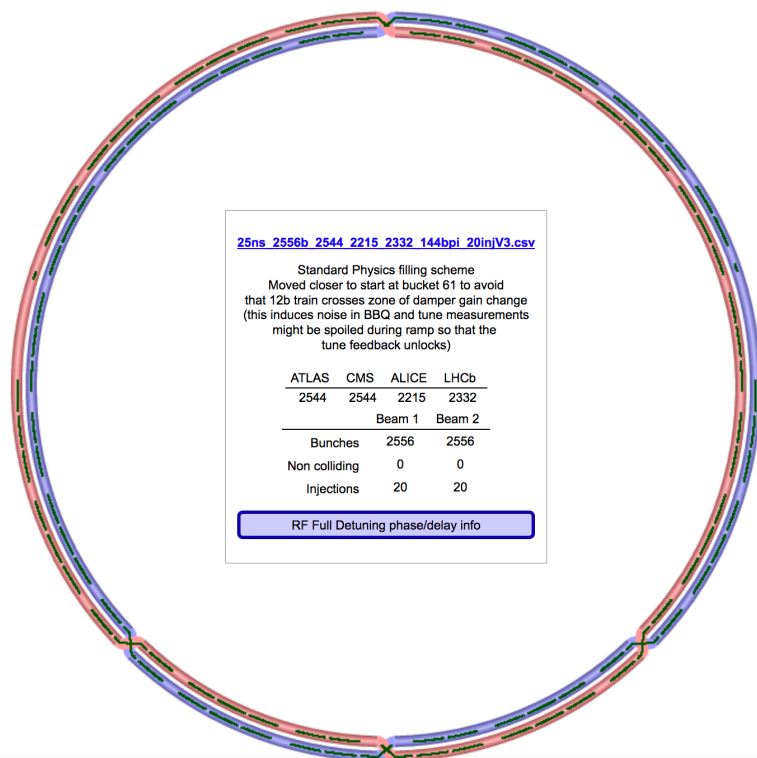
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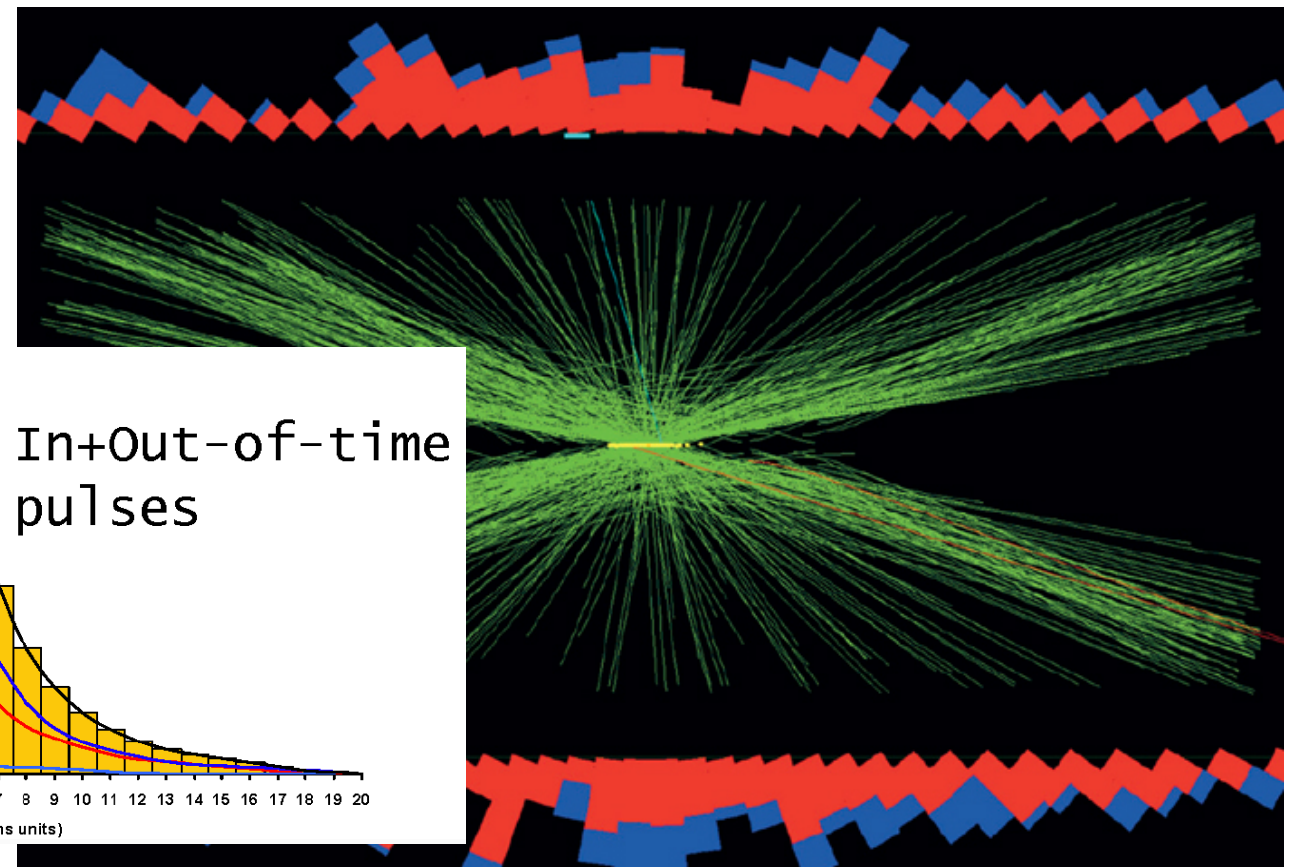
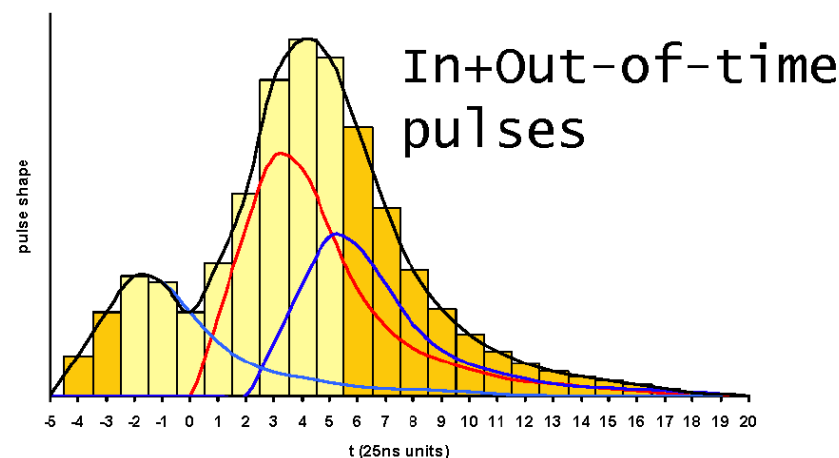
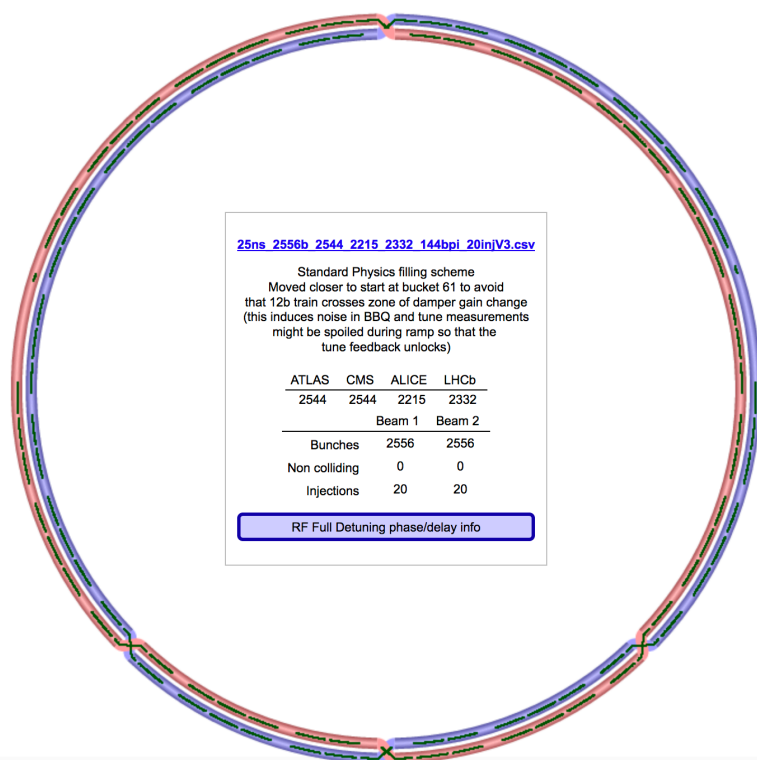
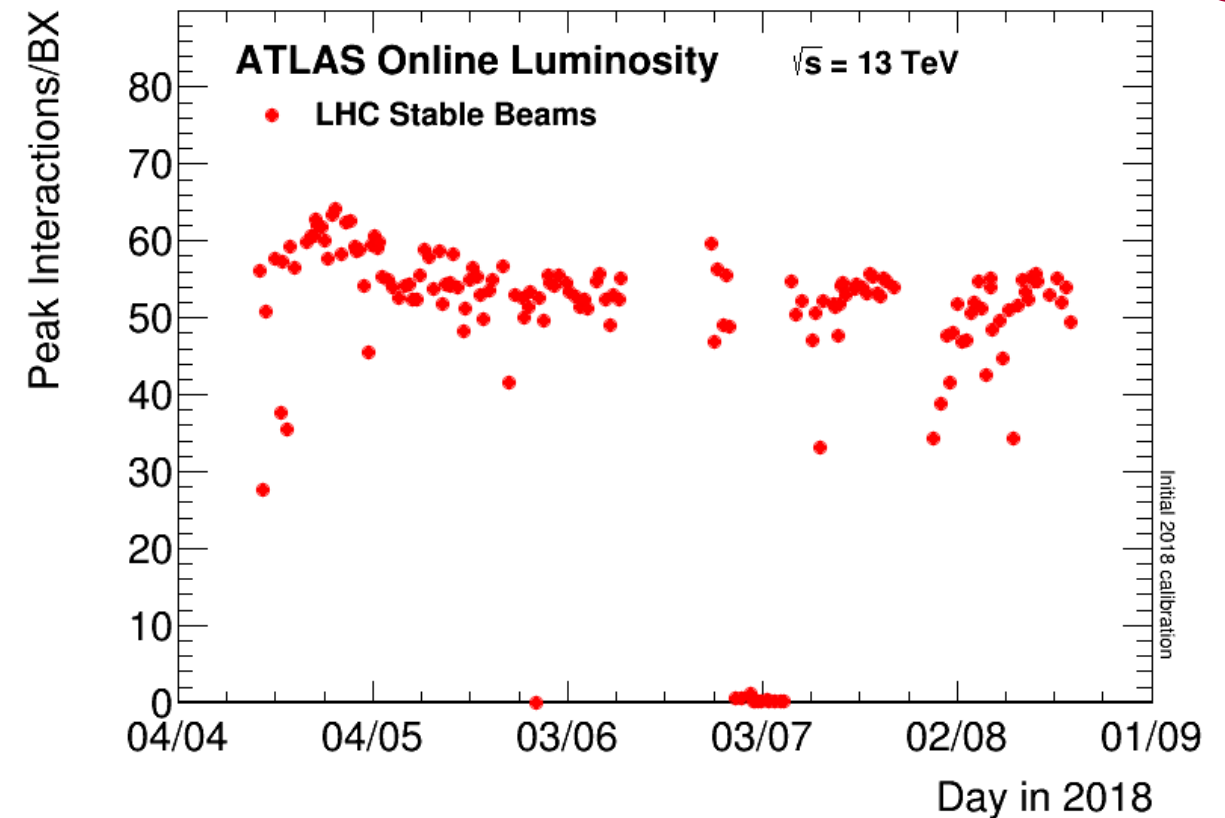
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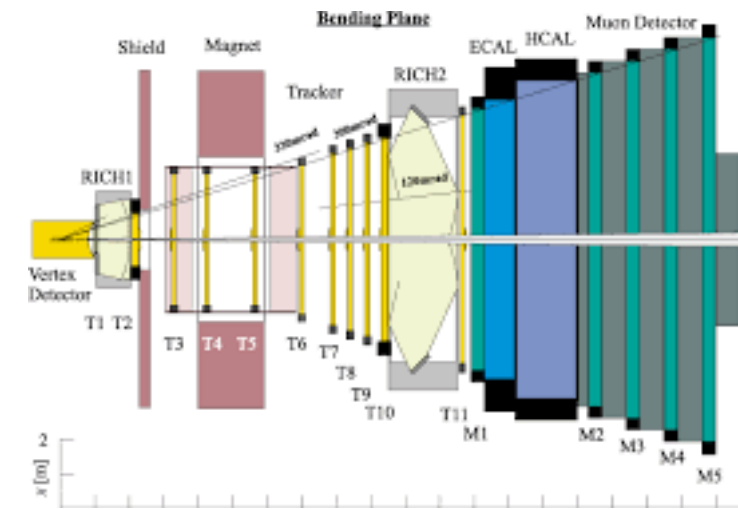
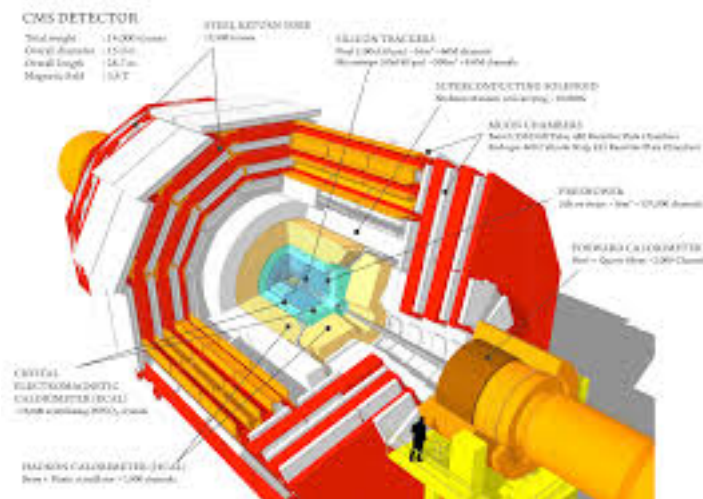
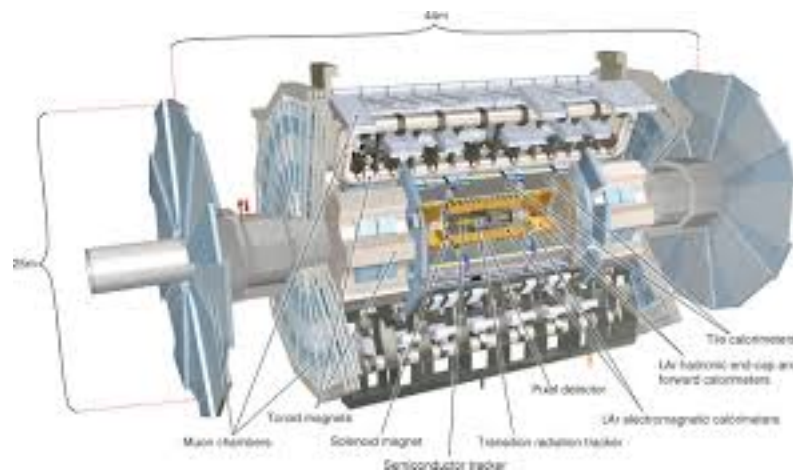
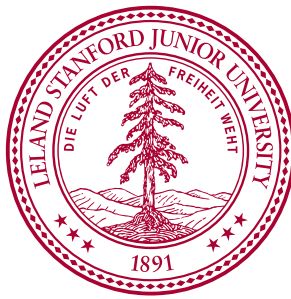


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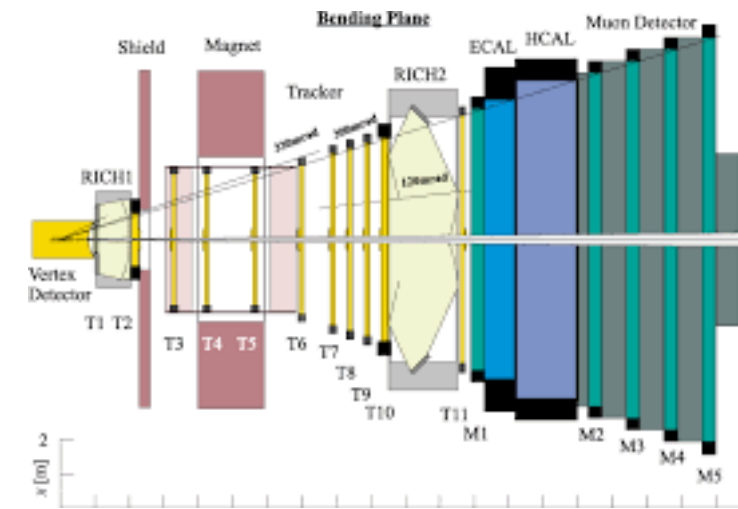
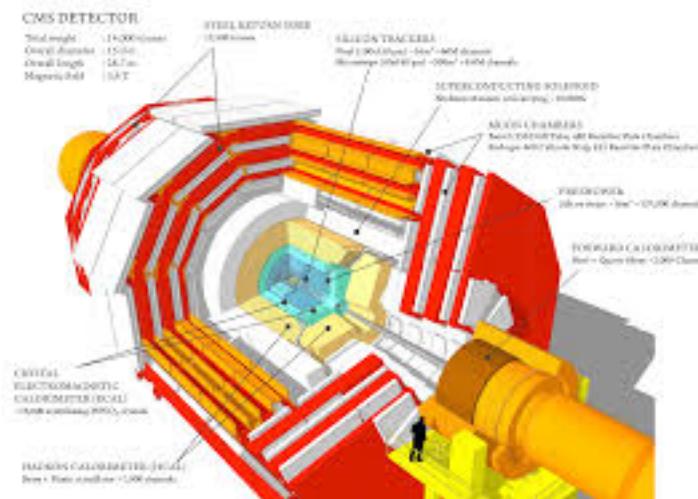
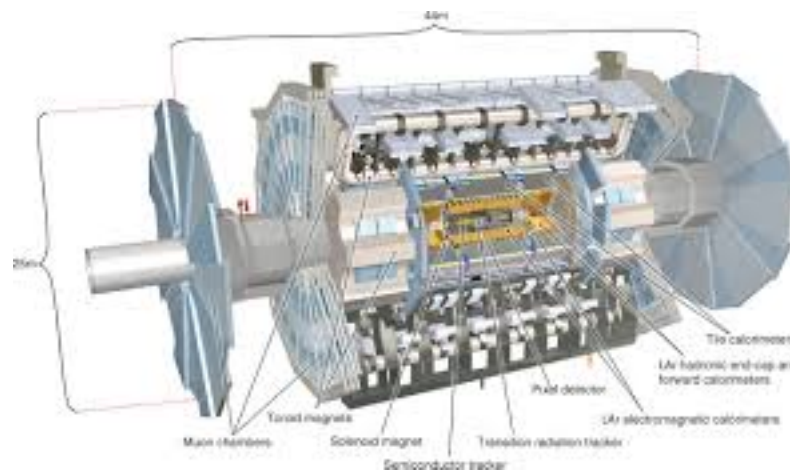
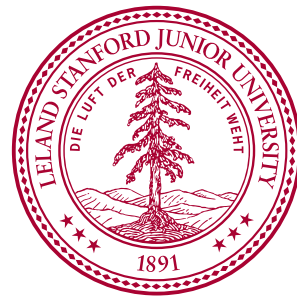
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THE CHALLENGE: PART 3

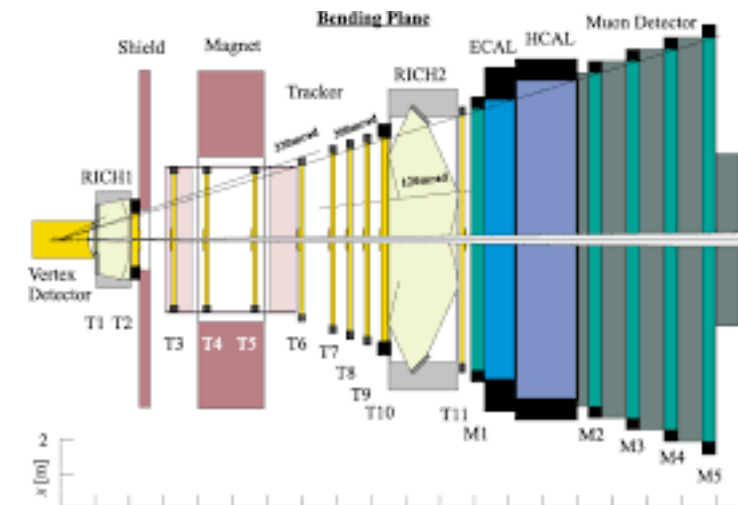
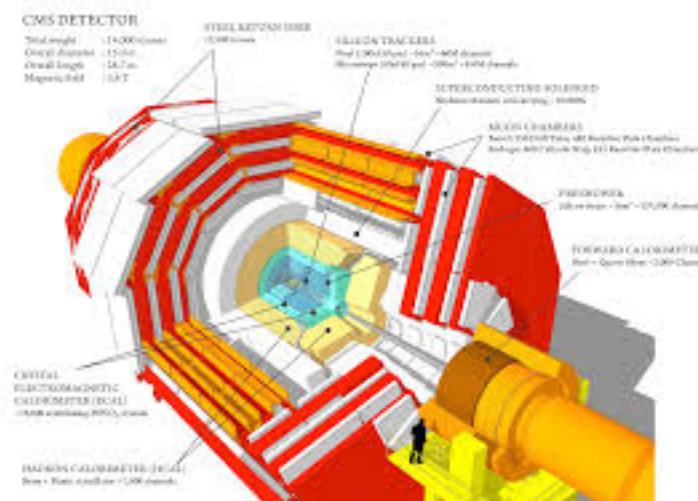
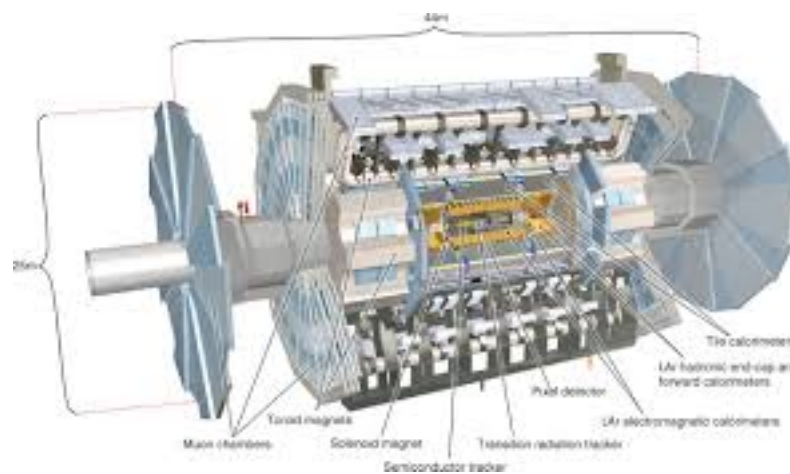
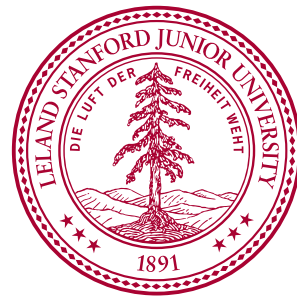


THE CHALLENGE: PART 3

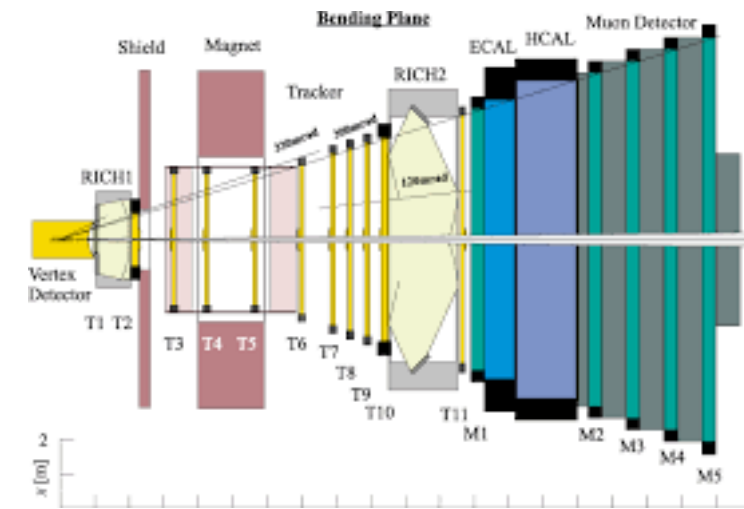


- Each collision produces a lot of data
 - Number of channels: ~100M (ATLAS/CMS); (1M LHCb)
 - Event size: 1 Mb (ATLAS/CMS) ; 100 kB (LHCb)

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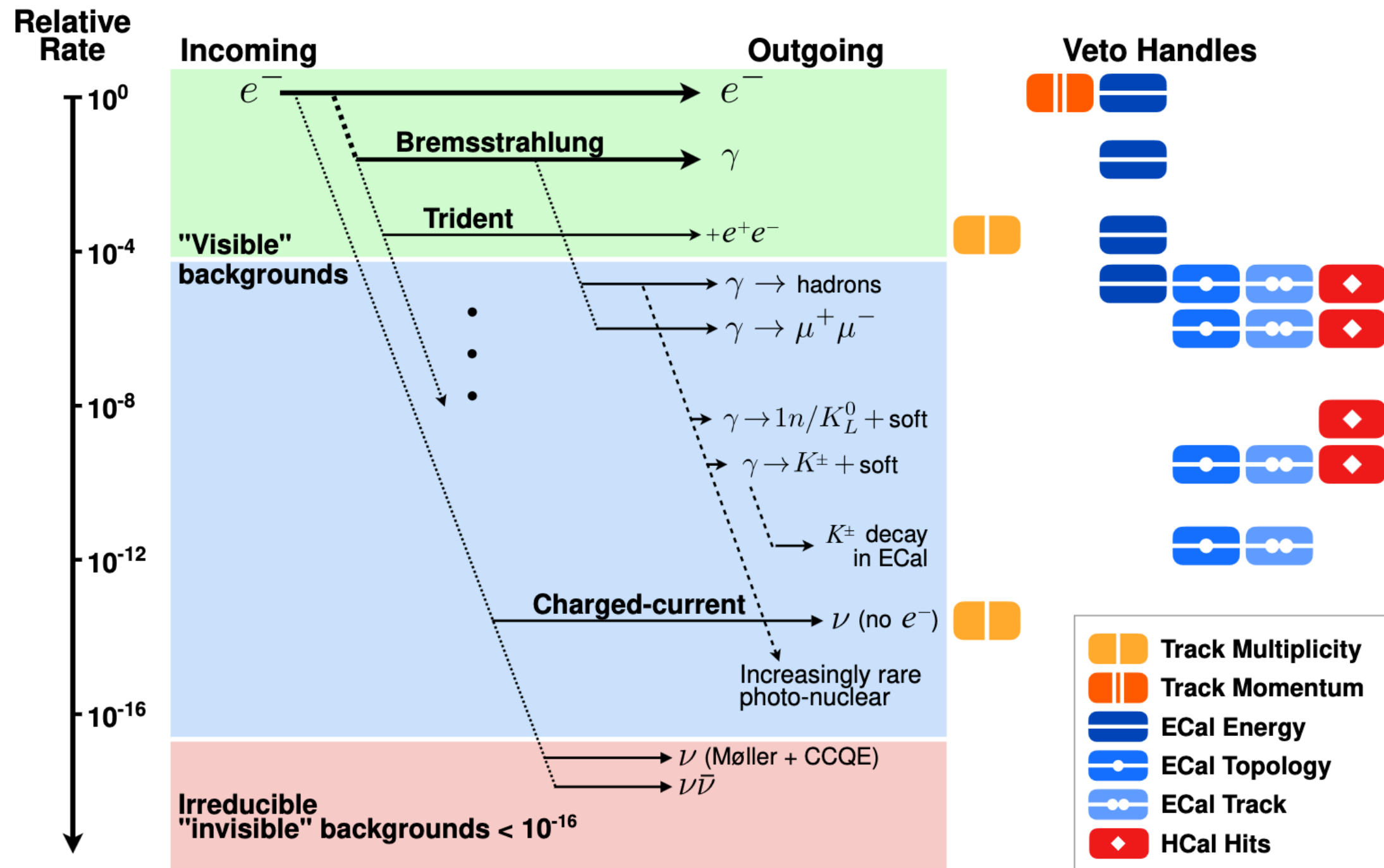
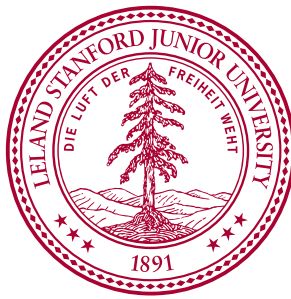


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 - Number of channels: ~100M (ATLAS/CMS); (1M LHCb)
 - Event size: 1 Mb (ATLAS/CMS) ; 100 kB (LHCb)
- Need to get that data to disk for analysis!
 - Can't write all of it — 150000 PB/year!



- 8

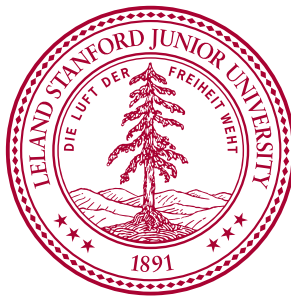
THE CHALLENGE: LMDX



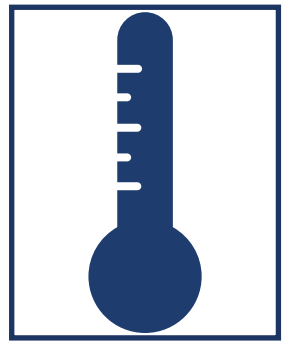
THE BASICS: A TOY EXAMPLE

DRAWS HEAVILY FROM EXAMPLE BY ANDREA NEGRI

FIXED FREQUENCY PROCESSING



Sensor



Trigger

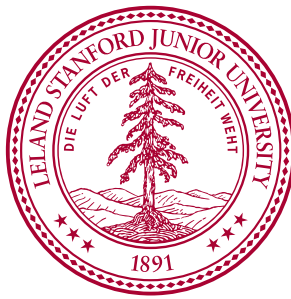


* How is an event defined?

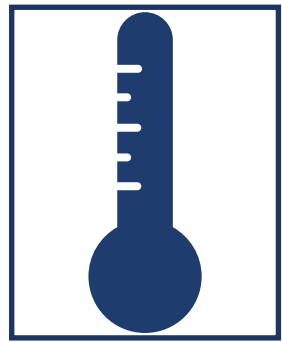
* What is the processing time per event?

* What is the maximum sustainable readout rate?

FIXED FREQUENCY PROCESSING



Sensor

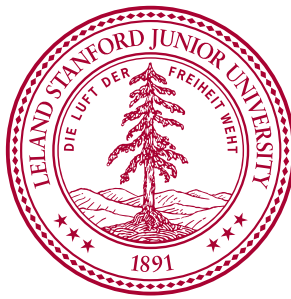


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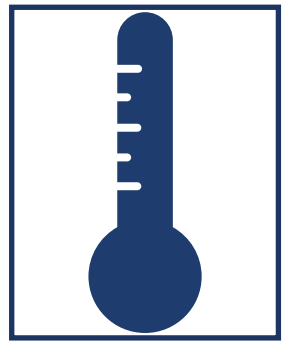


- * How is an event defined?
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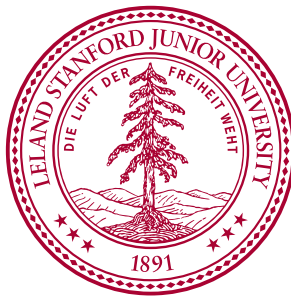


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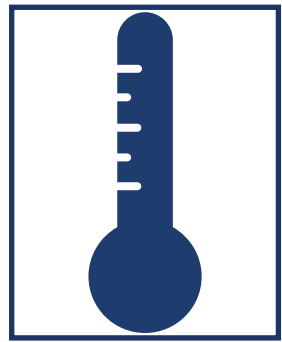


- * How is an event defined?
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- * What is the processing
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- * $\tau = \tau(\text{ADC}) + \tau(\text{proc})$
+ $\tau(\text{storage})$
- * What is the maximum
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FIXED FREQUENCY PROCESSING



Sensor



Trigger



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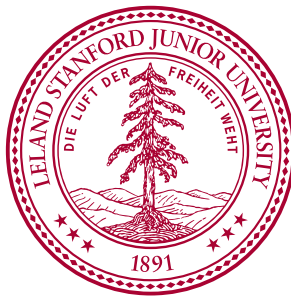
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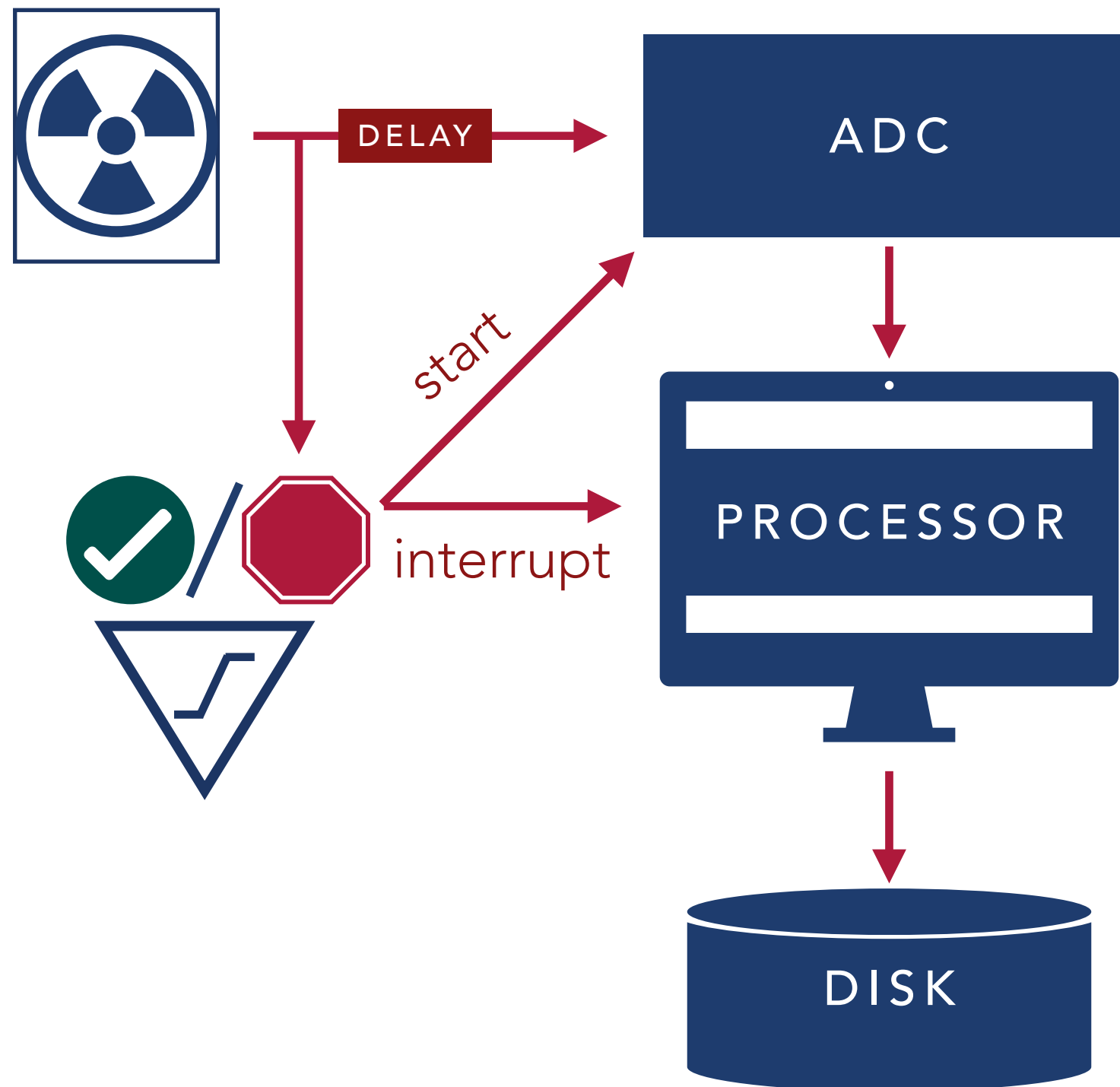
* $R = 1/\tau$

* If $\tau = 1\text{ms}$; $R = 1\text{kHz}$

STOCHASTIC PROCESSING



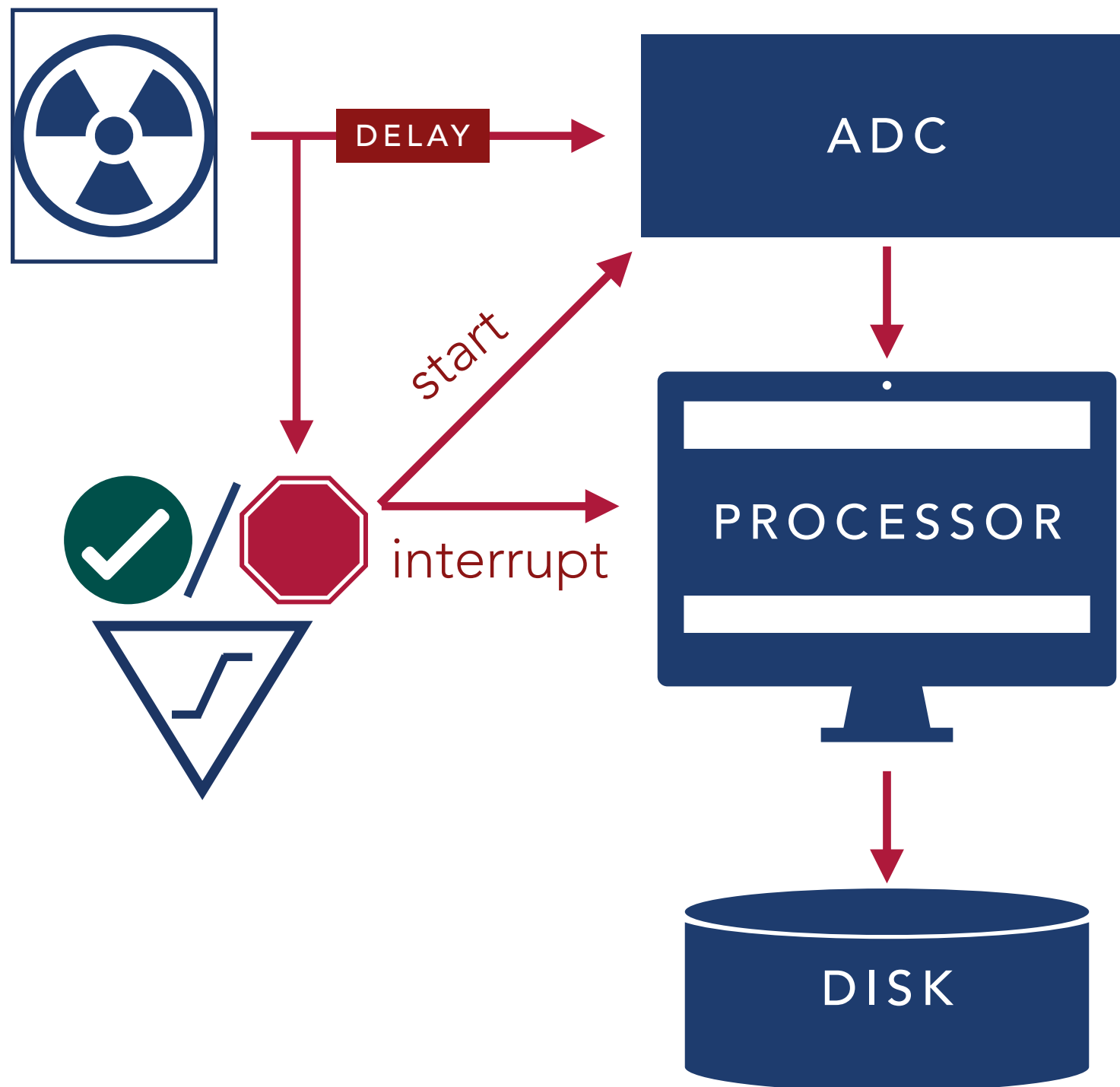
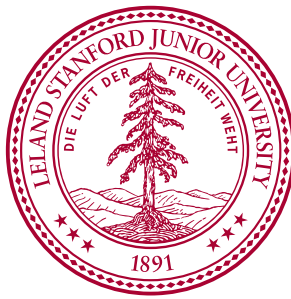
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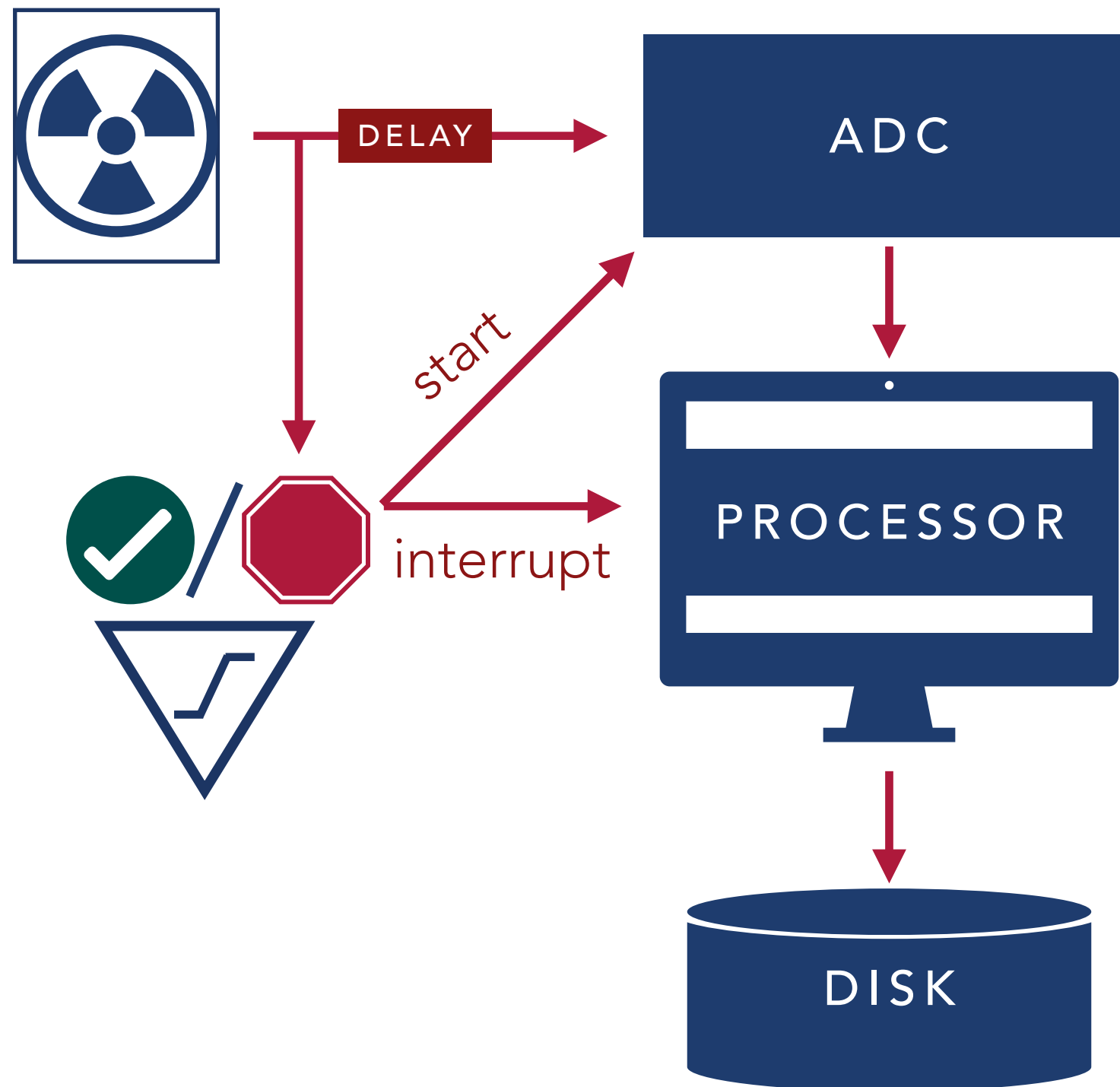
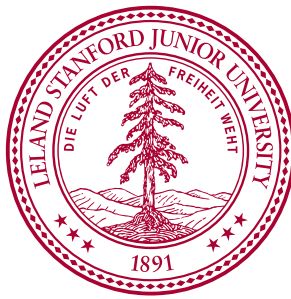
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STOCHASTIC PROCESSING

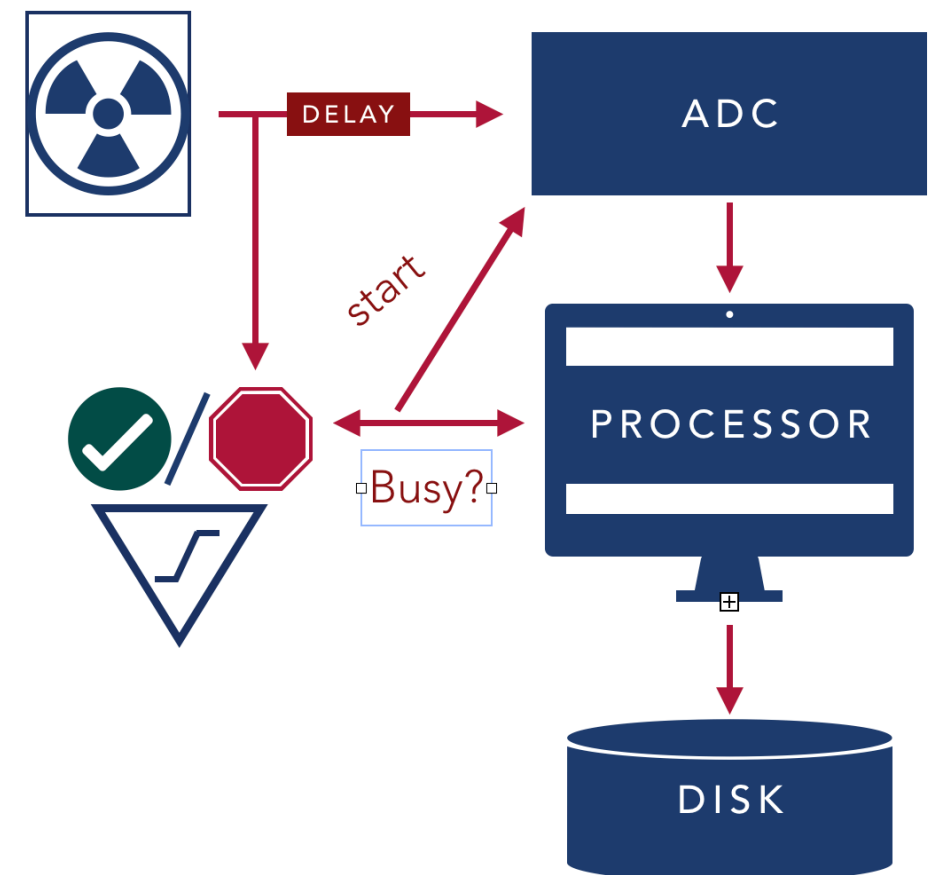
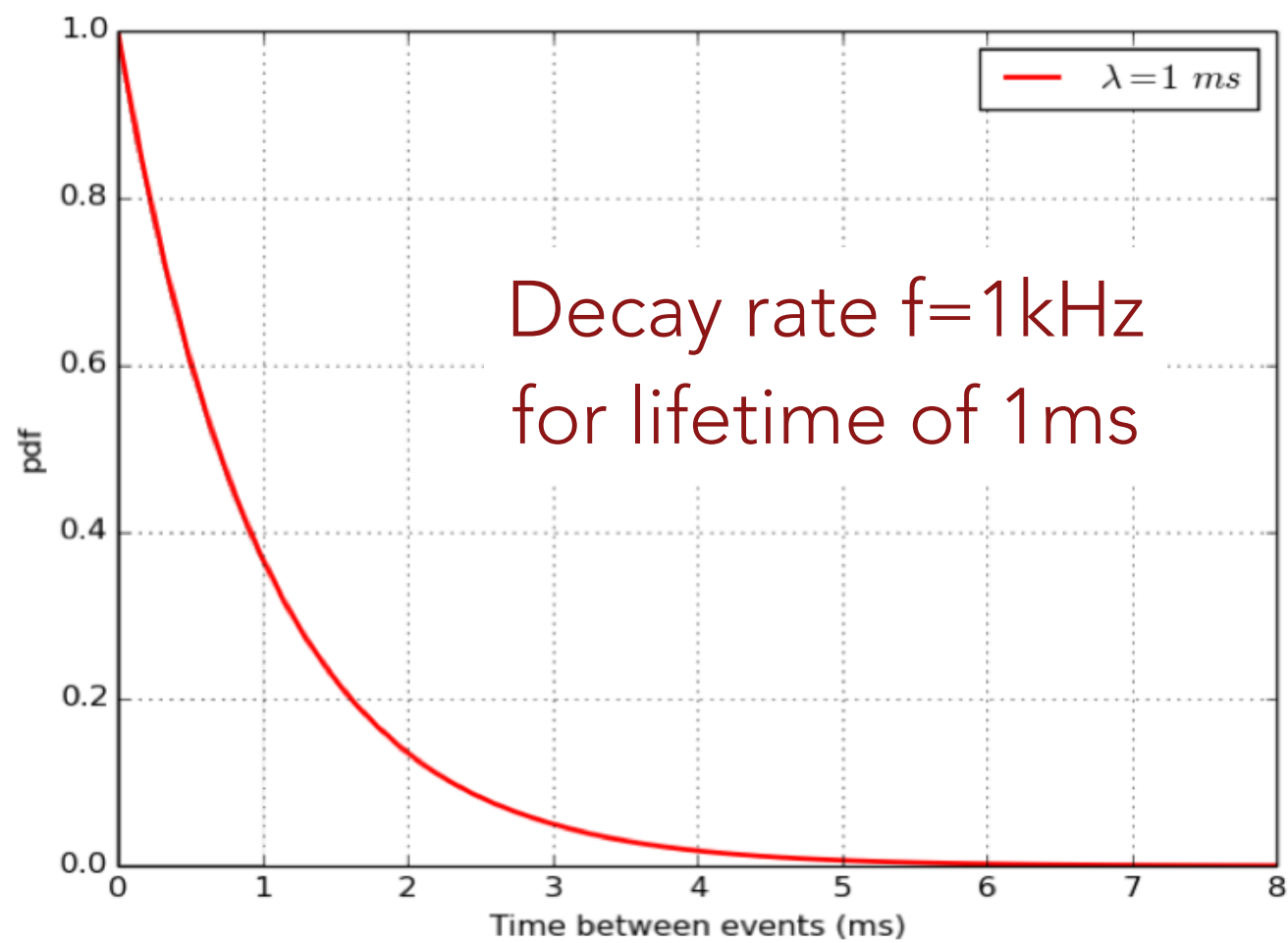


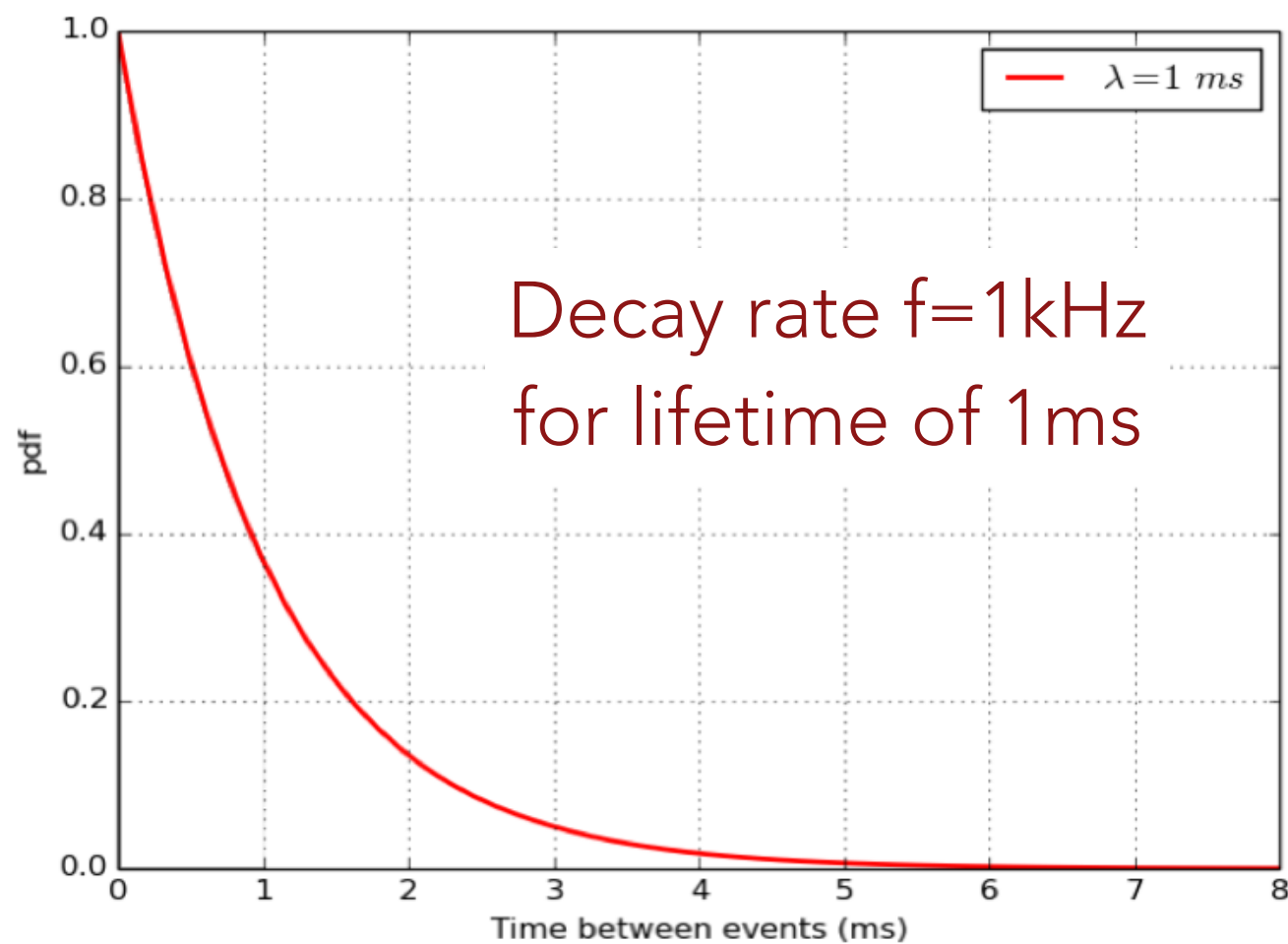
- * How is an event defined?
- * Event = decay = signal passing discriminator threshold
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STOCHASTIC PROCESSING

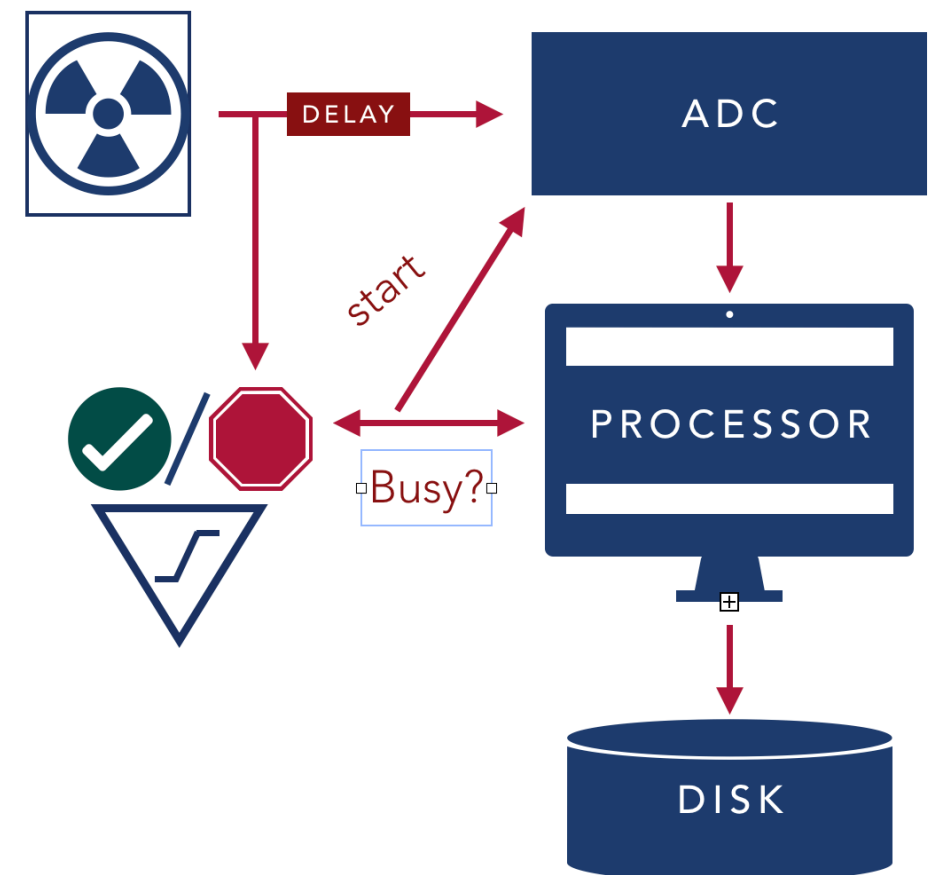


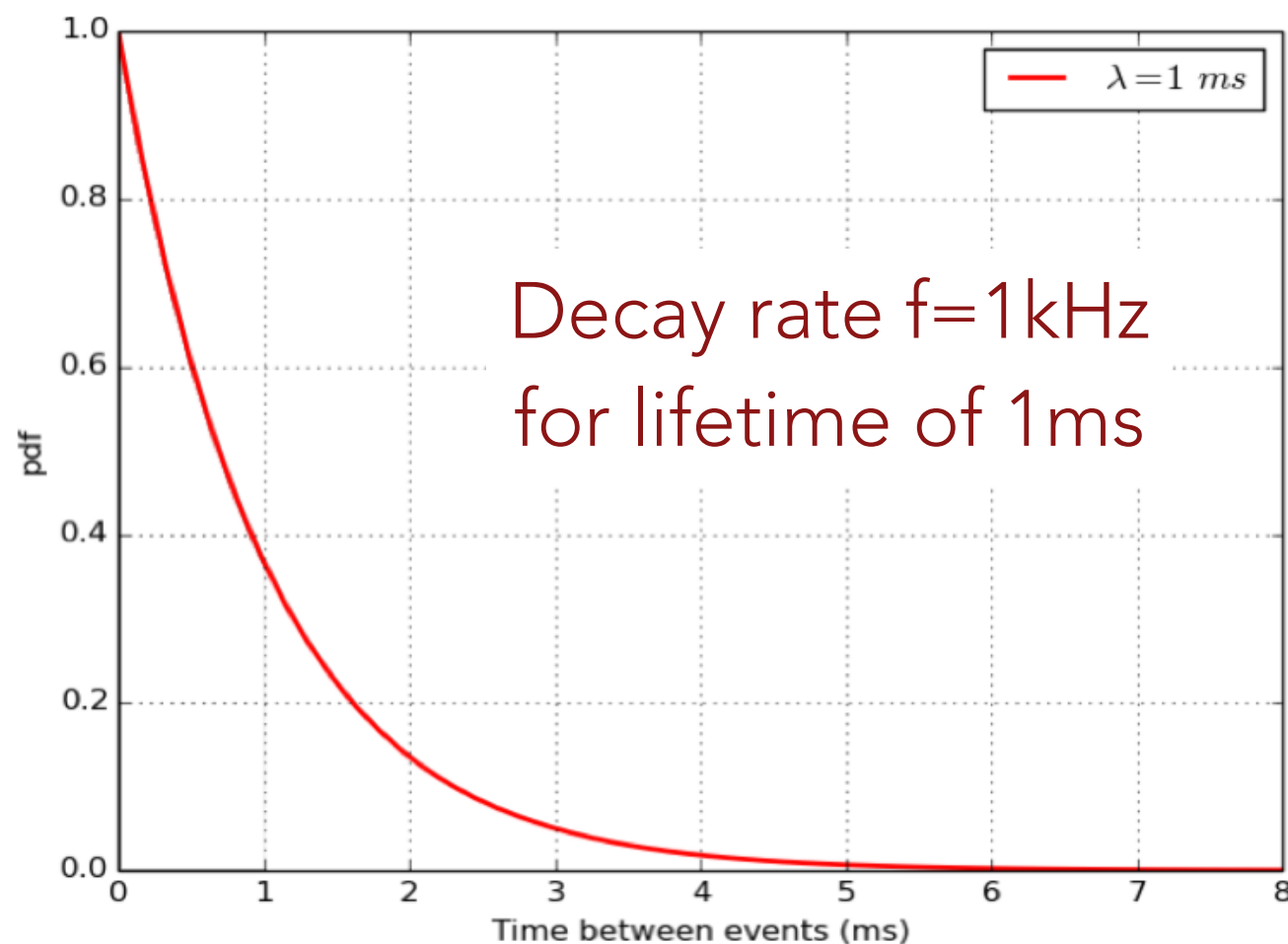
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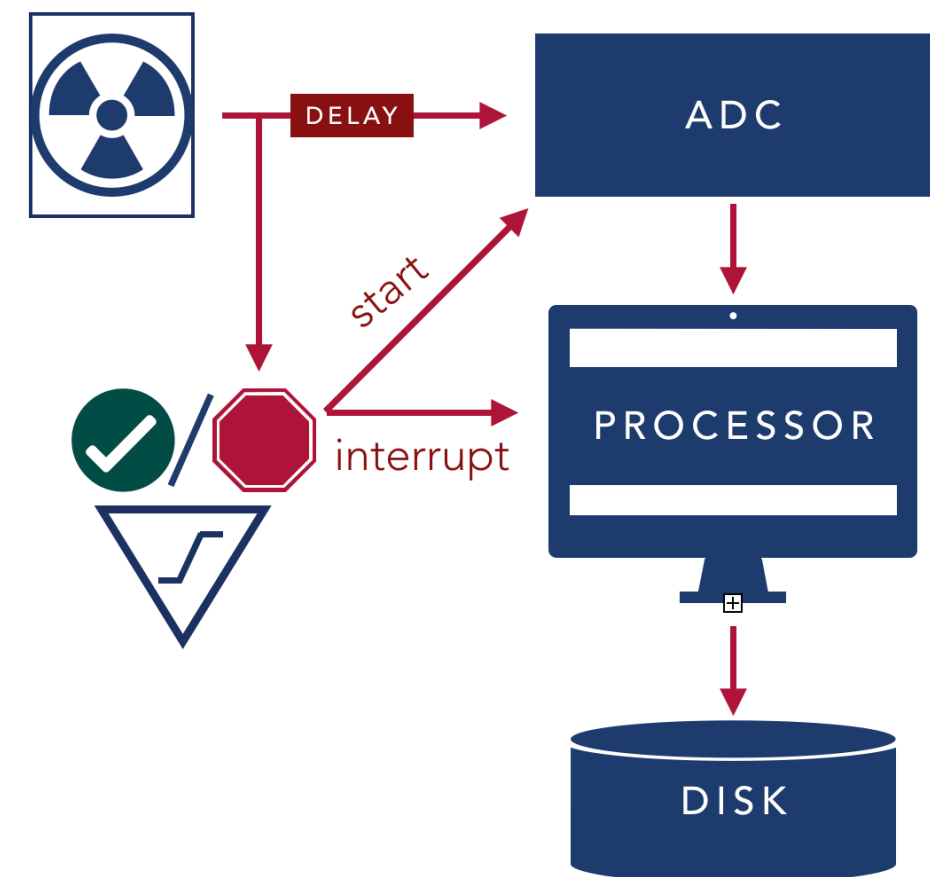
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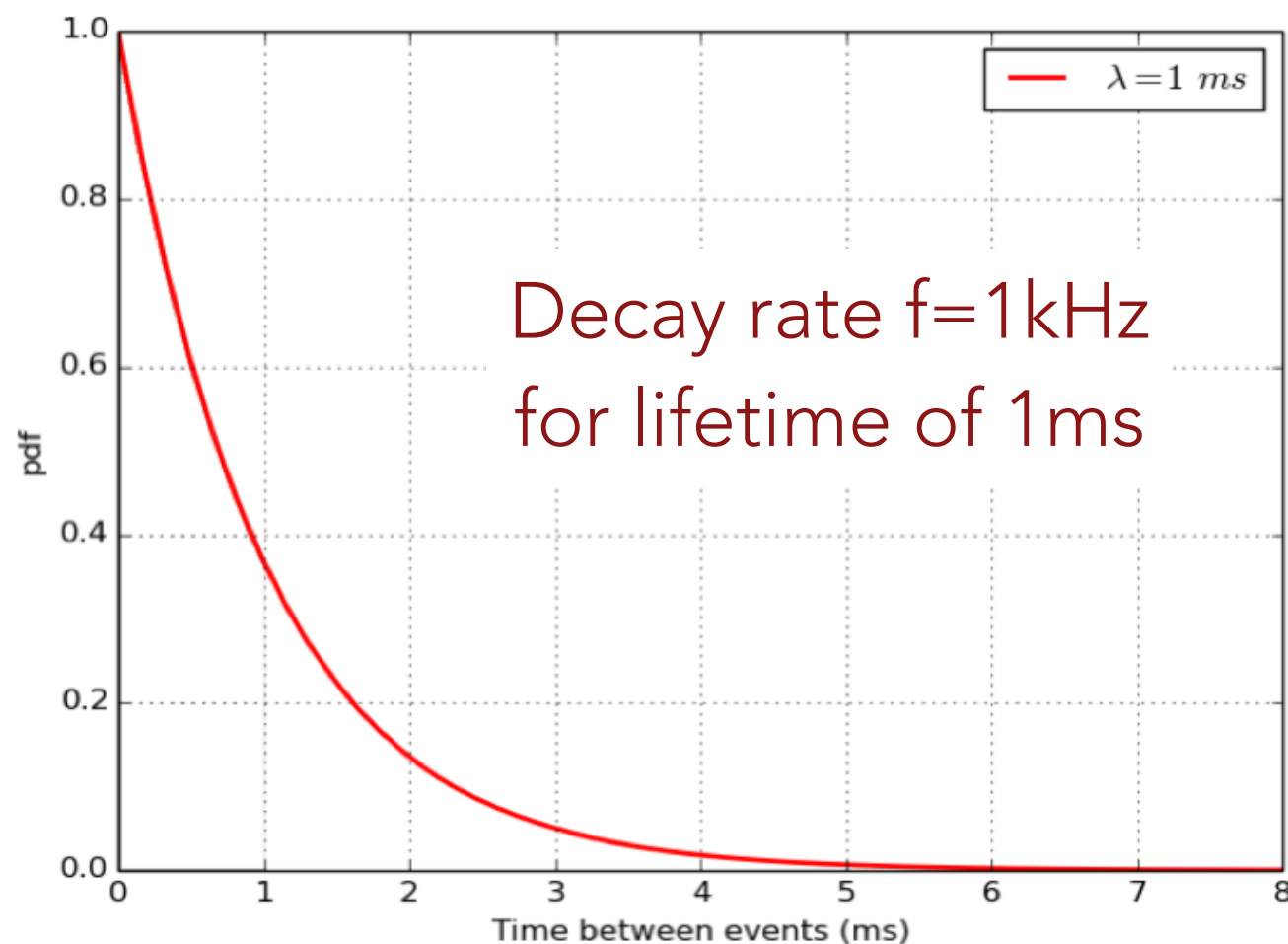




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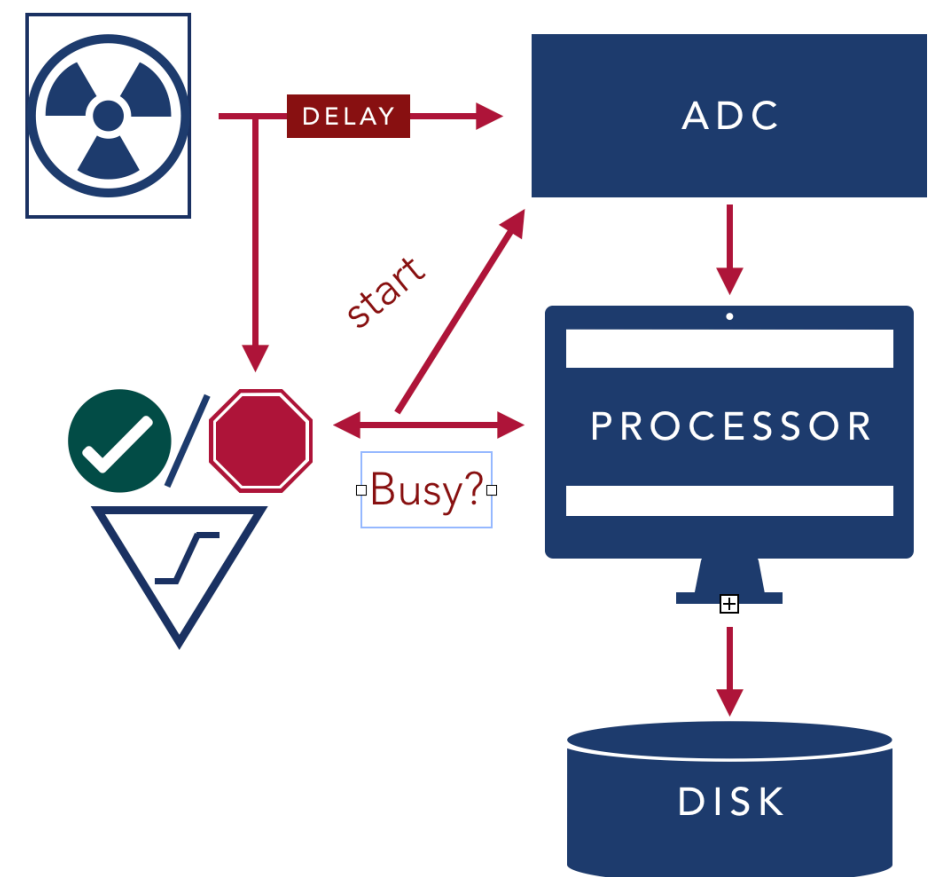
Will keep hitting interrupt unless processing system can tell the trigger that it's BUSY



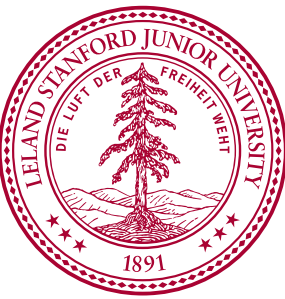


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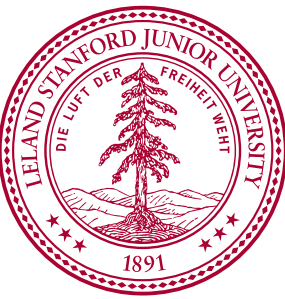


BRIEF PAUSE TO REGROUP

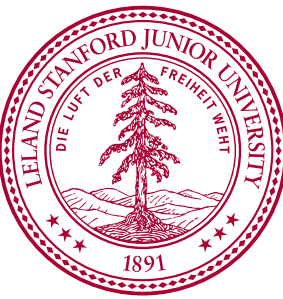


- For stochastic processes, our system needs to be able to:
 - Determine if there is an “event” (trigger)
 - Process and store the data from the event (acquisition)
 - Have a **feedback** mechanism so that the trigger knows if the data processing pipeline is free to process a new event

SO HOW FAST CAN WE PROCESS
EVENTS?

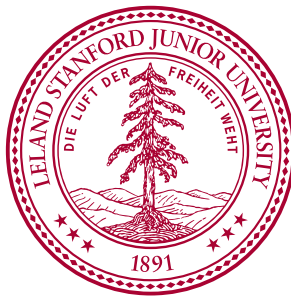


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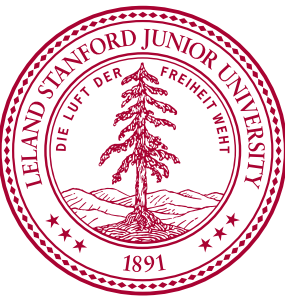
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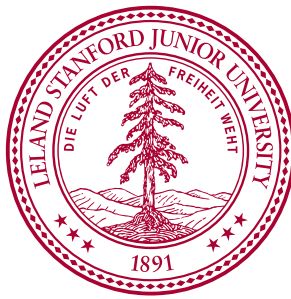
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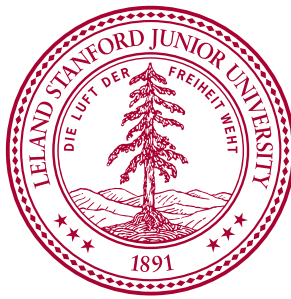
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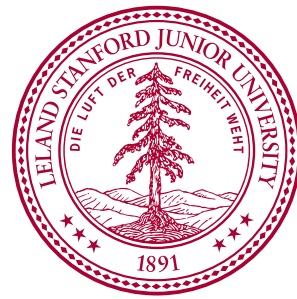
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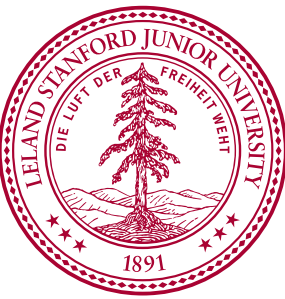
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- What is the probability that our system is busy in terms of τ and v ?
 - $P[\text{busy}] = \tau v$; $P[\text{free}] = 1 - \tau v$
- Therefore, our DAQ rate is $v = f P[\text{free}] = f (1 - \tau v)$; $v = f/(1 + f\tau)$

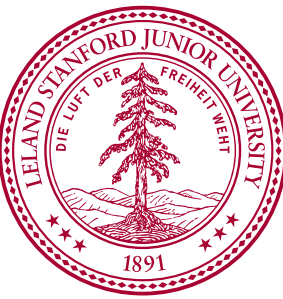
RATES AND EFFICIENCIES



- What can we say about our DAQ rate relative to our physics process rate?
- What can we say about our efficiency to record events?
- So if $f = 1/\tau = 1 \text{ kHz}$; then $v = 500 \text{ Hz}$;
 $\epsilon = 50\%$
- How can we maximize our efficiency?

τ

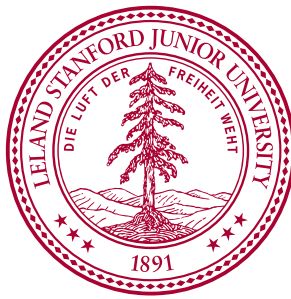
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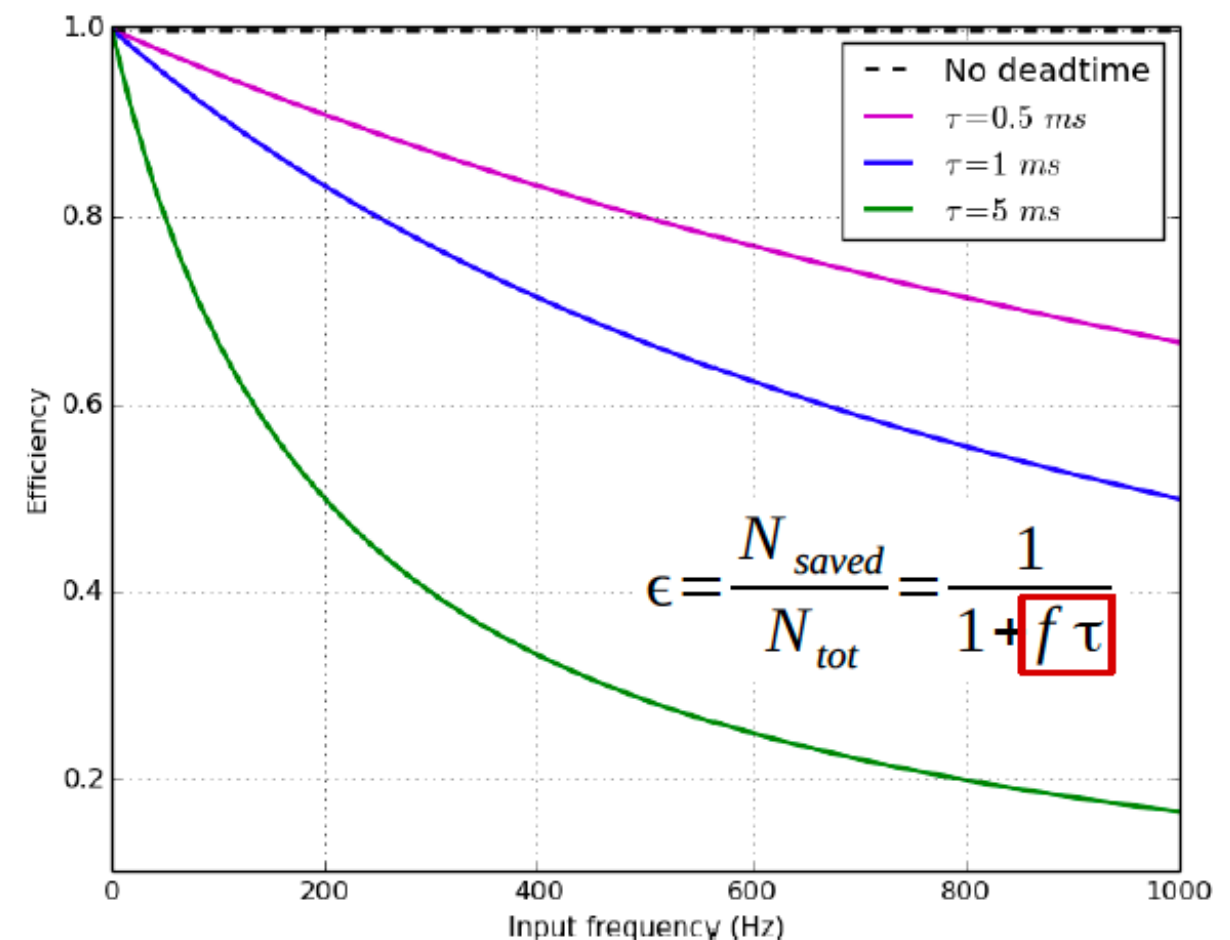
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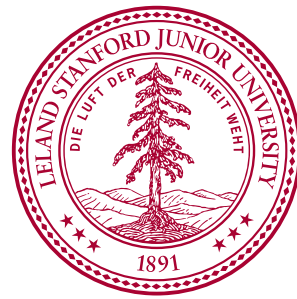


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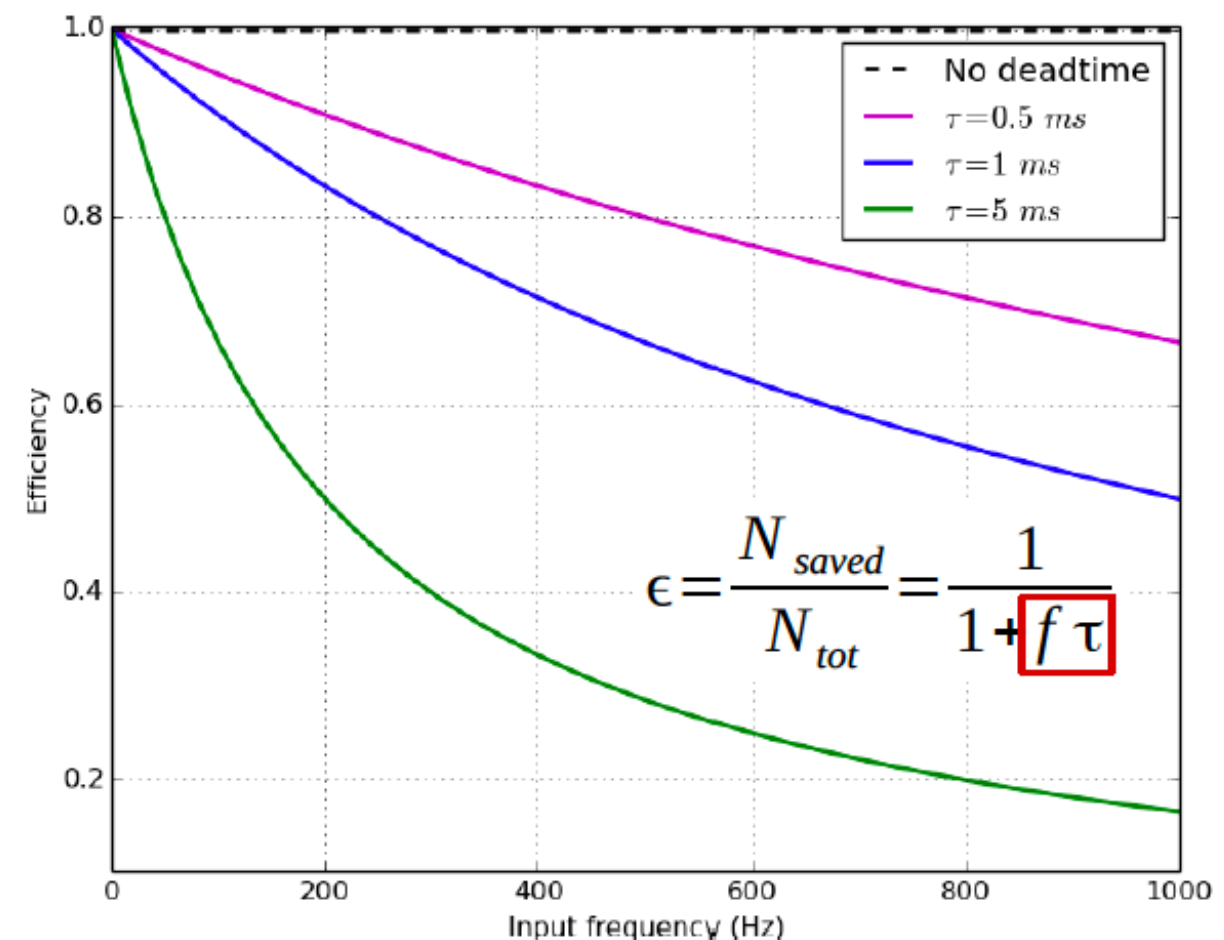


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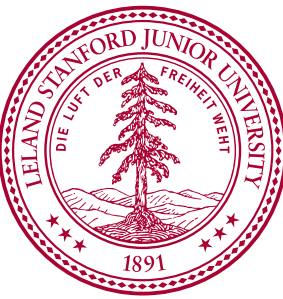
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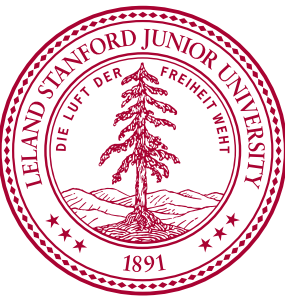
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 - We need $f\tau \ll 1$
 - For $\epsilon = 99\%$ and $f = 1$ kHz we need $\tau = 0.01$ ms!



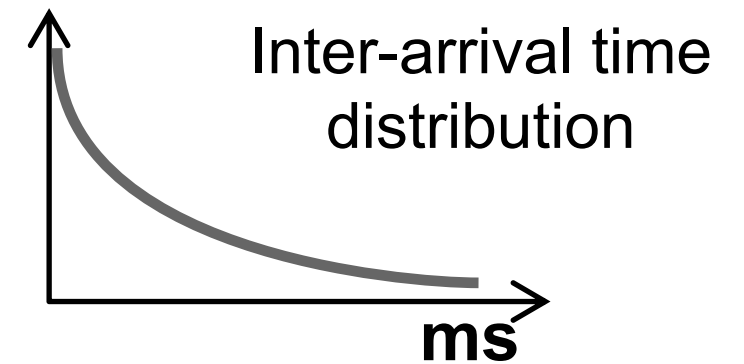
HOW CAN WE MAKE OUR SYSTEM MORE EFFICIENT??



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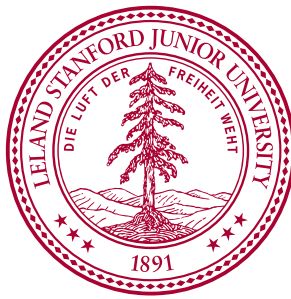


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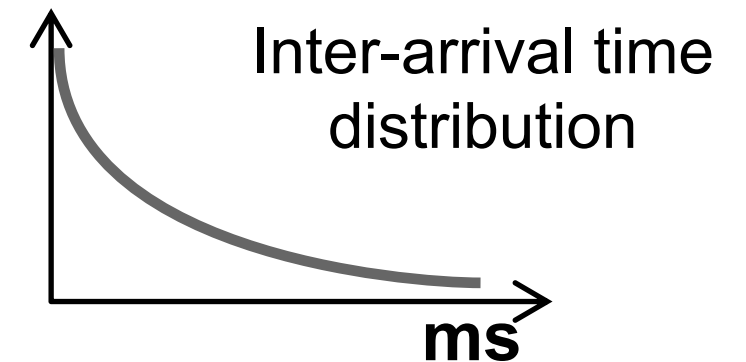


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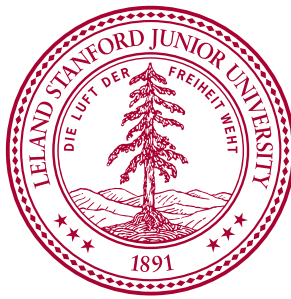


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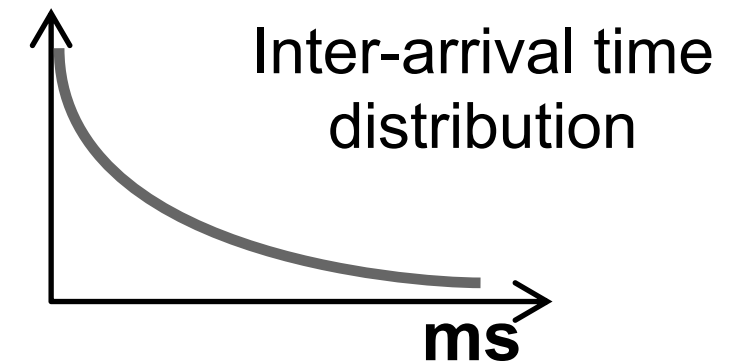


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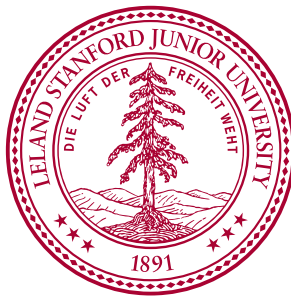


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- This is called **de-randomization** and we achieve it by buffering the data (having a holding queue where we can slot it up to be processed)

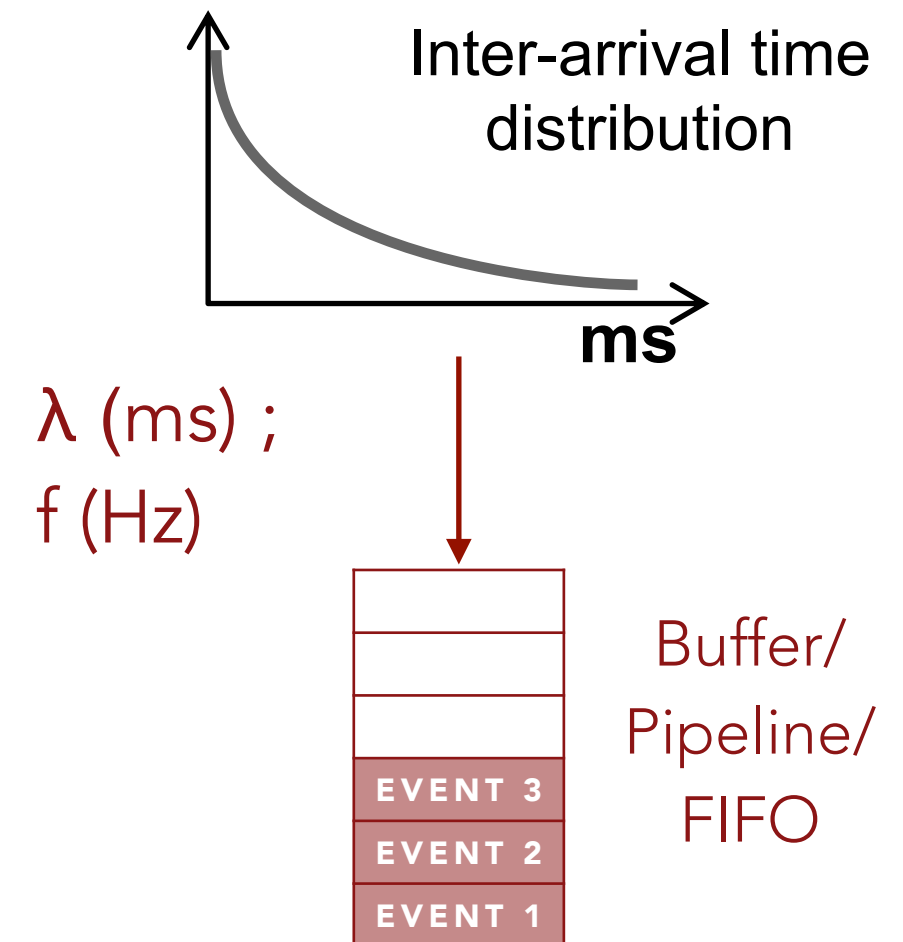


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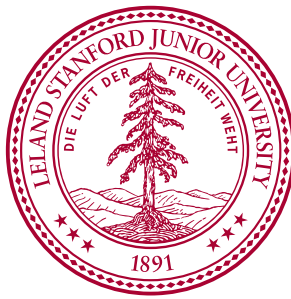
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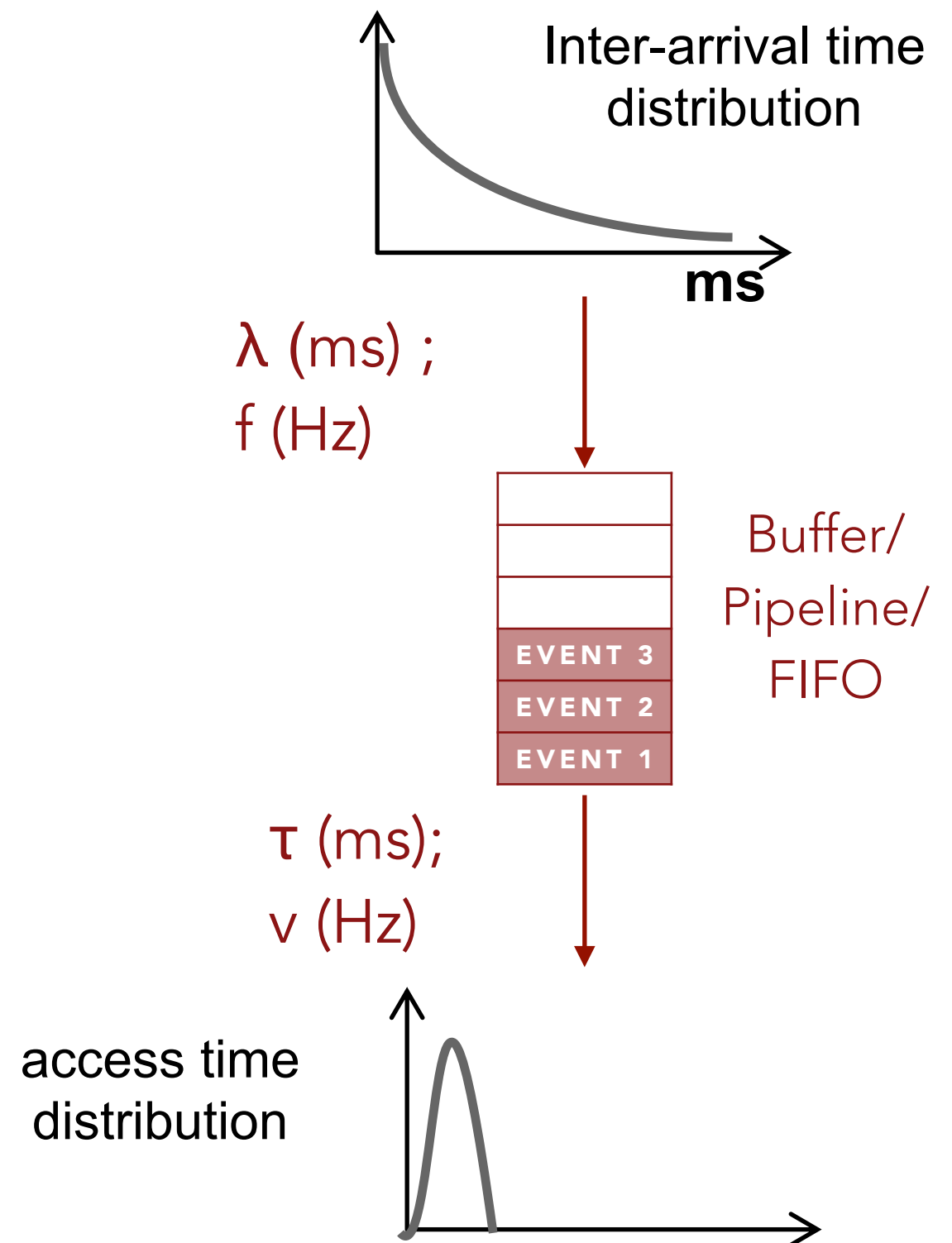
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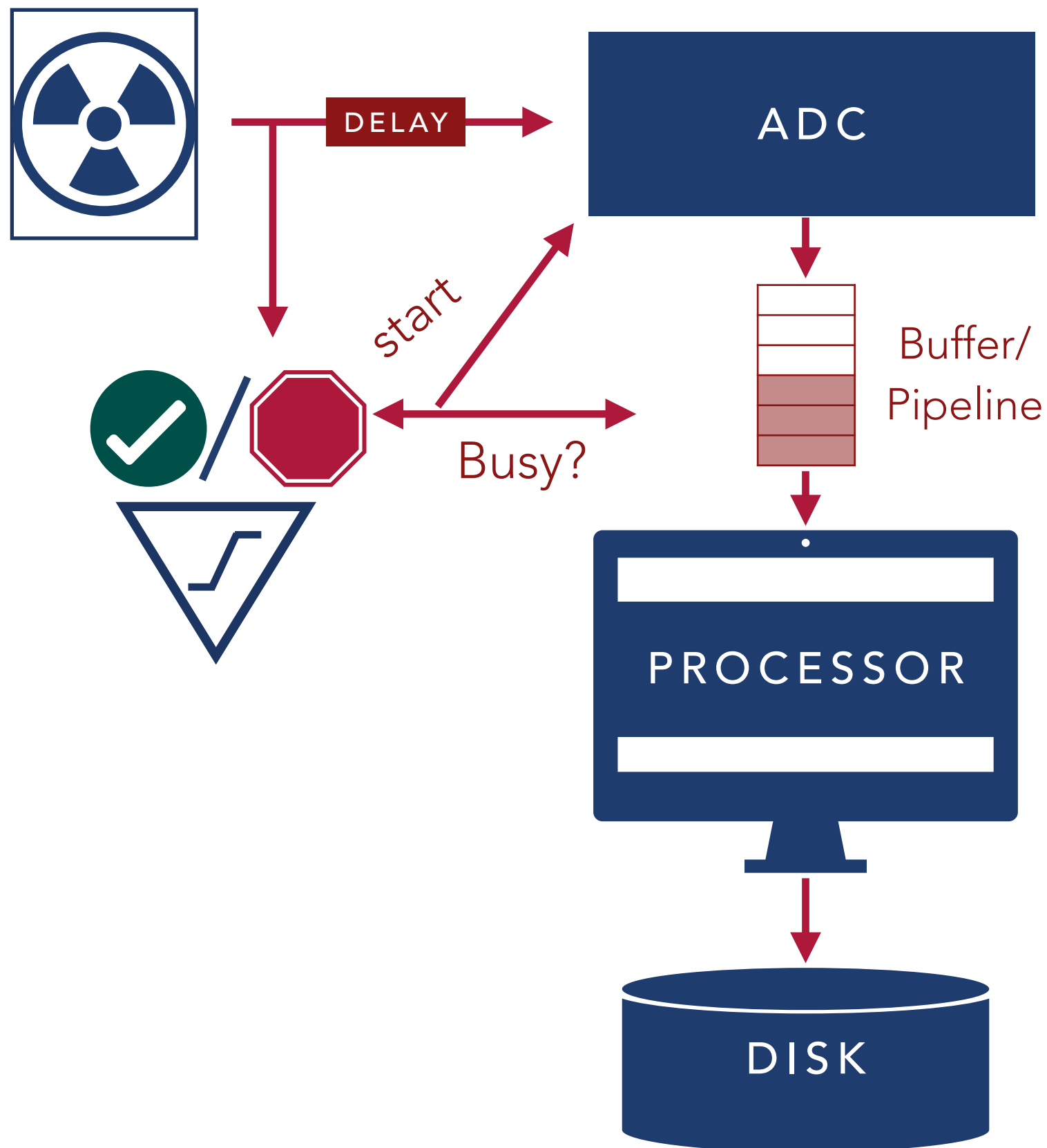
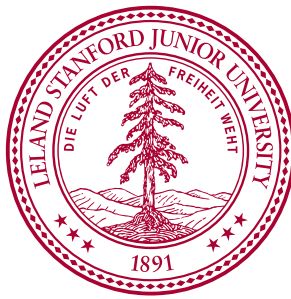
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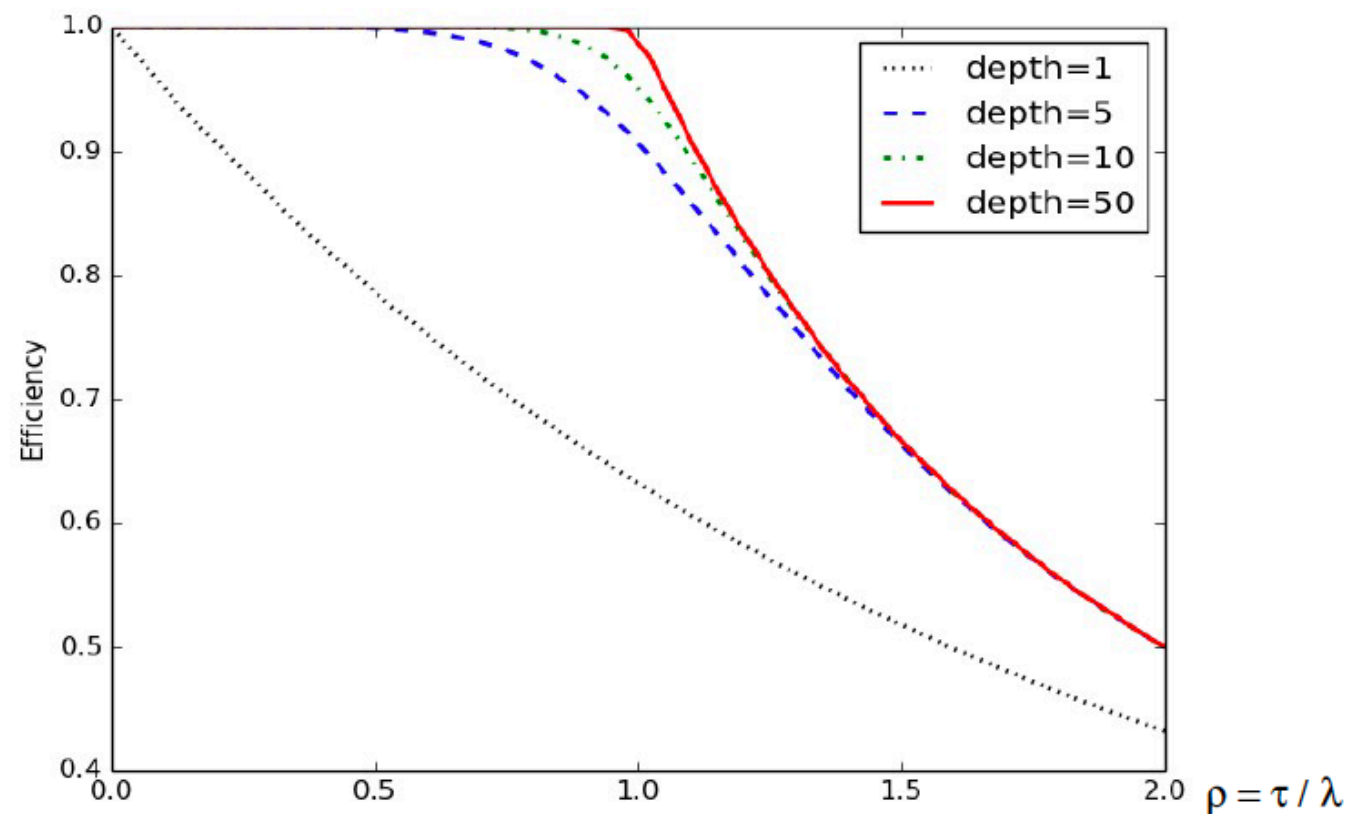
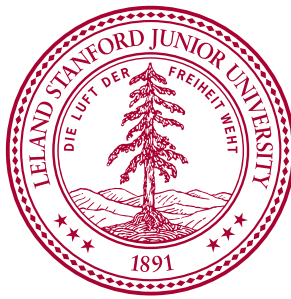


DE-RANDOMIZING



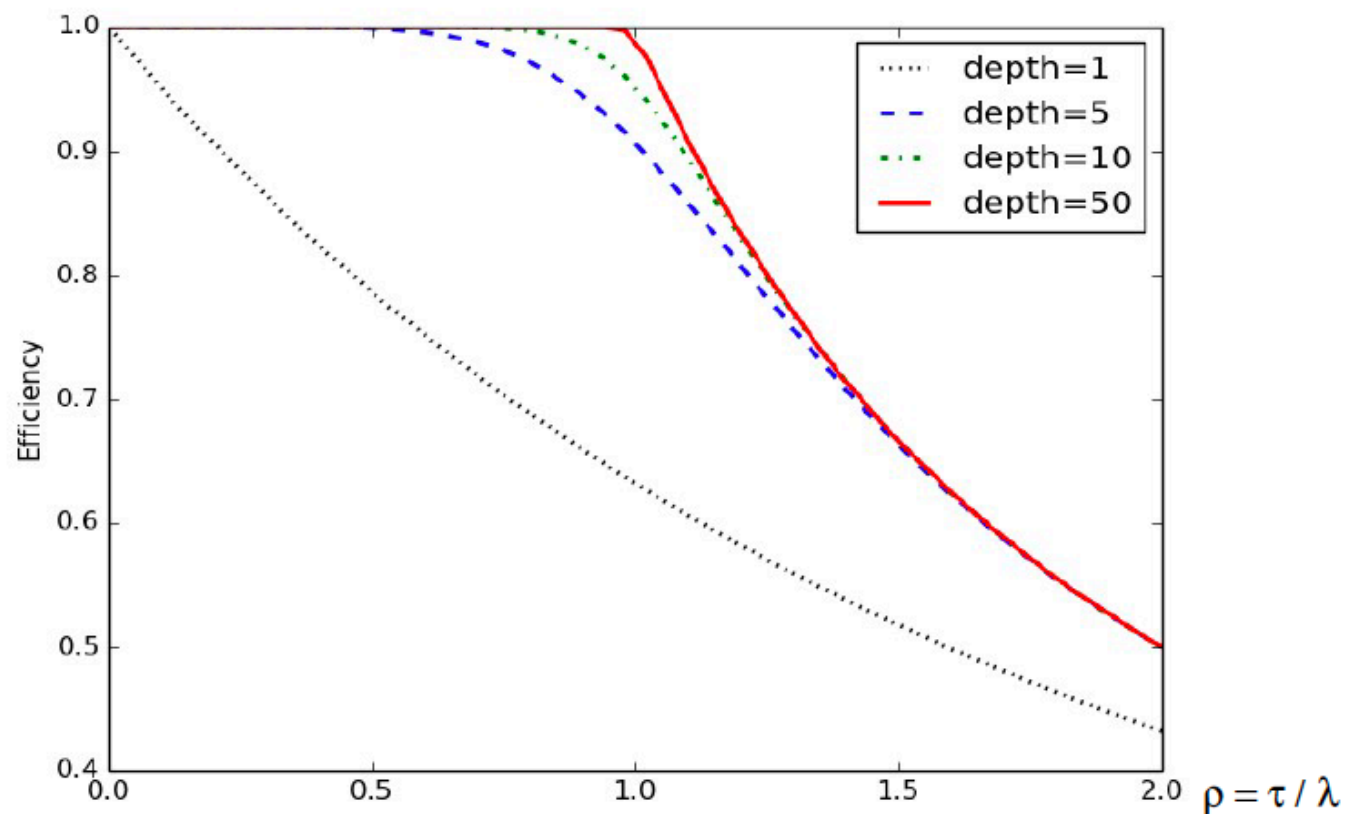
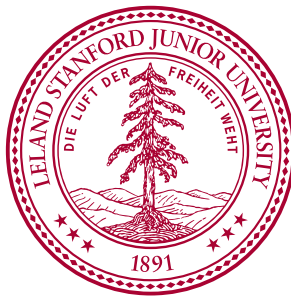
- * Busy is now defined by if the buffer is full or not.
- * Processor pulls data from the buffer at fixed rate, separating the event receiving and data processing steps

QUEUEING THEORY



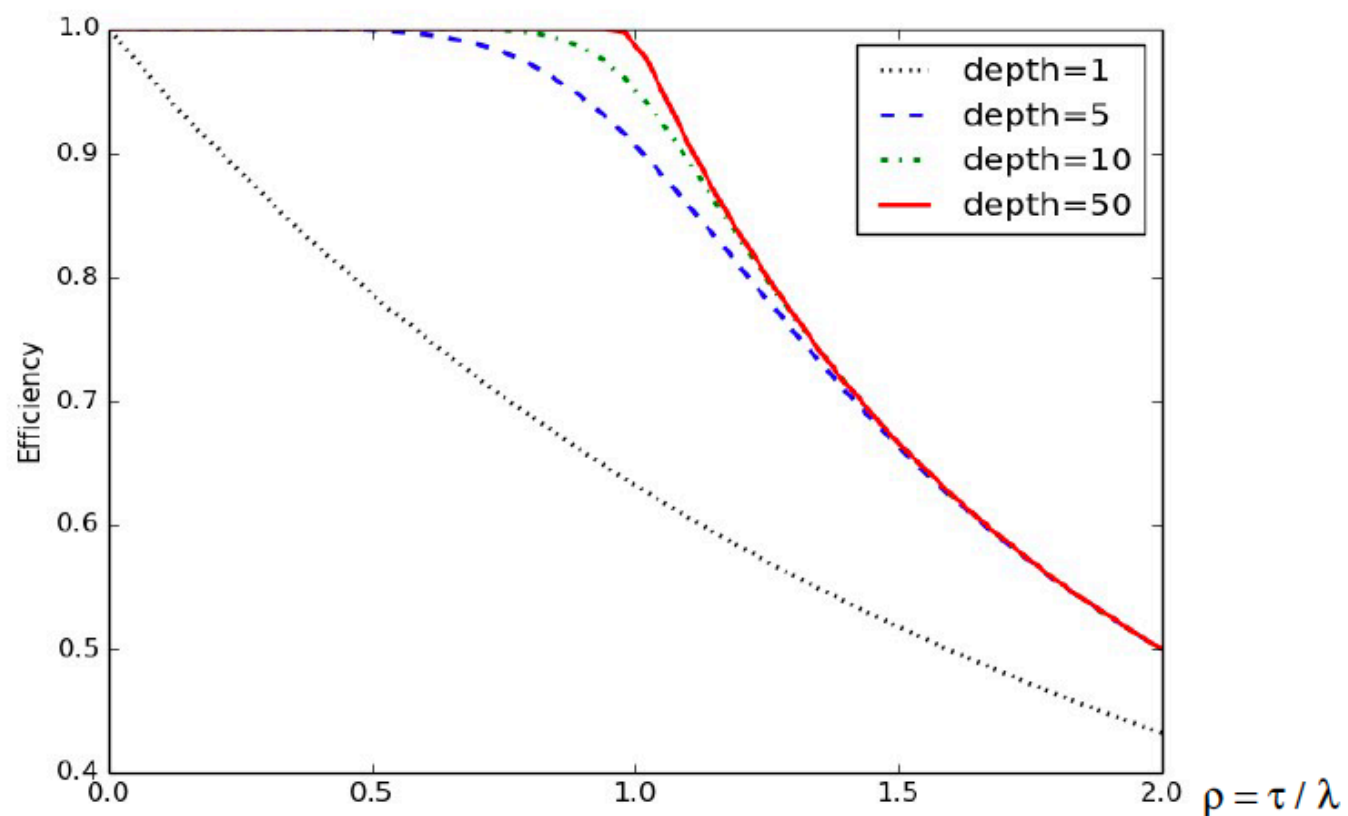
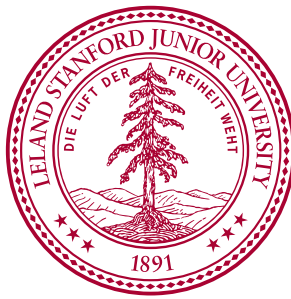
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- Qualitatively describe the system for:
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QUEUEING THEORY



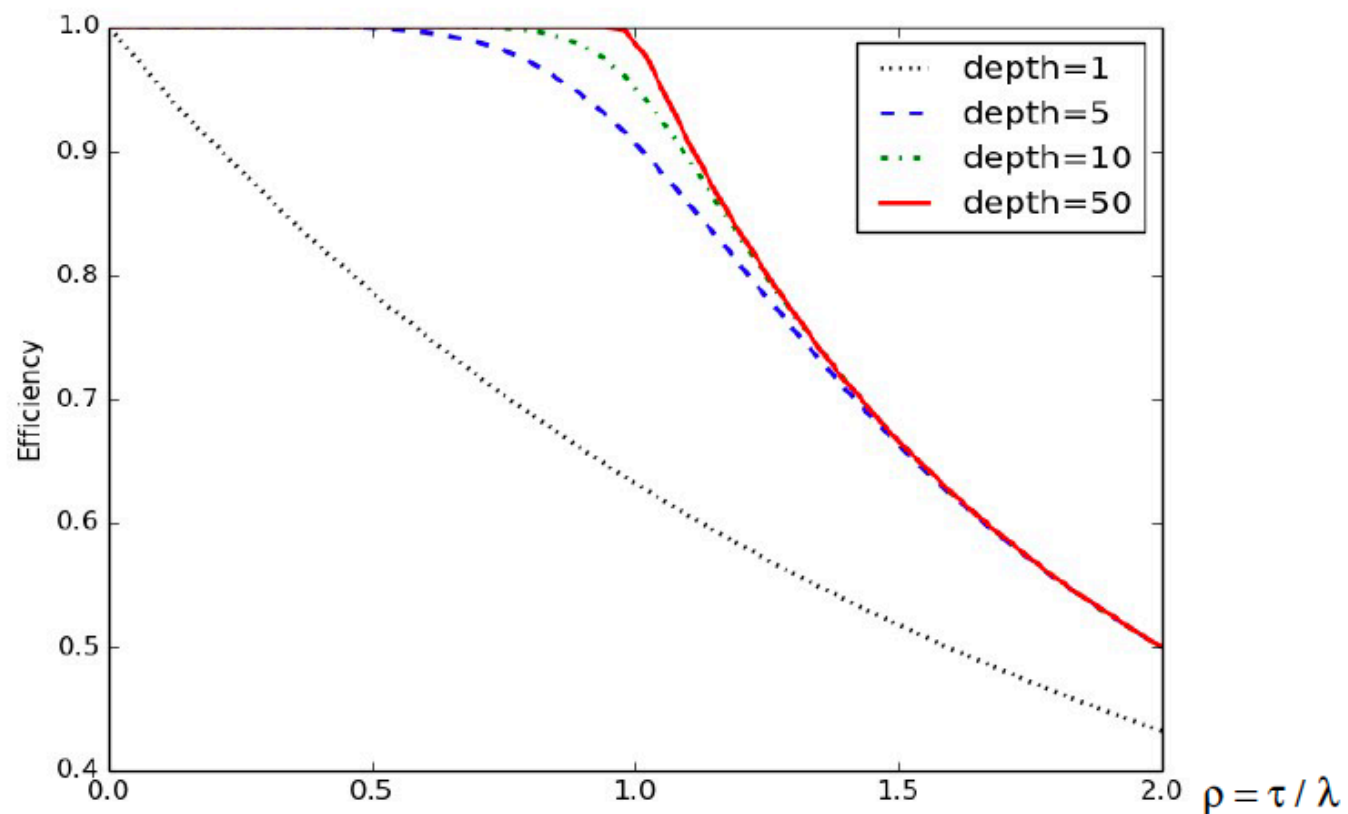
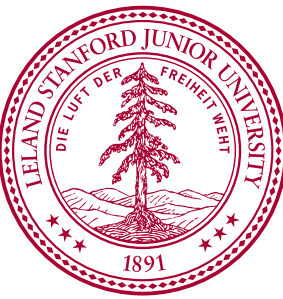
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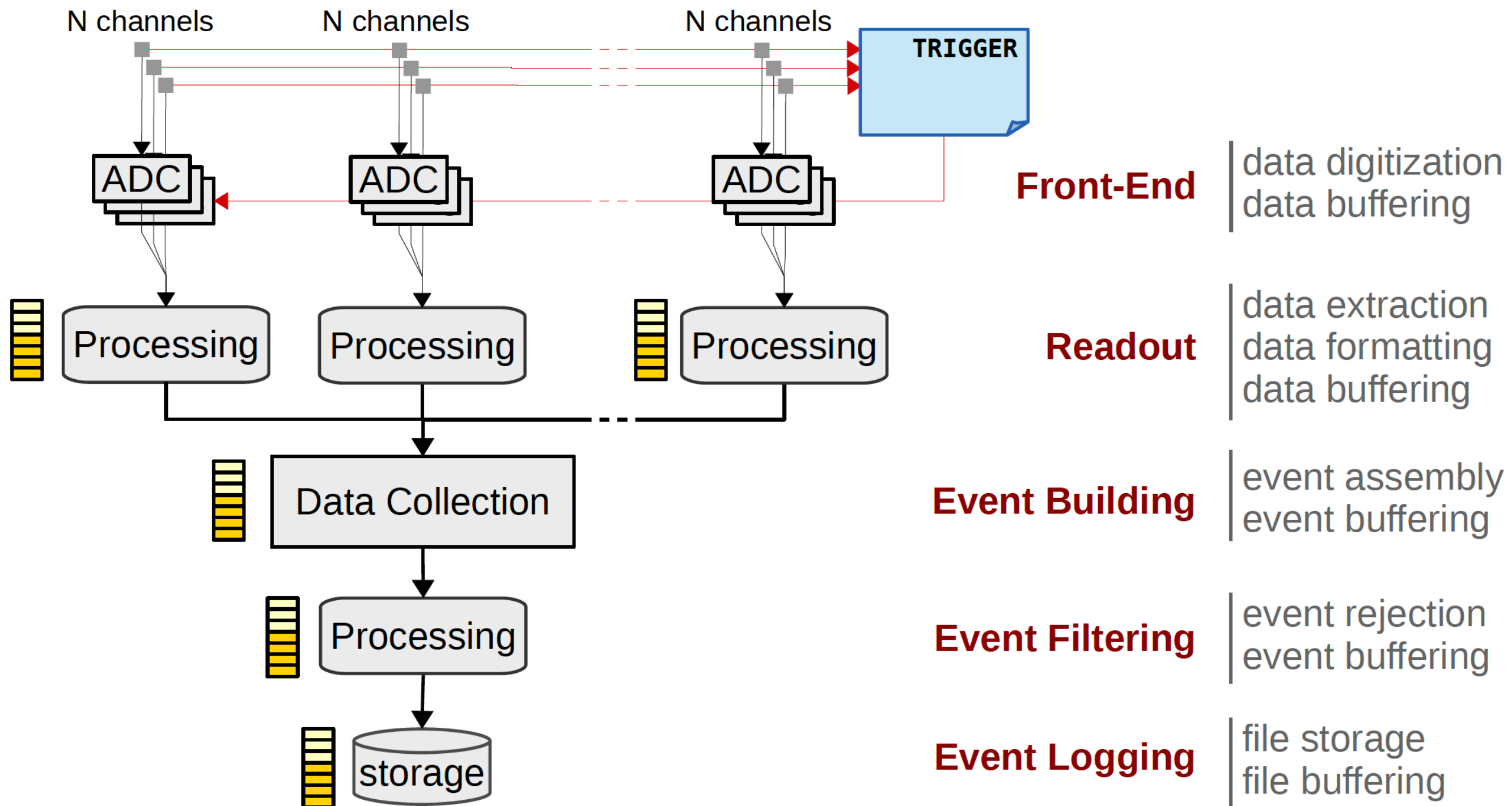
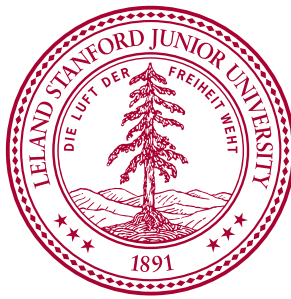
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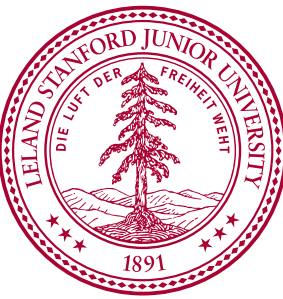


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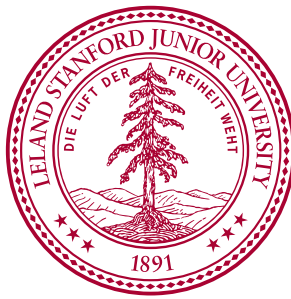
GENERALIZING TO MULTI-CHANNEL SYSTEM



THAT TOY WAS CUTE, BUT WHAT ABOUT
REAL EXPERIMENTS LIKE AT THE LHC?

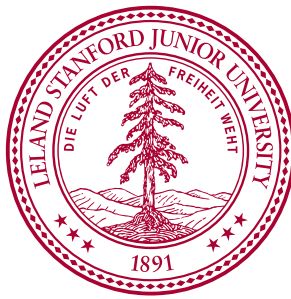


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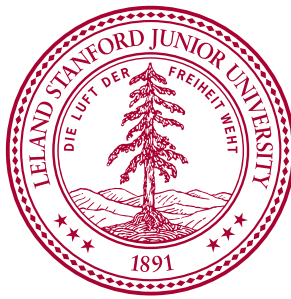
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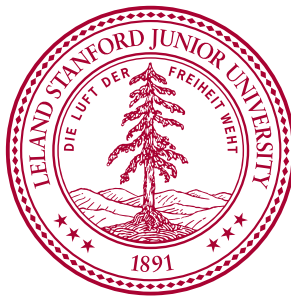
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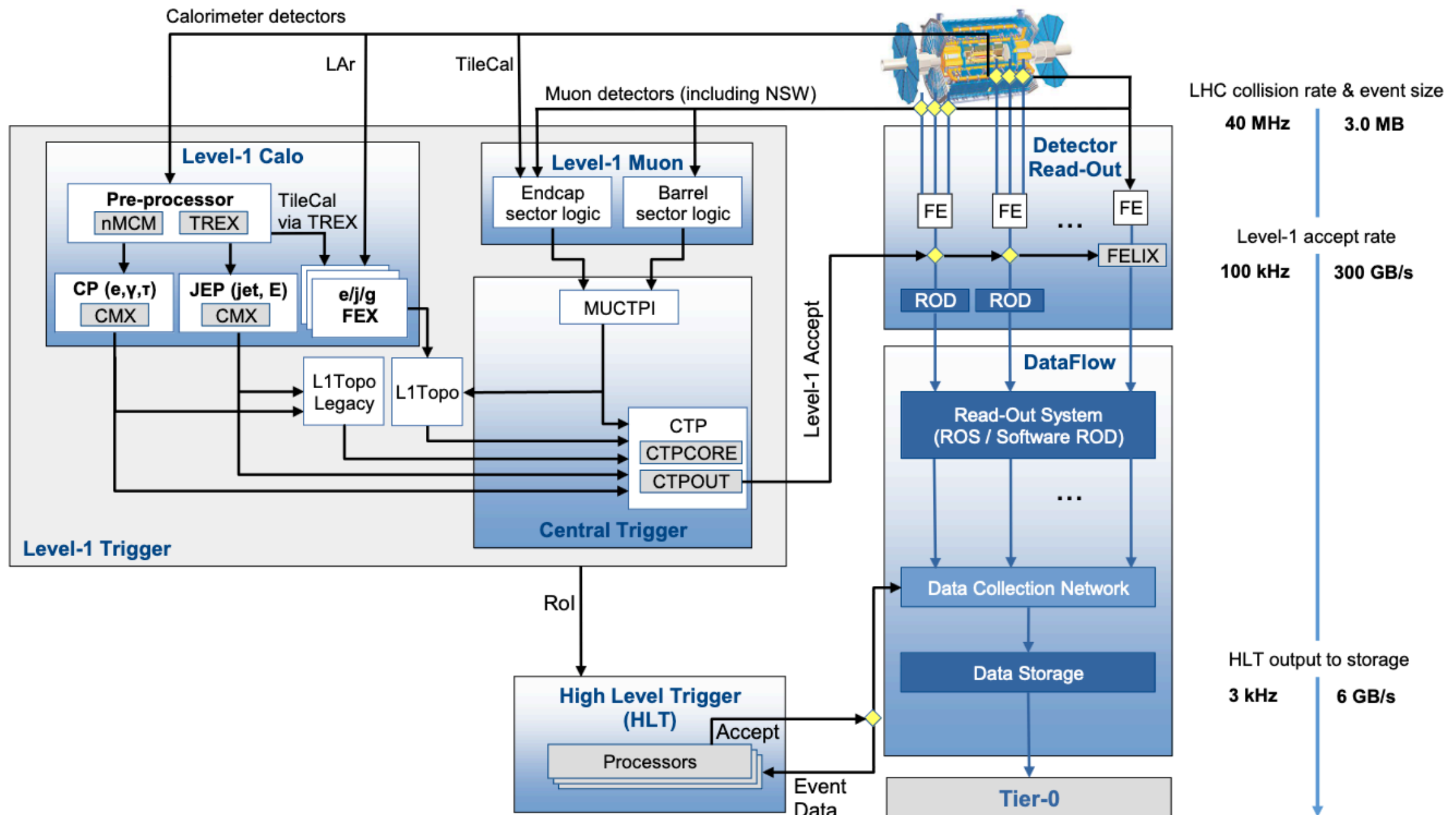
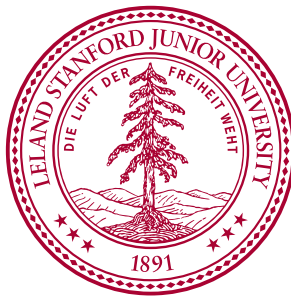
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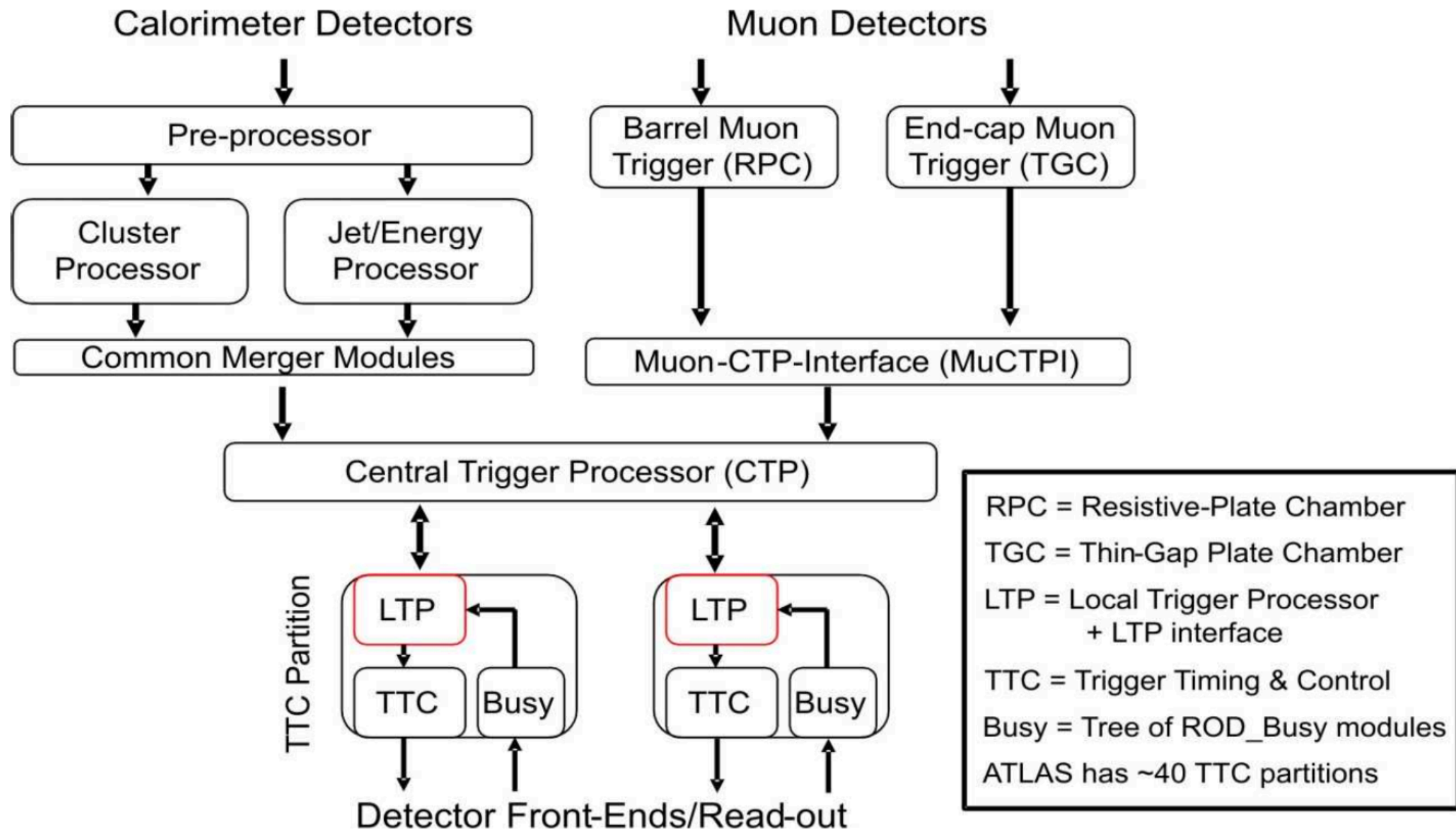
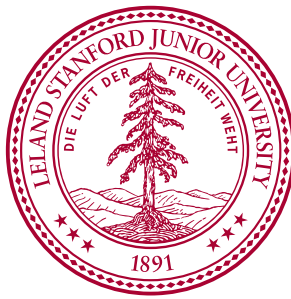


- What are the similarities & differences?
 - Fixed frequency of LHC collisions means you don't need to have continuous readout
 - But events are still random —> de-randomization is needed!
- Remainder of today and tomorrow's lectures are going to explain how these basic concepts are applied to the LHC trigger & data acquisition problem now and in the the future

ATLAS RUN II TDAQ SYSTEM



ATLAS LEVEL 1 TRIGGER SYSTEM



[Fig. Ref](#)

ATLAS LEVEL 1 TRIGGER SYSTEM

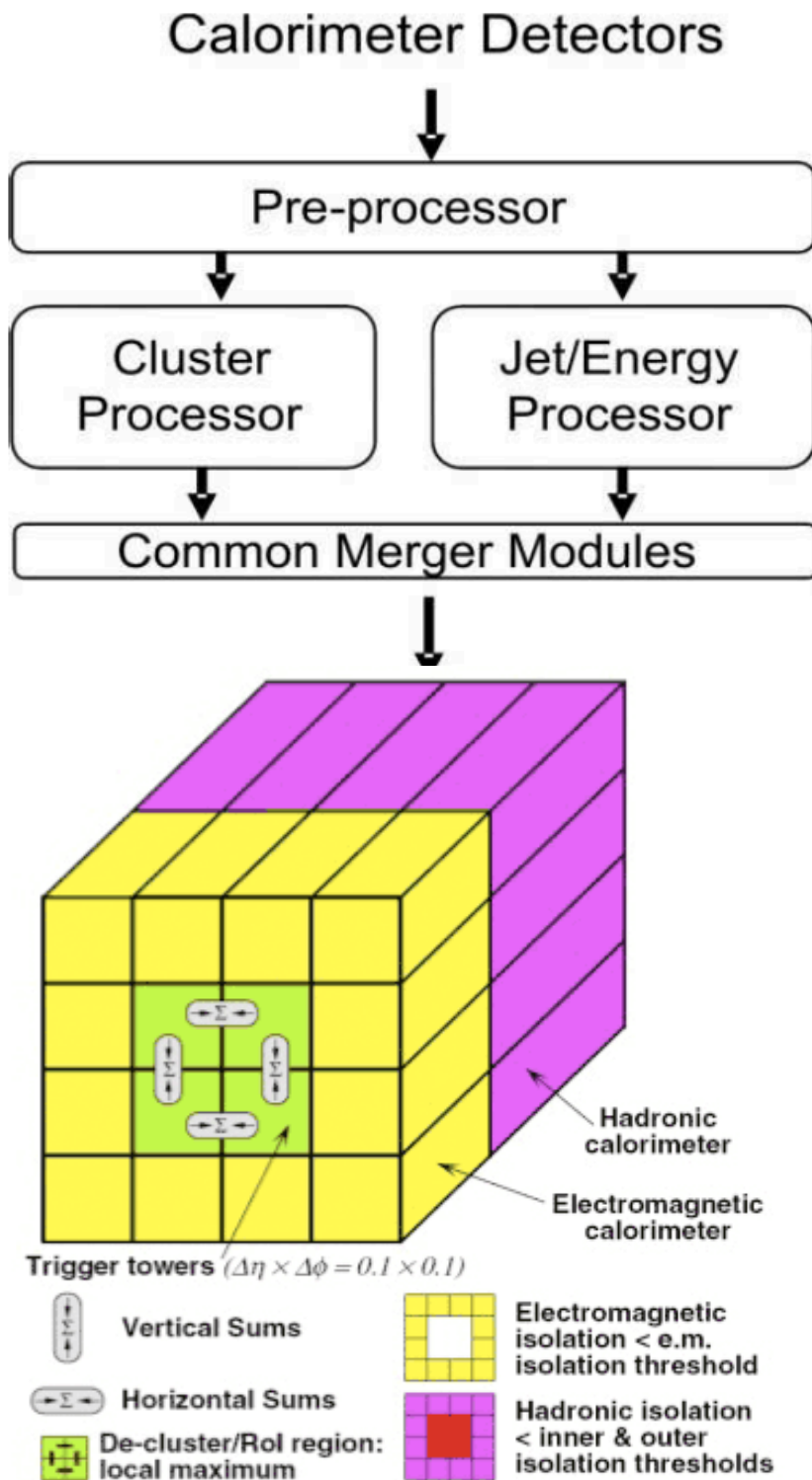
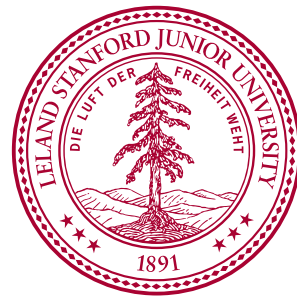
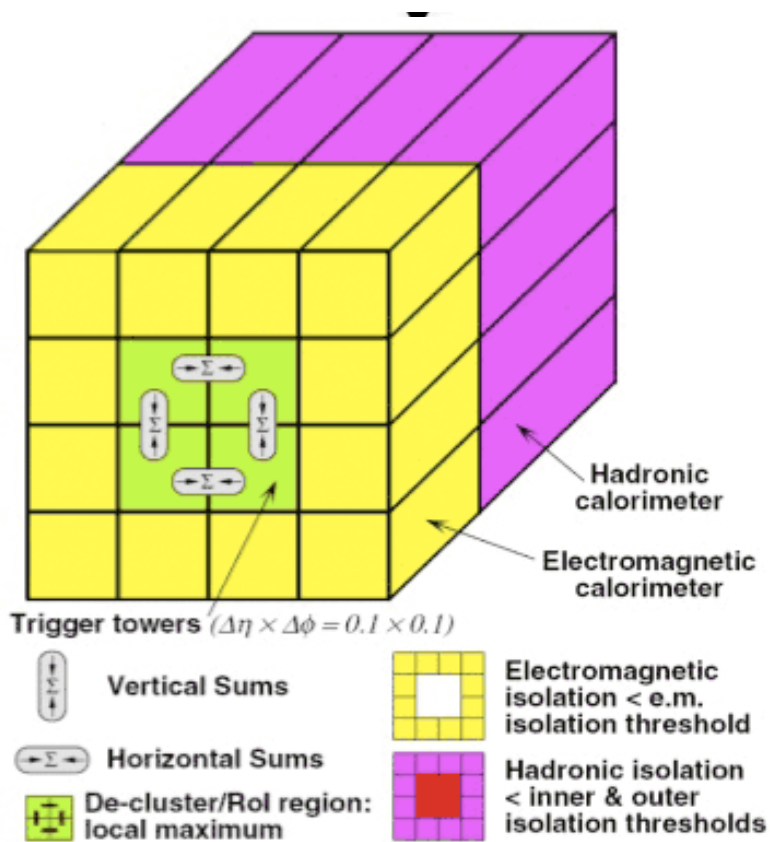
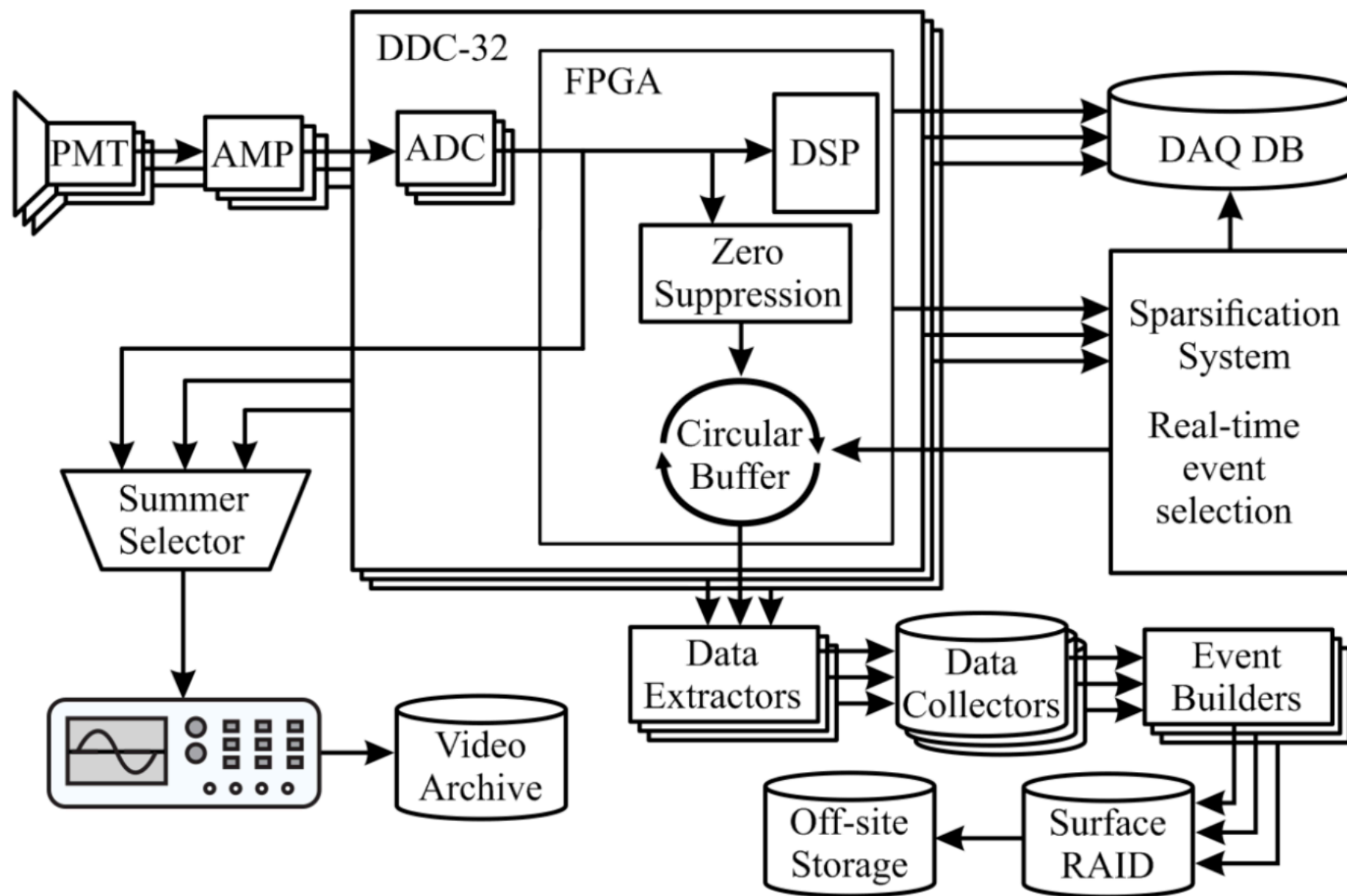
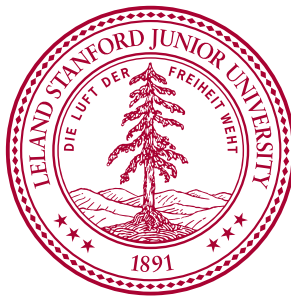


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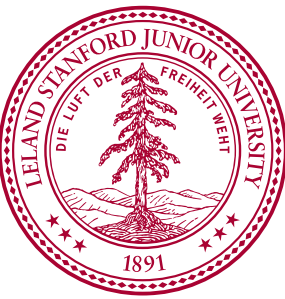


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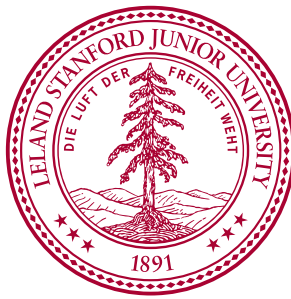
LZ TDAQ SYSTEM



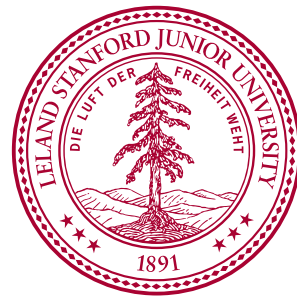
QUESTIONS?



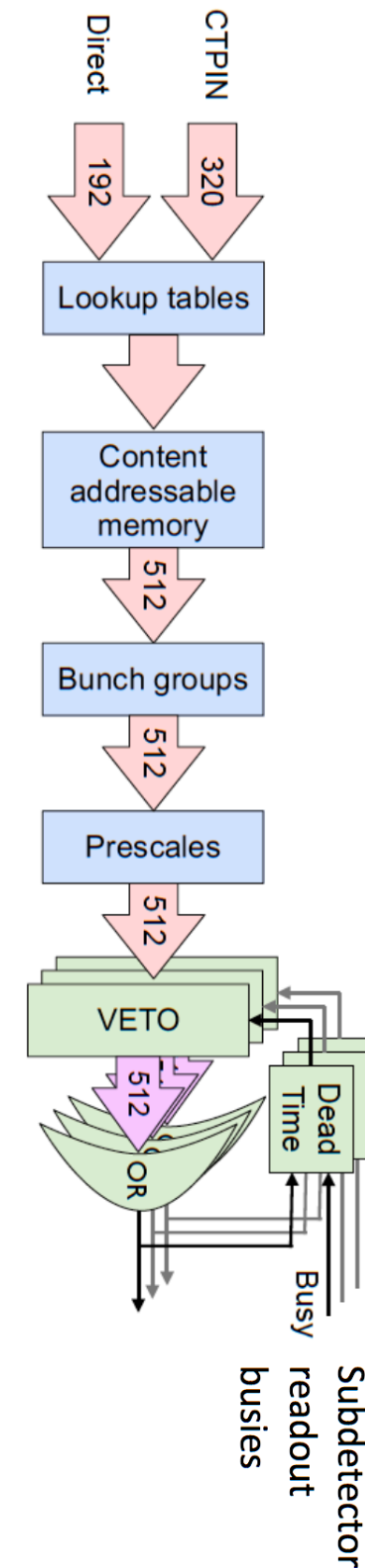
CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



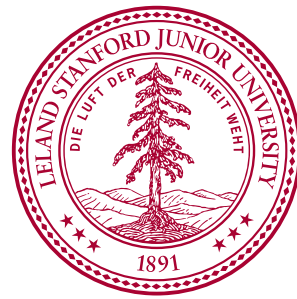
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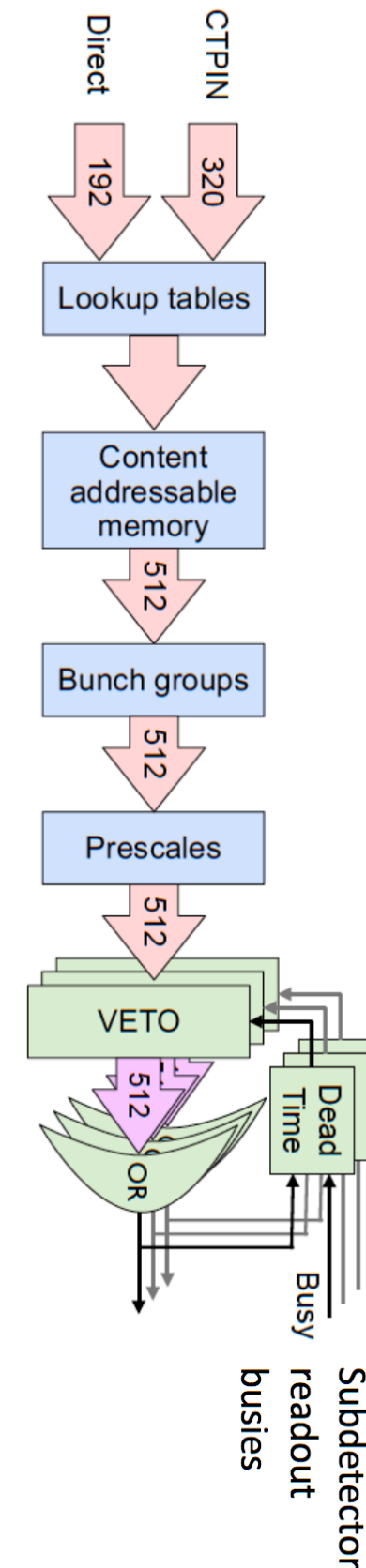
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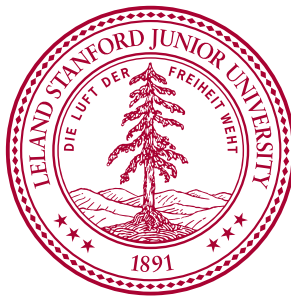
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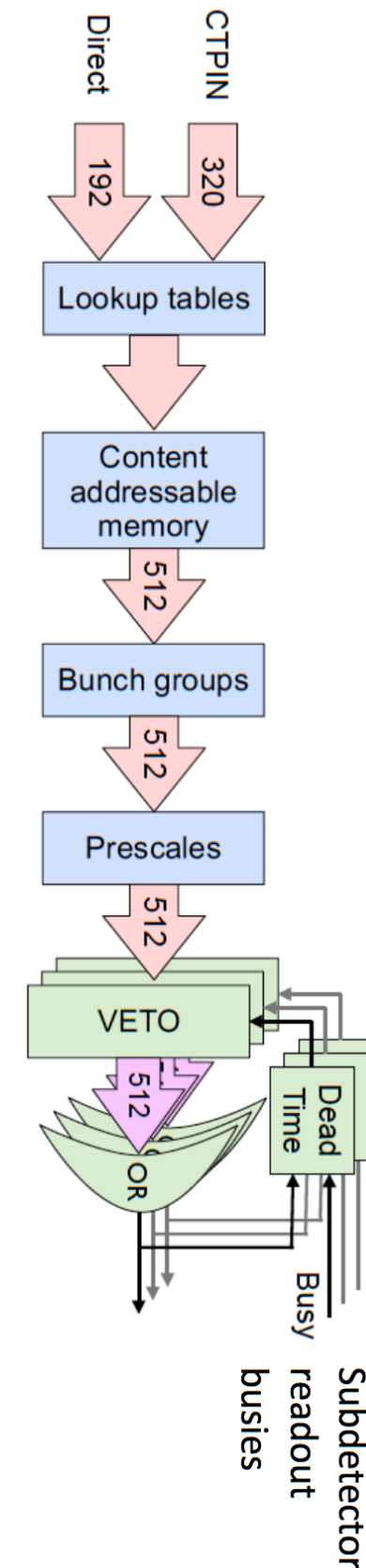
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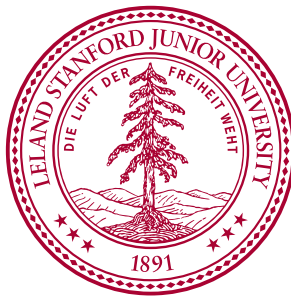
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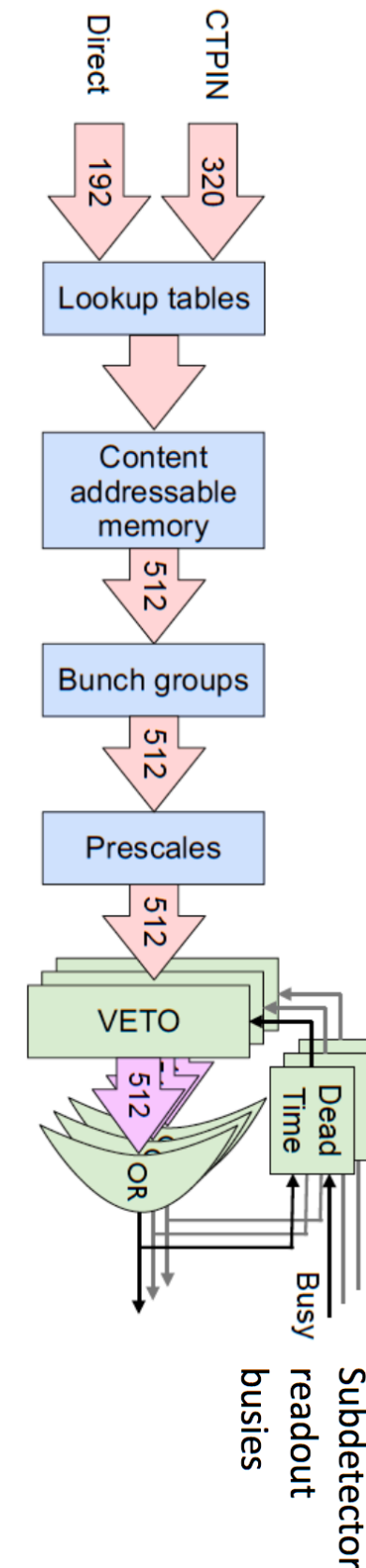
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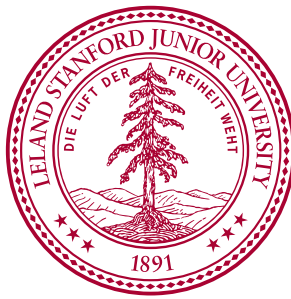
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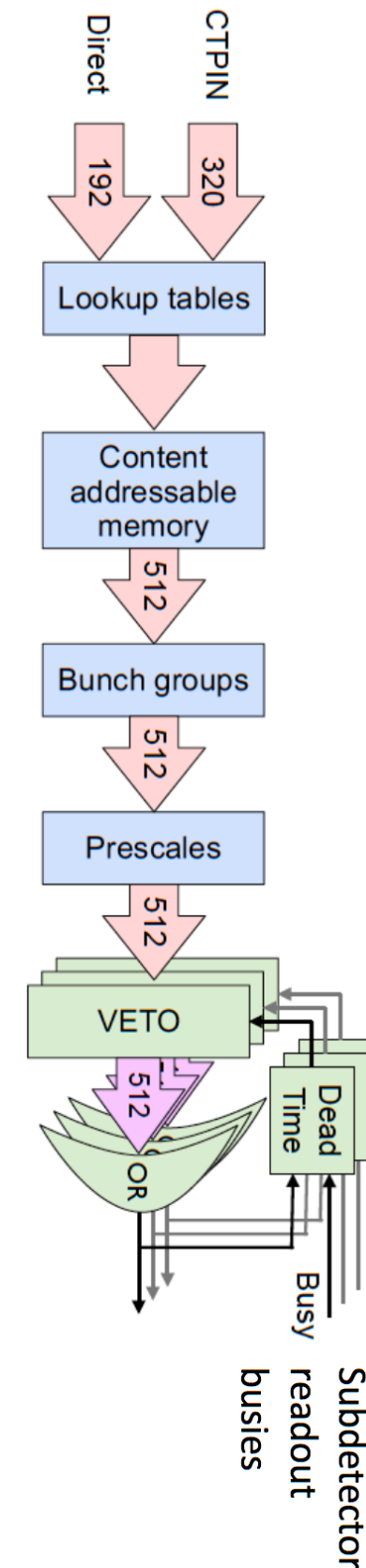
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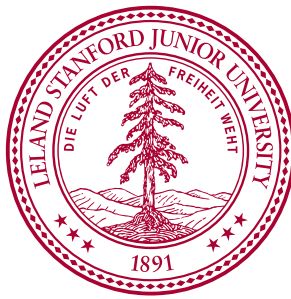
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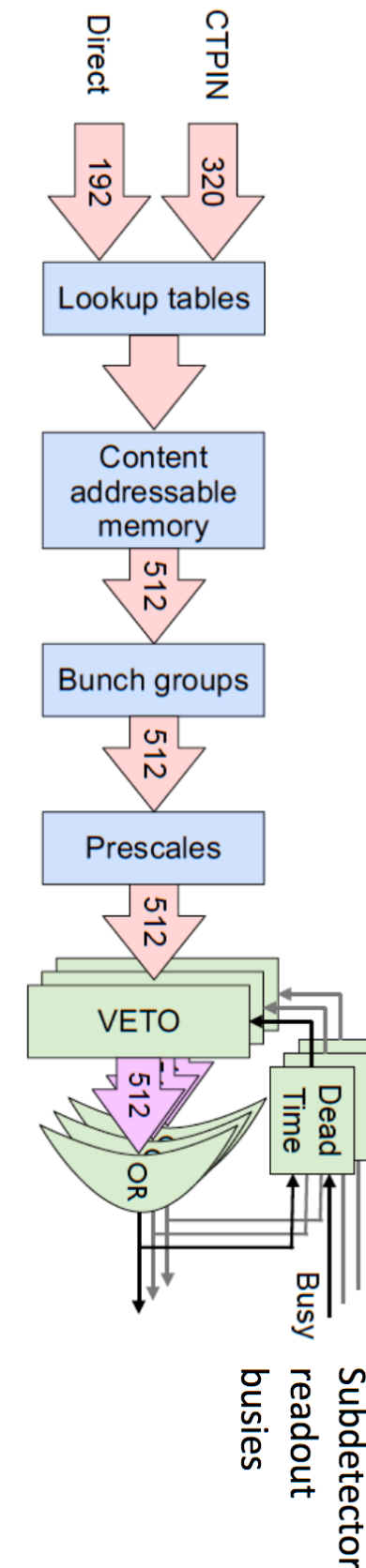
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 - Controls detector BUSY



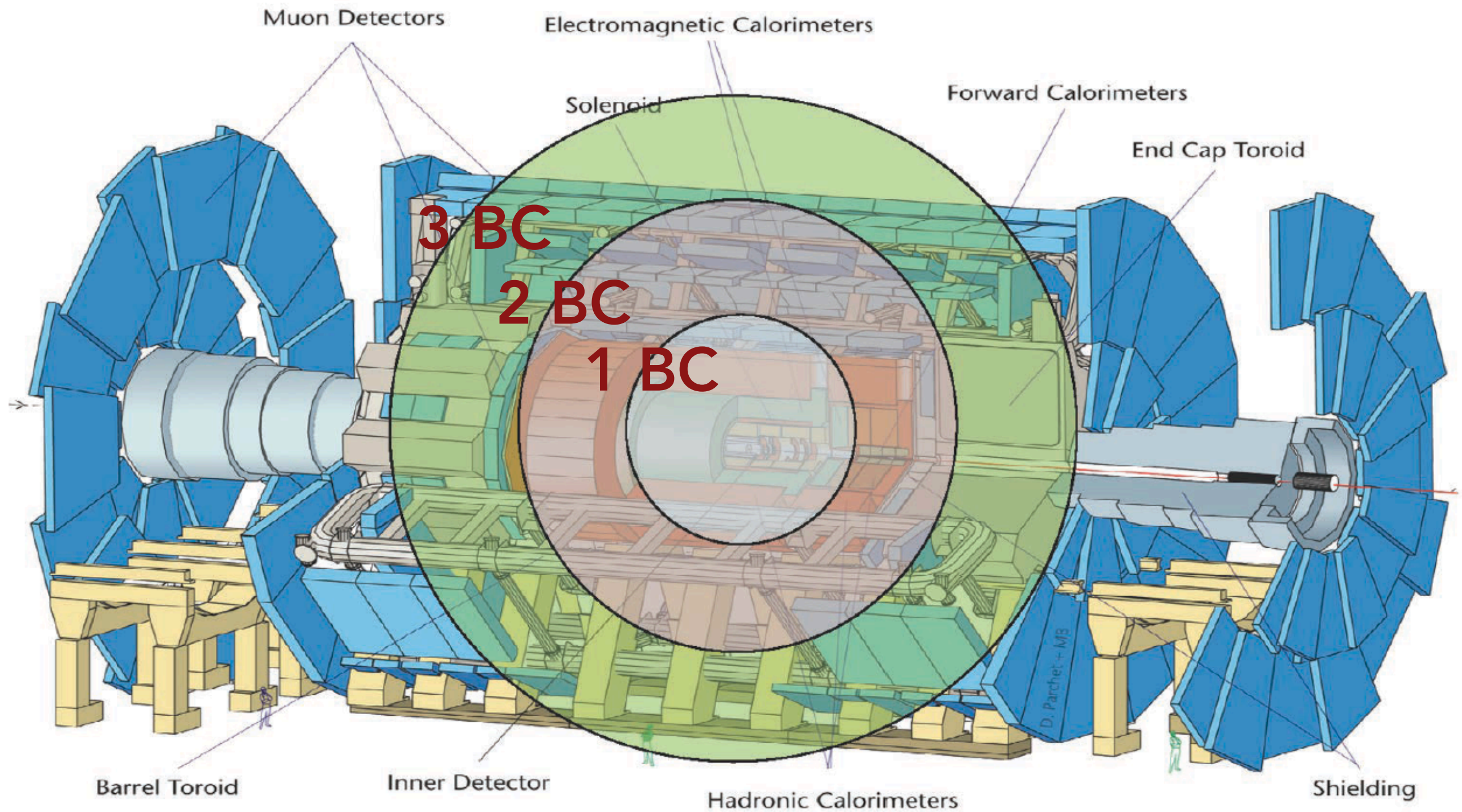
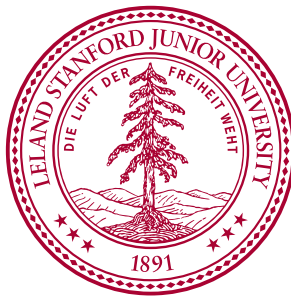
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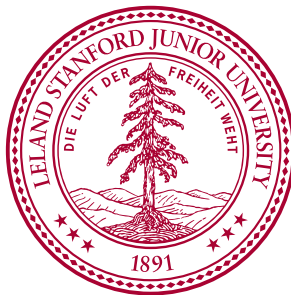
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 - Controls detector BUSY
 - **All within 100ns**



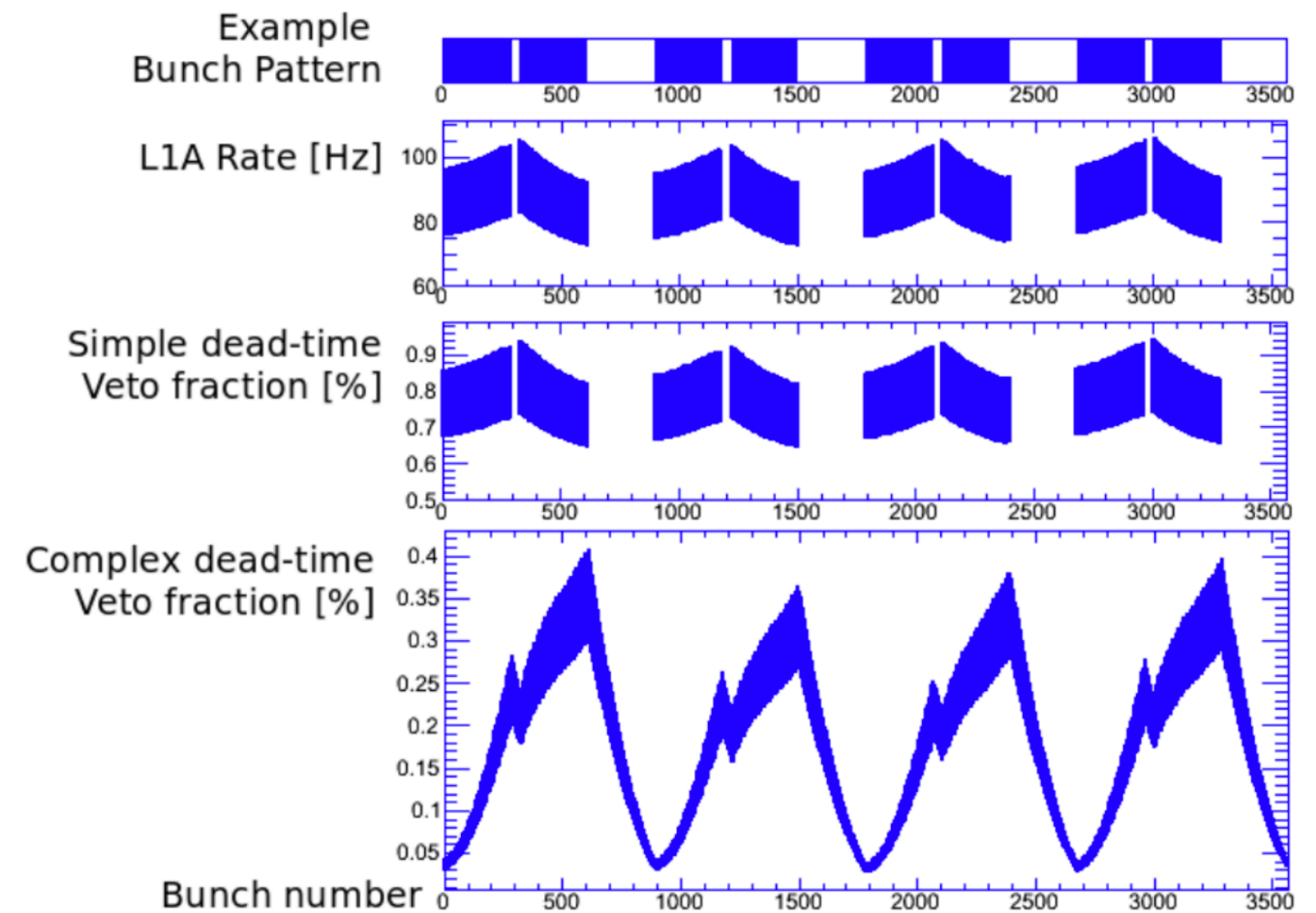
TIMING IS EVERYTHING



ATLAS DEADTIME

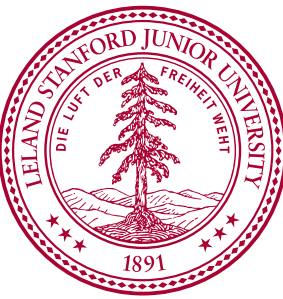


- Simple dead-time veto:
 - No new L1A after fixed number of BC
- Leaky-bucket Deadtime Algorithm:
 - Bucket leaks at rate R
 - Contents increase by X at each L1A until full, then BUSY is asserted
 - Allows system to maintain high efficiency for data taking



[Fig. Ref](#)

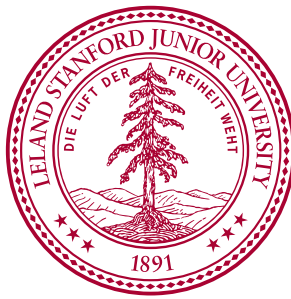
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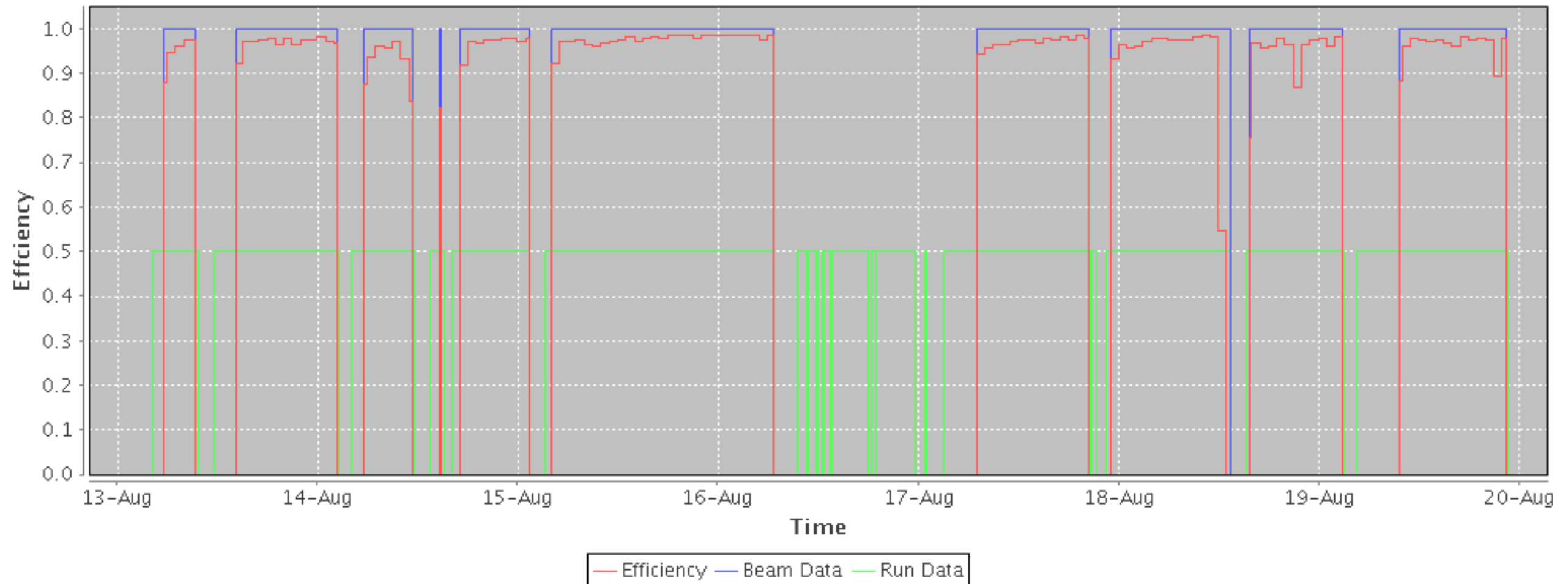
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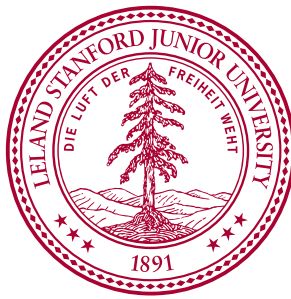
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asserted

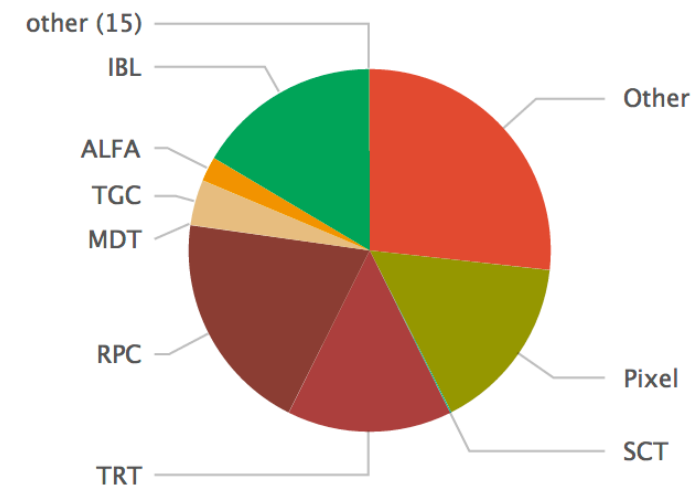
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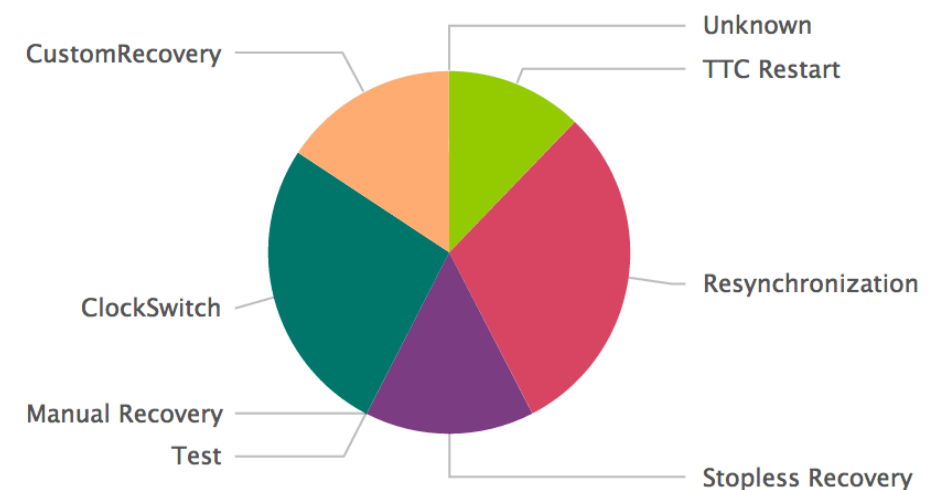


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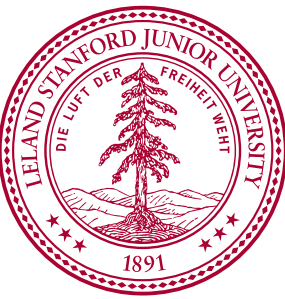
Trigger Held by System



Trigger Held by Reason



SUMMARY



- TDAQ is the system which allows us to take data off our detectors for analysis
- Efficiency of data taking is controlled through stochastic input rate, DAQ processing rate, and ability to buffer events to process
- We'll learn more about how these are implemented and what people are thinking about the future tomorrow!

